



# PROBLEM SOLVING AND SEARCH IN ARTIFICIAL INTELLIGENCE

## Lecture 5 Answer-Set Programming: Motivation and Introduction

\* slides adapted from Torsten Schaub [Gebser et al.(2012)]

Lucia Gomez Alvarez

Dresden

# Agenda

- 1 Introduction
- 2 Uninformed Search versus Informed Search (Best First Search, A\* Search, Heuristics)
- 3 Local Search, Stochastic Hill Climbing, Simulated Annealing
- 4 Tabu Search
- 5 Answer-set Programming (ASP)
- 6 Constraint Satisfaction (CSP)
- 7 Evolutionary Algorithms/ Genetic Algorithms
- 8 Structural Decomposition Techniques (Tree/Hypertree Decompositions)

# Outline

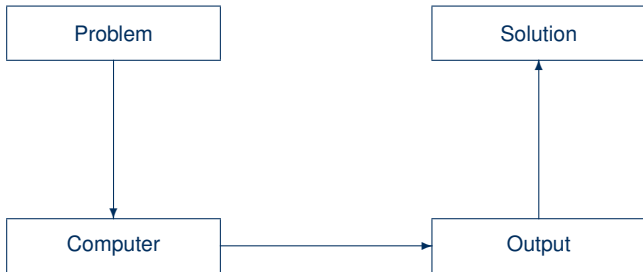
## 1 Motivation

- Declarative Problem Solving
- ASP in a Nutshell
- ASP Paradigm

## 2 Introduction

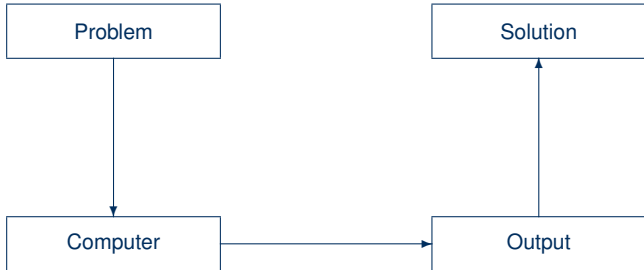
- Syntax
- Semantics
- Examples
- Language Constructs and Extensions
- Modelling

# Informatics



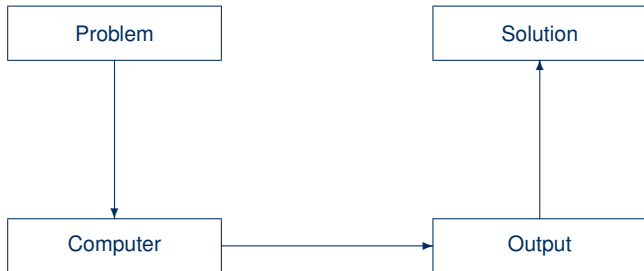
# Informatics

“What is the problem?” versus “How to solve the problem?”



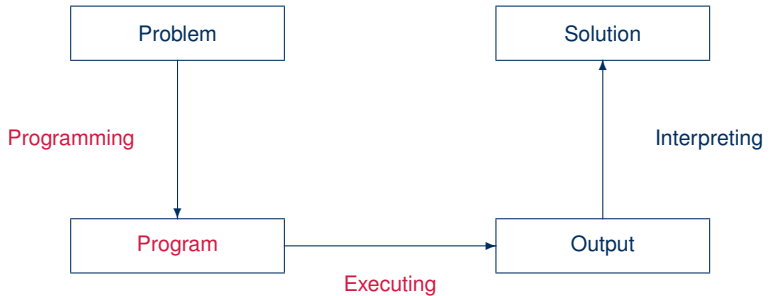
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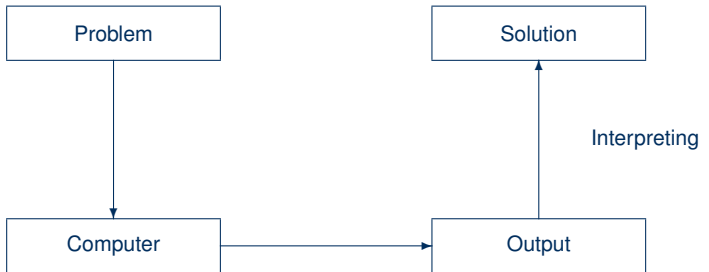
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# Declarative problem solving

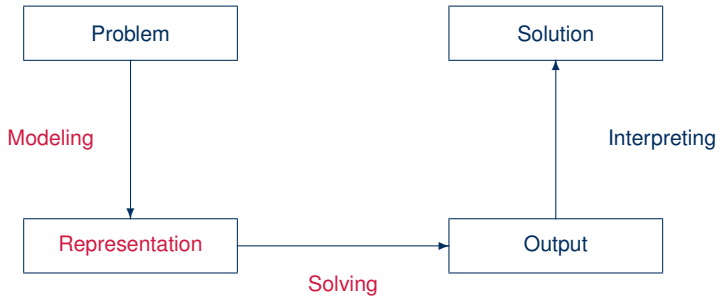
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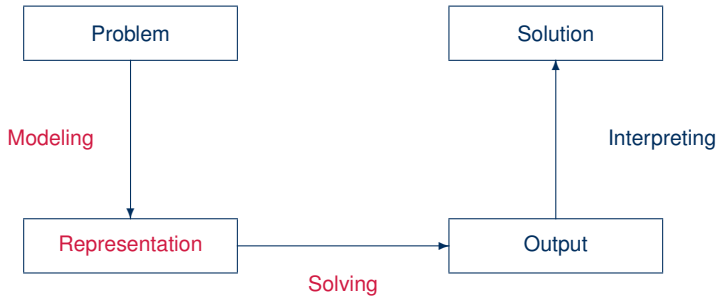


# Declarative problem solving

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# Declarative problem solving



# Answer Set Programming

in a Nutshell

- ASP is an approach to **declarative problem solving**, combining
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- ASP embraces many emerging application areas

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**ASP = DB+LP+KR+SAT**

# KR's shift of paradigm

Theorem Proving based approach (eg. Prolog)

- 1 Provide a representation of the problem
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- 1 Provide a representation of the problem
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# LP-style playing with blocks

## Prolog program

```
on(a,b).
```

```
on(b,c).
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```
above(X,Y) :- on(X,Y).
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above(X,Y) :- on(X,Z), above(Z,Y).
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## Prolog queries (answered via fixed execution)

```
?- above(a,c).  
  
Fatal Error: local stack overflow.
```

# SAT-style playing with blocks

## Formula

$on(a, b)$   
 $\wedge on(b, c)$   
 $\wedge (on(X, Y) \rightarrow above(X, Y))$   
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## Herbrand model

$\left\{ \begin{array}{ccccc} on(a, b), & on(b, c), & on(a, c), & on(b, b), & \\ above(a, b), & above(b, c), & above(a, c), & above(b, b), & above(c, b) \end{array} \right\}$

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➡ **Answer Set Programming (ASP)**

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## Stable Herbrand model

```
{ on(a,b), on(b,c), above(b,c), above(a,b), above(a,c) }
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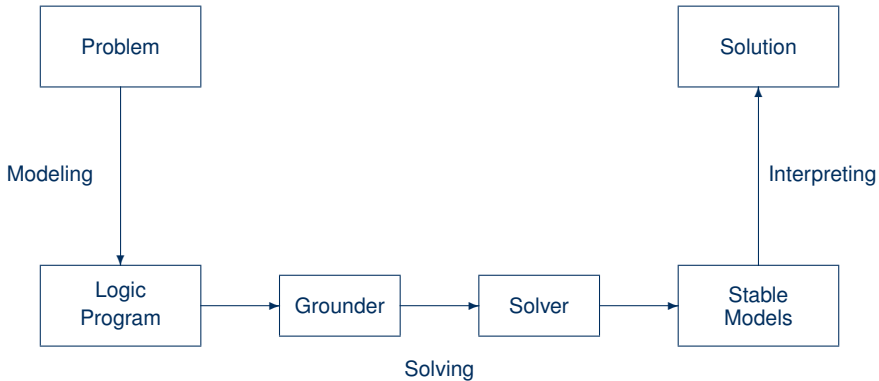
# ASP versus Prolog

ASP	Prolog
Model generation	Query orientation
Bottom-up	Top-down
Modeling language	Programming language
Rule-based format	
Instantiation Flat terms	Unification Nested terms

# ASP versus SAT

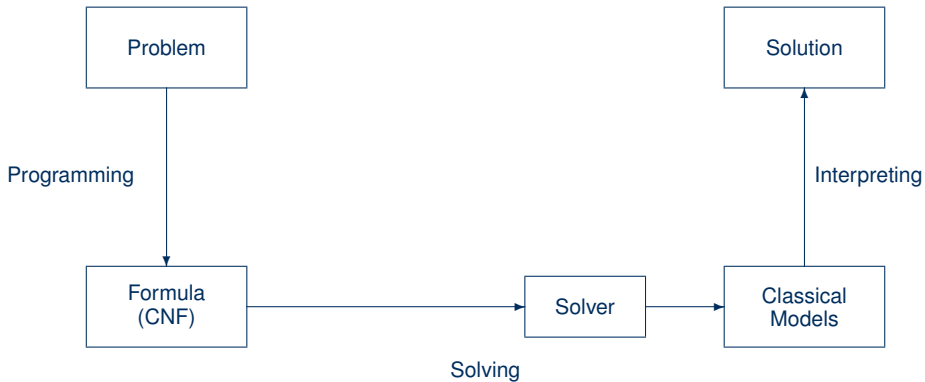
ASP	SAT
Model generation	
Bottom-up	
Constructive Logic	Classical Logic
Closed (and open) world reasoning	Open world reasoning
Modeling language	—
Complex reasoning modes	Satisfiability Testing
Satisfiability	Satisfiability
Enumeration	Enumeration
Optimization	—
Intersection/Union	—
$NP^{(NP)}$	$NP$

# ASP solving

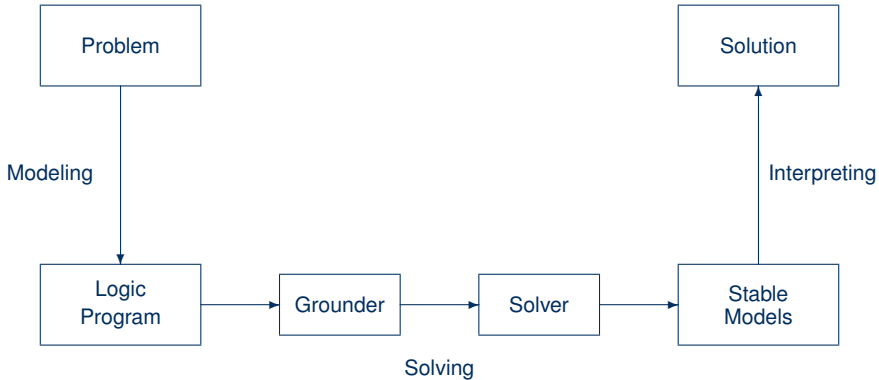




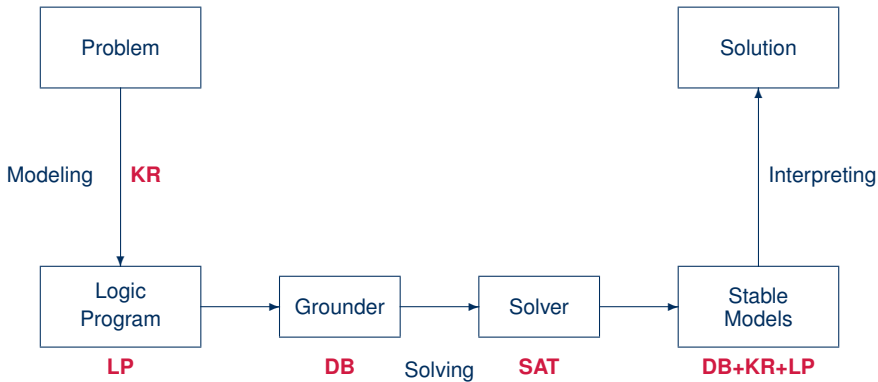
# SAT solving



# Rooting ASP solving



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- Combinatorial search problems in the realm of *P*, *NP*, and *NP<sup>NP</sup>* (some with substantial amount of data), like
  - Automated Planning
  - Code Optimization
  - Composition of Renaissance Music
  - Database Integration
  - Decision Support for NASA shuttle controllers
  - Model Checking
  - Product Configuration
  - Robotics
  - System Biology
  - System Synthesis
  - (industrial) Team-building
  - and many many more

# What does ASP offer?

- Integration of DB, KR, and SAT techniques
- Succinct, elaboration-tolerant problem representations
  - Rapid application development tool
- Easy handling of dynamic, knowledge intensive applications
  - including: data, frame axioms, exceptions, defaults, closures, etc

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# Agenda

## 1 Motivation

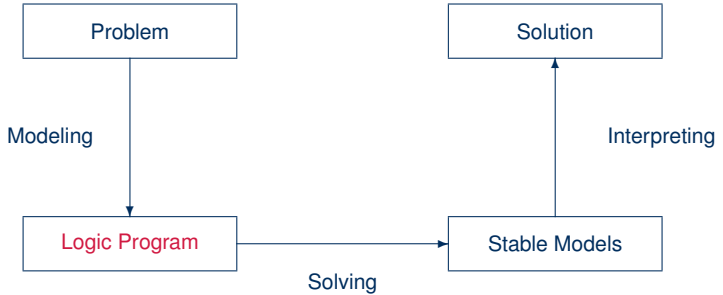
- Declarative Problem Solving
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- ASP Paradigm

## 2 Introduction

- Syntax
- Semantics
- Examples
- Language Constructs and Extensions
- Modelling



# Problem solving in ASP: Syntax



# Normal logic programs

- A (normal) **logic program** over a set  $\mathcal{A}$  of atoms is a finite **set** of rules
- A (normal) **rule**,  $r$ , is of the form

$$a_0 \leftarrow a_1, \dots, a_m, \text{not } a_{m+1}, \dots, \text{not } a_n$$

where  $0 \leq m \leq n$  and each  $a_i \in \mathcal{A}$  is an atom for  $0 \leq i \leq n$

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- Notation

$$\begin{aligned} \text{head}(r) &= a_0 \\ \text{body}(r) &= \{a_1, \dots, a_m, \text{not } a_{m+1}, \dots, \text{not } a_n\} \\ \text{body}(r)^+ &= \{a_1, \dots, a_m\} \\ \text{body}(r)^- &= \{a_{m+1}, \dots, a_n\} \end{aligned}$$

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- A program is called **positive** if  $\text{body}(r)^- = \emptyset$  for all its rules

# Rough notational convention

We sometimes use the following notation interchangeably in order to stress the respective view:

	true, false	if	and	or	iff	default negation	classical negation
source code		$:-$	$,$	$ $		<code>not</code>	$-$
logic program		$\leftarrow$	$,$	$;$		<i>not</i>	$\neg$
formula	$\perp, \top$	$\rightarrow$	$\wedge$	$\vee$	$\leftrightarrow$	$\sim$	$\neg$

# Default Vs Classical Negation

Example of default negation:

```
trainSchedulingInstance(rf654,Dresden,Berlin,9,30,am).  
trainSchedulingInstance(rf654,Dresden,Berlin,10,30,am).
```

```
takeCar(P5,origin,dest,h,m,d) :- trip(origin,dest,h,m,d), not  
trainSchedulingInstance(-,origin,dest,h,m,d).
```

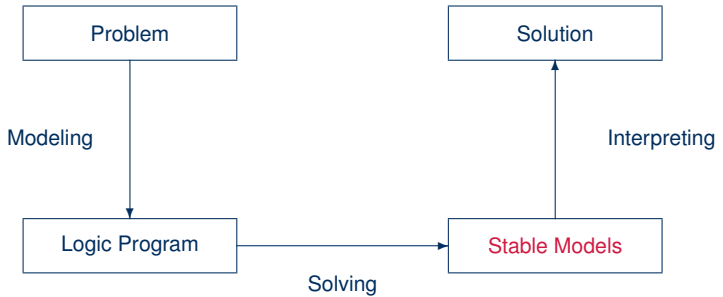
Example of classical negation

```
-domestic(giraffe).  
strong(tiger).  
wild(p) :- -domestic(p).
```

Combined example of default and classical negation

```
fly(X) :- bird(X), not -fly(X).  
-fly(X) :- penguin(X).  
bird(X) :- penguin(X). bird(X) :- eagle(X).
```

# Problem solving in ASP: Semantics



# Formal Definition

## Stable models of positive programs

- A set of atoms  $X$  is **closed under** a positive program  $P$  iff for any  $r \in P$ ,  $head(r) \in X$  whenever  $body(r)^+ \subseteq X$ 
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- The **smallest** set of atoms which is closed under a positive program  $P$  is denoted by  $Cn(P)$ 
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  - $Cn(P)$  corresponds to the  $\subseteq$ -smallest model of  $P$  (ditto)
- The set  $Cn(P)$  of atoms is the **stable model** of a positive program  $P$

# Some “logical” remarks

- Positive rules are also referred to as **definite clauses**
  - Definite clauses are disjunctions with **exactly one** positive atom:

$$a_0 \vee \neg a_1 \vee \dots \vee \neg a_m$$

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- **Horn clauses** are clauses with **at most** one positive atom
  - Every definite clause is a Horn clause but not vice versa
  - Non-definite Horn clauses can be regarded as integrity constraints
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  - Non-definite Horn clauses can be regarded as integrity constraints
  - A set of Horn clauses has a **smallest model** or none
- This **smallest model** is the intended semantics of such sets of clauses
  - Given a positive program  $P$ ,  $Cn(P)$  corresponds to the smallest model of the set of definite clauses corresponding to  $P$

# Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$\{p, q\}$ ,  $\{q, r\}$ , and  $\{p, q, r\}$

$$\Phi \quad \boxed{q \wedge (q \wedge \neg r \rightarrow p)}$$

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$p$	$\mapsto$	1
$q$	$\mapsto$	1
$r$	$\mapsto$	0



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Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

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Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

# Formal Definition

## Stable model of normal programs

- The **Gelfond-Lifschitz Reduct**[Gelfond and Lifschitz(1991)],  $P^X$ , of a program  $P$  relative to a set  $X$  of atoms is defined by

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- A set  $X$  of atoms is a **stable model** of a program  $P$ , if  $Cn(P^X) = X$
- Note:  $Cn(P^X)$  is the  $\subseteq$ -smallest (classical) model of  $P^X$
- Note: Every atom in  $X$  is justified by an “applying rule from  $P$ ”



# A closer look at $P^X$

- The **Gelfond-Lifschitz Reduct**[Gelfond and Lifschitz(1991)],  $P^X$ , of a program  $P$  relative to a set  $X$  of atoms is defined by

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- In other words, given a set  $X$  of atoms from  $P$ ,

$P^X$  is obtained from  $P$  by **deleting**

- 1 each **rule** having *not*  $a$  in its body with  $a \in X$  and then
- 2 all **negative atoms** of the form *not*  $a$  in the bodies of the remaining rules

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- 1 each rule having **not  $a$**  in its body with  $a \in X$  and then
- 2 all negative atoms of the form **not  $a$**  in the bodies of the remaining rules

- Note: Only **negative body literals** are evaluated w.r.t.  $X$

# A first example

$$P = \{p \leftarrow p, q \leftarrow \text{not } p\}$$

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$X$		$Cn(P^X)$
$\emptyset$		
$\{p\}$		
$\{q\}$		
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$\{p\}$	$p \leftarrow p$	$\emptyset$
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$
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$\emptyset$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <b>x</b>
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$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$
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$\{p\}$	$p \leftarrow p$	$\emptyset$	✗
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$	✓
$\{p, q\}$	$p \leftarrow p$	$\emptyset$	

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- A logic program may have zero, one, or multiple stable models!
- If  $X$  is a stable model of a logic program  $P$ , then  $X$  is a model of  $P$  (seen as a formula)
- If  $X$  and  $Y$  are stable models of a normal program  $P$ , then  $X \not\subseteq Y$

# Programs with Variables

Let  $P$  be a logic program

- Let  $\mathcal{T}$  be a set of (variable-free) **terms**
- Let  $\mathcal{A}$  be a set of (variable-free) **atoms** constructable from  $\mathcal{T}$

# Programs with Variables

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- Let  $\mathcal{T}$  be a set of variable-free **terms** (also called **Herbrand universe**)
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# Programs with Variables

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- Let  $\mathcal{T}$  be a set of (variable-free) terms
- Let  $\mathcal{A}$  be a set of (variable-free) atoms constructable from  $\mathcal{T}$
- **Ground Instances** of  $r \in P$ : Set of variable-free rules obtained by replacing all variables in  $r$  by elements from  $\mathcal{T}$ :

$$\text{ground}(r) = \{r\theta \mid \theta : \text{var}(r) \rightarrow \mathcal{T}, \text{var}(r\theta) = \emptyset\}$$

where  $\text{var}(r)$  stands for the set of all variables occurring in  $r$ ;  
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 $\theta$  is a (ground) substitution

- **Ground Instantiation** of  $P$ :  $\text{ground}(P) = \bigcup_{r \in P} \text{ground}(r)$

# An example

$$P = \{ r(a, b) \leftarrow, r(b, c) \leftarrow, t(X, Y) \leftarrow r(X, Y) \}$$

$$\mathcal{T} = \{a, b, c\}$$

$$\mathcal{A} = \left\{ \begin{array}{l} r(a, a), r(a, b), r(a, c), r(b, a), r(b, b), r(b, c), r(c, a), r(c, b), r(c, c), \\ t(a, a), t(a, b), t(a, c), t(b, a), t(b, b), t(b, c), t(c, a), t(c, b), t(c, c) \end{array} \right\}$$

# An example

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$$\text{ground}(P) = \left\{ \begin{array}{l} r(a, b) \leftarrow, \\ r(b, c) \leftarrow, \\ t(a, a) \leftarrow r(a, a), t(b, a) \leftarrow r(b, a), t(c, a) \leftarrow r(c, a), \\ t(a, b) \leftarrow r(a, b), t(b, b) \leftarrow r(b, b), t(c, b) \leftarrow r(c, b), \\ t(a, c) \leftarrow r(a, c), t(b, c) \leftarrow r(b, c), t(c, c) \leftarrow r(c, c) \end{array} \right\}$$

# An example

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$$\text{ground}(P) = \left\{ \begin{array}{l} r(a, b) \leftarrow, \\ r(b, c) \leftarrow, \\ t(a, b) \leftarrow r(a, b), \\ t(b, c) \leftarrow r(b, c), \end{array} \right\}$$

- **Intelligent Grounding** aims at reducing the ground instantiation

# Stable models of programs with Variables

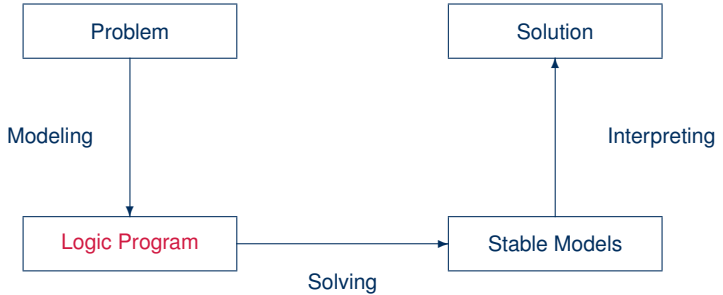
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# Stable models of programs with Variables

Let  $P$  be a normal logic program with variables

- A set  $X$  of (**ground**) atoms is a **stable model** of  $P$ ,  
if  $Cn(\mathit{ground}(P)^X) = X$

# Problem solving in ASP: Extended Syntax



# Language Constructs and Extensions



# Language Constructs and Extensions

- Variables (over the Herbrand Universe)
  - $p(X) :- q(X)$  over constants  $\{a,b,c\}$  stands for  
 $p(a) :- q(a), p(b) :- q(b), p(c) :- q(c)$

# Language Constructs and Extensions

- Conditional Literals

–  $p \text{ :- } q(X) \text{ : } r(X) \text{ given } r(a), r(b), r(c)$  stands for  
 $p \text{ :- } q(a), q(b), q(c)$

# Language Constructs and Extensions

- Disjunction

–  $p(X) \mid q(X) \text{ :- } r(X)$

# Language Constructs and Extensions

- Integrity Constraints
  - $\text{:- } q(X), p(X)$

# Language Constructs and Extensions

- Choice

- $2 \{ p(X,Y) : q(X) \} 7 :- r(Y)$

# Language Constructs and Extensions

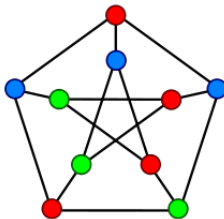
- Aggregates

- `s(Y) :- r(Y), 2 #count { p(X,Y) : q(X) } 7`
- `also: #sum, #avg, #min, #max, #even, #odd`

# Language Constructs and Extensions

- **Variables** (over the Herbrand Universe)
  - $p(X) :- q(X)$  over constants  $\{a,b,c\}$  stands for  
 $p(a) :- q(a), p(b) :- q(b), p(c) :- q(c)$
- **Conditional Literals**
  - $p :- q(X) : r(X)$  given  $r(a), r(b), r(c)$  stands for  
 $p :- q(a), q(b), q(c)$
- **Disjunction**
  - $p(X) \mid q(X) :- r(X)$
- **Integrity Constraints**
  - $:- q(X), p(X)$
- **Choice**
  - $2 \{ p(X,Y) : q(X) \} 7 :- r(Y)$
- **Aggregates**
  - $s(Y) :- r(Y), 2 \#count \{ p(X,Y) : q(X) \} 7$
  - **also:**  $\#sum, \#avg, \#min, \#max, \#even, \#odd$

## Example 3-Colorability



- Vertices are represented with predicates  $\text{node}(X)$ ;
- Edges are represented with predicates  $\text{edge}(X, Y)$ .

Question: Is there a valid assignment of three colors for an input graph  $G$  such that no two adjacent vertices have the same color?



# Graph coloring

node (1..6) .

# Graph coloring

node (1..6) .

edge (1, 2) .    edge (1, 3) .    edge (1, 4) .

edge (2, 4) .    edge (2, 5) .    edge (2, 6) .

edge (3, 1) .    edge (3, 4) .    edge (3, 5) .

edge (4, 1) .    edge (4, 2) .

edge (5, 3) .    edge (5, 4) .    edge (5, 6) .

edge (6, 2) .    edge (6, 3) .    edge (6, 5) .

# Graph coloring

```
node (1..6) .
```

```
edge (1,2) .   edge (1,3) .   edge (1,4) .
```

```
edge (2,4) .   edge (2,5) .   edge (2,6) .
```

```
edge (3,1) .   edge (3,4) .   edge (3,5) .
```

```
edge (4,1) .   edge (4,2) .
```

```
edge (5,3) .   edge (5,4) .   edge (5,6) .
```

```
edge (6,2) .   edge (6,3) .   edge (6,5) .
```

```
col(r) .   col(b) .   col(g) .
```

# Graph coloring

```
node (1..6) .
```

```
edge (1,2) .   edge (1,3) .   edge (1,4) .
```

```
edge (2,4) .   edge (2,5) .   edge (2,6) .
```

```
edge (3,1) .   edge (3,4) .   edge (3,5) .
```

```
edge (4,1) .   edge (4,2) .
```

```
edge (5,3) .   edge (5,4) .   edge (5,6) .
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edge (6,2) .   edge (6,3) .   edge (6,5) .
```

```
col(r) .   col(b) .   col(g) .
```

**Problem  
instance**

# Graph coloring

```
node(1..6).
```

```
edge(1,2). edge(1,3). edge(1,4).
```

```
edge(2,4). edge(2,5). edge(2,6).
```

```
edge(3,1). edge(3,4). edge(3,5).
```

```
edge(4,1). edge(4,2).
```

```
edge(5,3). edge(5,4). edge(5,6).
```

```
edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

```
1 { color(X,C) : col(C) } 1 :- node(X).
```

# Graph coloring

```
node(1..6).
```

```
edge(1,2). edge(1,3). edge(1,4).
```

```
edge(2,4). edge(2,5). edge(2,6).
```

```
edge(3,1). edge(3,4). edge(3,5).
```

```
edge(4,1). edge(4,2).
```

```
edge(5,3). edge(5,4). edge(5,6).
```

```
edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

```
1 { color(X,C) : col(C) } 1 :- node(X).
```

```
:- edge(X,Y), color(X,C), color(Y,C).
```

# Graph coloring

```
node(1..6).
```

```
edge(1,2). edge(1,3). edge(1,4).
```

```
edge(2,4). edge(2,5). edge(2,6).
```

```
edge(3,1). edge(3,4). edge(3,5).
```

```
edge(4,1). edge(4,2).
```

```
edge(5,3). edge(5,4). edge(5,6).
```

```
edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

```
1 { color(X,C) : col(C) } 1 :- node(X).
```

```
:- edge(X,Y), color(X,C), color(Y,C).
```

} Problem  
encoding

# Graph coloring

```
node(1..6).
```

```
edge(1,2). edge(1,3). edge(1,4).
```

```
edge(2,4). edge(2,5). edge(2,6).
```

```
edge(3,1). edge(3,4). edge(3,5).
```

```
edge(4,1). edge(4,2).
```

```
edge(5,3). edge(5,4). edge(5,6).
```

```
edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

} **Problem  
instance**

```
1 { color(X,C) : col(C) } 1 :- node(X).
```

```
:- edge(X,Y), color(X,C), color(Y,C).
```

} **Problem  
encoding**



# color.lp

```
node(1..6).
```

```
edge(1,2). edge(1,3). edge(1,4).
```

```
edge(2,4). edge(2,5). edge(2,6).
```

```
edge(3,1). edge(3,4). edge(3,5).
```

```
edge(4,1). edge(4,2).
```

```
edge(5,3). edge(5,4). edge(5,6).
```

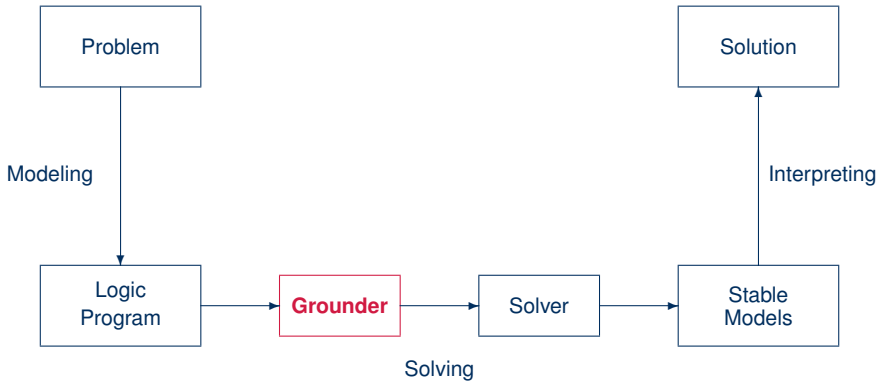
```
edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

```
1 { color(X,C) : col(C) } 1 :- node(X).
```

```
:- edge(X,Y), color(X,C), color(Y,C).
```

# ASP solving process



# Graph coloring: Grounding

```
$ gringo --text color.lp
```

# Graph coloring: Grounding

```
$ gringo --text color.lp
```

```
node(1). node(2). node(3). node(4). node(5). node(6).
```

```
edge(1,2). edge(1,3). edge(1,4). edge(2,4). edge(2,5). edge(2,6).
```

```
edge(3,1). edge(3,4). edge(3,5). edge(4,1). edge(4,2). edge(5,3).
```

```
edge(5,4). edge(5,6). edge(6,2). edge(6,3). edge(6,5).
```

```
col(r). col(b). col(g).
```

```
1 {color(1,r), color(1,b), color(1,g)} 1.
```

```
1 {color(2,r), color(2,b), color(2,g)} 1.
```

```
1 {color(3,r), color(3,b), color(3,g)} 1.
```

```
1 {color(4,r), color(4,b), color(4,g)} 1.
```

```
1 {color(5,r), color(5,b), color(5,g)} 1.
```

```
1 {color(6,r), color(6,b), color(6,g)} 1.
```

```
:- color(1,r), color(2,r). :- color(2,g), color(5,g). ... :- color(6,r), color(2,r).
```

```
:- color(1,b), color(2,b). :- color(2,r), color(6,r). :- color(6,b), color(2,b).
```

```
:- color(1,g), color(2,g). :- color(2,b), color(6,b). :- color(6,g), color(2,g).
```

```
:- color(1,r), color(3,r). :- color(2,g), color(6,g). :- color(6,r), color(3,r).
```

```
:- color(1,b), color(3,b). :- color(3,r), color(1,r). :- color(6,b), color(3,b).
```

```
:- color(1,g), color(3,g). :- color(3,b), color(1,b). :- color(6,g), color(3,g).
```

```
:- color(1,r), color(4,r). :- color(3,g), color(1,g). :- color(6,r), color(5,r).
```

```
:- color(1,b), color(4,b). :- color(3,r), color(4,r). :- color(6,b), color(5,b).
```

```
:- color(1,g), color(4,g). :- color(3,b), color(4,b). :- color(6,g), color(5,g).
```

```
:- color(2,r), color(4,r). :- color(3,g), color(4,g).
```

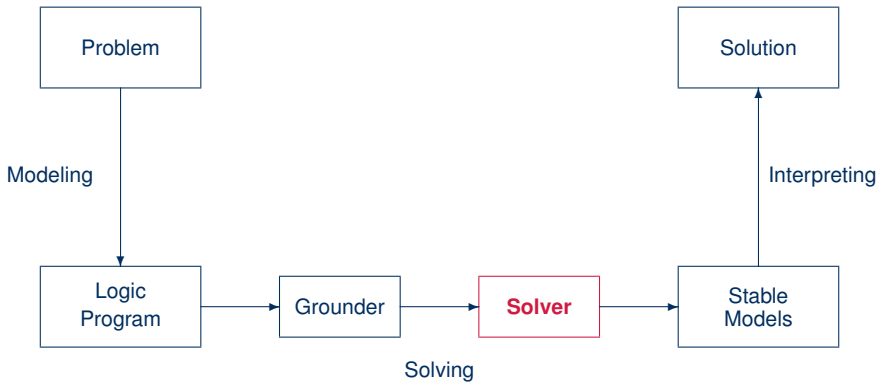
```
:- color(2,b), color(4,b). :- color(3,r), color(5,r).
```

```
:- color(2,g), color(4,g). :- color(3,b), color(5,b).
```

```
:- color(2,r), color(5,r). :- color(3,g), color(5,g).
```

```
:- color(2,b), color(5,b). :- color(4,r), color(1,r).
```

# ASP solving process



# Graph coloring: Solving

```
$ gringo color.lp | clasp 0
```

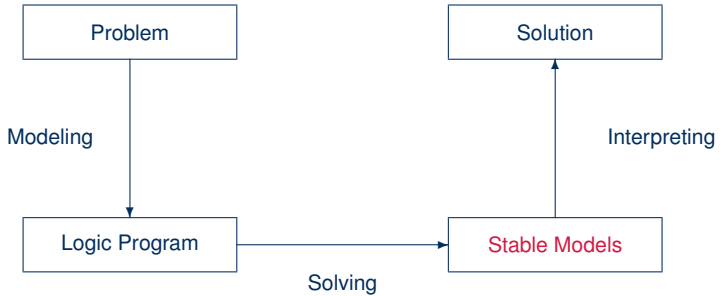
# Graph coloring: Solving

```
$ gringo color.lp | clasp 0
```

```
clasp version 2.1.0
Reading from stdin
Solving...
Answer: 1
edge(1,2) ... col(r) ... node(1) ... color(6,b) color(5,g) color(4,b) color(3,r) color(2,r)
Answer: 2
edge(1,2) ... col(r) ... node(1) ... color(6,r) color(5,g) color(4,r) color(3,b) color(2,b)
Answer: 3
edge(1,2) ... col(r) ... node(1) ... color(6,g) color(5,b) color(4,g) color(3,r) color(2,r)
Answer: 4
edge(1,2) ... col(r) ... node(1) ... color(6,r) color(5,b) color(4,r) color(3,g) color(2,g)
Answer: 5
edge(1,2) ... col(r) ... node(1) ... color(6,g) color(5,r) color(4,g) color(3,b) color(2,b)
Answer: 6
edge(1,2) ... col(r) ... node(1) ... color(6,b) color(5,r) color(4,b) color(3,g) color(2,g)
SATISFIABLE

Models      : 6
Time        : 0.002s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)
CPU Time    : 0.000s
```

# Problem solving in ASP: Reasoning Modes





# Outline

- 1 Motivation
  - Declarative Problem Solving
  - ASP in a Nutshell
  - ASP Paradigm
- 2 Introduction
  - Syntax
  - Semantics
  - Examples
  - Language Constructs and Extensions
  - Modelling
- 3 Modelling (Lecture 6)
- 4 Language constructs (Lecture 6)
- 5 Optimization (Lecture 7)
- 6 Language extensions (Lecture 7)
- 7 Computational aspects (Lecture 7)

# References



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- See also: <http://potassco.sourceforge.net>