

COMPLEXITY THEORY

Lecture 10: Polynomial Space

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Knowledge-Based Systems

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Quantified Boolean Formulae (QBF)

A QBF is a formula of the following form:

$$Q_1X_1.Q_2X_2.\cdots Q_\ell X_\ell.\varphi[X_1,\ldots,X_\ell]$$

where $Q_i \in \{\exists, \forall\}$ are quantifiers, X_i are propositional logic variables, and φ is a propositional logic formula with variables X_1, \ldots, X_ℓ and constants \top (true) and \bot (false)

Semantics:

- Propositional formulae without variables (only constants ⊤ and ⊥) are evaluated as usual
- $\exists X. \varphi[X]$ is true if either $\varphi[X/\top]$ or $\varphi[X/\bot]$ are true
- ∀X.φ[X] is true if both φ[X/⊤] and φ[X/⊥] are true
 (where φ[X/⊤] is "φ with X replaced by ⊤, and similar for ⊥)

The Class PSpace

We defined PSpace as:

$$\mathsf{PSpace} = \bigcup_{d \ge 1} \mathsf{DSpace}(n^d)$$

and we observed that

 $P \subseteq NP \subseteq PSpace = NPSpace \subseteq ExpTime$.

We can also define a corresponding notion of PSpace-hardness:

Definition 10.1:

- A language **H** is PSpace-hard, if $L \leq_p H$ for every language $L \in PS$ pace.
- A language **C** is PSpace-complete, if **C** is PSpace-hard and **C** ∈ PSpace.

slide 3 of 34

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Deciding QBF Validity

TRUE QBF

Input: A quantified Boolean formula φ .

Problem: Is φ true (valid)?

Observation: We can assume that the quantified formula is in CNF or 3-CNF (same transformations possible as for propositional logic formulae)

Consider a propositional logic formula φ with variables X_1, \ldots, X_ℓ :

Example 10.2: The QBF $\exists X_1 \cdots \exists X_\ell . \varphi$ is true if and only if φ is satisfiable.

Example 10.3: The QBF $\forall X_1 \cdots \forall X_\ell \cdot \varphi$ is true if and only if φ is a tautology.

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 Complexity Theory
 slide 4 of 34
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 slide 5 of 34

The Power of QBF

Theorem 10.4: TRUE QBF is PSpace-complete.

Proof:

- TRUE QBF ∈ PSpace:
 Give an algorithm that runs in polynomial space.
- (2) **True QBF** is PSpace-hard: Proof by reduction from the word problem for polynomially space-bounded TMs.

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PSpace-Hardness of True QBF

Express TM computation in logic, similar to Cook-Levin

Given:

- a polynomial p
- a *p*-space bounded 1-tape NTM $\mathcal{M} = (Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}})$
- a word w

Intended reduction

Define a QBF $\varphi_{p,\mathcal{M},w}$ such that

 $\varphi_{p,\mathcal{M},w}$ is true if and only if \mathcal{M} accepts w in space p(|w|).

Note

We show the reduction for NTMs, which is more than needed, but makes little difference in logic and allows us to reuse our previous formulae from Cook-Levin

Solving True QBF in PSpace

```
01 TRUEQBF(\varphi) {
02    if \varphi has no quantifiers :
03       return "evaluation of \varphi"
04    else if \varphi = \exists X.\psi :
05       return (TRUEQBF(\psi[X/\top]) OR TRUEQBF(\psi[X/\bot]))
06    else if \varphi = \forall X.\psi :
07       return (TRUEQBF(\psi[X/\top]) AND TRUEQBF(\psi[X/\bot]))
08 }
```

- Evaluation in line 03 can be done in polynomial space
- Recursions in lines 05 and 07 can be executed one after the other, reusing space
- Maximum depth of recursion = number of variables (linear)
- Store one variable assignment per recursive call

→ polynomial space algorithm

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Review: Encoding Configurations

Use propositional variables for describing configurations:

```
Q_q for each q \in Q means "\mathcal{M} is in state q \in Q"
```

 P_i for each $0 \le i < p(n)$ means "the head is at Position i"

 $S_{a,i}$ for each $a \in \Gamma$ and $0 \le i < p(n)$ means "tape cell i contains Symbol a"

Represent configuration $(q, p, a_0 \dots a_{p(n)})$

by assigning truth values to variables from the set

$$\overline{C} := \{Q_q, P_i, S_{a,i} \mid q \in Q, \quad a \in \Gamma, \quad 0 \le i < p(n)\}$$

using the truth assignment β defined as

$$\beta(Q_s) := \begin{cases} 1 & s = q \\ 0 & s \neq q \end{cases} \qquad \beta(P_i) := \begin{cases} 1 & i = p \\ 0 & i \neq p \end{cases} \qquad \beta(S_{a,i}) := \begin{cases} 1 & a = a_i \\ 0 & a \neq a_i \end{cases}$$

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slide 6 of 34

Review: Validating Configurations

We define a formula $\operatorname{Conf}(\overline{C})$ for a set of configuration variables

$$\overline{C} = \{Q_q, P_i, S_{a,i} \mid q \in Q, \quad a \in \Gamma, \quad 0 \le i < p(n)\}$$

as follows:

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Review: Transitions Between Configurations

Consider the following formula $Next(\overline{C}, \overline{C}')$ defined as

$$\mathsf{Conf}(\overline{C}) \wedge \mathsf{Conf}(\overline{C}') \wedge \mathsf{NoChange}(\overline{C}, \overline{C}') \wedge \mathsf{Change}(\overline{C}, \overline{C}').$$

NoChange :=
$$\bigvee_{0 \le p < p(n)} \left(P_p \land \bigwedge_{i \ne p, a \in \Gamma} \left(S_{a,i} \to S'_{a,i} \right) \right)$$

$$\mathsf{Change} := \bigvee_{0 \leq p < p(n)} \left(P_p \wedge \bigvee_{q \in \underline{Q}} \left(Q_q \wedge S_{a,p} \wedge \bigvee_{(q',b,D) \in \delta(q,a)} (Q'_{q'} \wedge S'_{b,p} \wedge P'_{D(p)}) \right) \right)$$

where D(p) is the position reached by moving in direction D from p.

Lemma 10.6: For any assignment
$$\beta$$
 defined on $\overline{C} \cup \overline{C}'$:
$$\beta \text{ satisfies Next}(\overline{C}, \overline{C}') \quad \text{if and only if} \quad \text{conf}(\overline{C}, \beta) \vdash_{\mathcal{M}} \text{conf}(\overline{C}', \beta)$$

Review: Validating Configurations

For an assignment β defined on variables in \overline{C} define

$$\mathsf{conf}(\overline{C},\beta) := \begin{cases} \beta(Q_q) = 1, \\ (q,p,w_0 \dots w_{p(n)}) \mid & \beta(P_p) = 1, \\ \beta(S_{w_i,i}) = 1 \text{ for all } 0 \le i < p(n) \end{cases}$$

Note: β may be defined on other variables besides those in \overline{C} .

Lemma 10.5: If β satisfies $Conf(\overline{C})$ then $|conf(\overline{C}, \beta)| = 1$. We can therefore write $conf(\overline{C}, \beta) = (q, p, w)$ to simplify notation.

Observations:

- $conf(\overline{C}, \beta)$ is a potential configuration of \mathcal{M} , but it may not be reachable from the start configuration of \mathcal{M} on input w.
- Conversely, every configuration $(q, p, w_1 \dots w_{p(n)})$ induces a satisfying assignment β or which conf $(\overline{C}, \beta) = (q, p, w_1 \dots w_{p(n)})$.

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Review: Start and End

Defined so far:

- $\bullet \ \operatorname{Conf}(\overline{C}) \colon \overline{C}$ describes a potential configuration
- $\operatorname{Next}(\overline{C}, \overline{C}')$: $\operatorname{conf}(\overline{C}, \beta) \vdash_{\mathcal{M}} \operatorname{conf}(\overline{C}', \beta)$

Start configuration: Let $w = w_0 \cdots w_{n-1} \in \Sigma^*$ be the input word

$$\mathsf{Start}_{\mathcal{M},w}(\overline{C}) := \mathsf{Conf}(\overline{C}) \land Q_{q_0} \land P_0 \land \bigwedge_{i=0}^{n-1} S_{w_i,i} \land \bigwedge_{i=n}^{p(n)-1} S_{\square,i}$$

Then an assignment β satisfies $\mathsf{Start}_{\mathcal{M},w}(\overline{C})$ if and only if \overline{C} represents the start configuration of \mathcal{M} on input w.

Accepting stop configuration:

$$\mathsf{Acc}\text{-}\mathsf{Conf}(\overline{C}) := \mathsf{Conf}(\overline{C}) \land Q_{q_{\mathsf{accent}}}$$

Then an assignment β satisfies $Acc\text{-Conf}(\overline{C})$ if and only if \overline{C} represents an accepting configuration of \mathcal{M} .

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Simulating Polynomial Space Computations

For Cook-Levin, we used one set of configuration variables for every computating step: polynomially time → polynomially many variables

Problem: For polynomial space, we have $2^{O(p(n))}$ possible steps . . .

What would Savitch do?

Define a formula CanYield_i $(\overline{C}_1, \overline{C}_2)$ to state that \overline{C}_2 is reachable from \overline{C}_1 in at most 2^i steps:

$$\begin{aligned} &\mathsf{CanYield}_0(\overline{C}_1,\overline{C}_2) := (\overline{C}_1 = \overline{C}_2) \vee \mathsf{Next}(\overline{C}_1,\overline{C}_2) \\ &\mathsf{CanYield}_{i+1}(\overline{C}_1,\overline{C}_2) := \exists \overline{C}.\mathsf{Conf}(\overline{C}) \wedge \mathsf{CanYield}_i(\overline{C}_1,\overline{C}) \wedge \mathsf{CanYield}_i(\overline{C},\overline{C}_2) \end{aligned}$$

But what is $\overline{C}_1 = \overline{C}_2$ supposed to mean here? It is short for:

$$\bigwedge_{q \in Q} Q_q^1 \leftrightarrow Q_q^2 \wedge \bigwedge_{0 \leq i < p(n)} P_i^1 \leftrightarrow P_i^2 \wedge \bigwedge_{a \in \Gamma, 0 \leq i < p(n)} S_{a,i}^1 \leftrightarrow S_{a,i}^2$$

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Did we do it?

Note: we used only existential quantifiers when defining $\varphi_{p,\mathcal{M},w}$:

$$\begin{split} & \mathsf{CanYield}_0(\overline{C}_1,\overline{C}_2) := (\overline{C}_1 = \overline{C}_2) \vee \mathsf{Next}(\overline{C}_1,\overline{C}_2) \\ & \mathsf{CanYield}_{i+1}(\overline{C}_1,\overline{C}_2) := \exists \overline{C}.\mathsf{Conf}(\overline{C}) \wedge \mathsf{CanYield}_{i}(\overline{C}_1,\overline{C}) \wedge \mathsf{CanYield}_{i}(\overline{C},\overline{C}_2) \\ & \varphi_{\mathcal{P},\mathcal{M},w} := \exists \overline{C}_1.\exists \overline{C}_2.\mathsf{Start}_{\mathcal{M},w}(\overline{C}_1) \wedge \mathsf{Acc\text{-}Conf}(\overline{C}_2) \wedge \mathsf{CanYield}_{\mathcal{Q}(n)}(\overline{C}_1,\overline{C}_2) \end{split}$$

Now that's quite interesting ...

- With only (non-negated) ∃ quantifiers, TRUE QBF coincides with SAT
- SAT is in NP
- So we showed that the word problem for PSpace NTMs to be in NP

So we found that NP = PSpace!

Strangely, most textbooks claim that this is not known to be true ... Are we up for the next Turing Award, or did we make a mistake?

Putting Everything Together

We define the formula $\varphi_{p,\mathcal{M},w}$ as follows:

$$\varphi_{p,M,w} := \exists \overline{C}_1. \exists \overline{C}_2. \mathsf{Start}_{M,w}(\overline{C}_1) \land \mathsf{Acc\text{-}Conf}(\overline{C}_2) \land \mathsf{CanYield}_{dp(p)}(\overline{C}_1, \overline{C}_2)$$

where we select d to be the least number such that \mathcal{M} has less than $2^{dp(n)}$ configurations in space p(n).

Lemma 10.7: $\varphi_{p,\mathcal{M},w}$ is satisfiable if and only if \mathcal{M} accepts w in space p(|w|).

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slide 15 of 34

Size

How big is $\varphi_{p,\mathcal{M},w}$?

$$\begin{split} & \mathsf{CanYield}_0(\overline{C}_1, \overline{C}_2) := (\overline{C}_1 = \overline{C}_2) \vee \mathsf{Next}(\overline{C}_1, \overline{C}_2) \\ & \mathsf{CanYield}_{i+1}(\overline{C}_1, \overline{C}_2) := \exists \overline{C}.\mathsf{Conf}(\overline{C}) \wedge \mathsf{CanYield}_{i}(\overline{C}_1, \overline{C}) \wedge \mathsf{CanYield}_{i}(\overline{C}, \overline{C}_2) \\ & \varphi_{p,M,w} := \exists \overline{C}_1. \exists \overline{C}_2.\mathsf{Start}_{M,w}(\overline{C}_1) \wedge \mathsf{Acc\text{-Conf}}(\overline{C}_2) \wedge \mathsf{CanYield}_{dp(n)}(\overline{C}_1, \overline{C}_2) \end{split}$$

Size of CanYield_{i+1} is more than twice the size of CanYield_i \rightarrow Size of $\varphi_{p,\mathcal{M},w}$ is in $2^{O(p(n))}$. Oops.

A correct reduction: We redefine CanYield by setting

$$\begin{split} &\mathsf{CanYield}_{i+1}(\overline{C}_1,\overline{C}_2) := \\ &\exists \overline{C}.\mathsf{Conf}(\overline{C}) \land \\ &\forall \overline{Z}_1. \forall \overline{Z}_2. (((\overline{Z}_1 = \overline{C}_1 \land \overline{Z}_2 = \overline{C}) \lor (\overline{Z}_1 = \overline{C} \land \overline{Z}_2 = \overline{C}_2)) \to \mathsf{CanYield}_i(\overline{Z}_1,\overline{Z}_2)) \end{split}$$

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 slide 16 of 34
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 slide 17 of 34

Size

Let's analyse the size more carefully this time:

$$\begin{split} &\mathsf{CanYield}_{i+1}(\overline{C}_1,\overline{C}_2) := \\ &\exists \overline{C}.\mathsf{Conf}(\overline{C}) \land \\ &\forall \overline{Z}_1.\forall \overline{Z}_2.(((\overline{Z}_1 = \overline{C}_1 \land \overline{Z}_2 = \overline{C}) \lor (\overline{Z}_1 = \overline{C} \land \overline{Z}_2 = \overline{C}_2)) \to \mathsf{CanYield}_i(\overline{Z}_1,\overline{Z}_2)) \end{split}$$

- CanYield_{i+1}(\overline{C}_1 , \overline{C}_2) extends CanYield_i(\overline{C}_1 , \overline{C}_2) by parts that are linear in the size of configurations \leadsto growth in O(p(n))
- Maximum index *i* used in $\varphi_{p,\mathcal{M},w}$ is dp(n), that is in O(p(n))
- Therefore: $\varphi_{p,\mathcal{M},w}$ has size $O(p^2(n))$ and thus can be computed in polynomial time

Exercise:

Why can we just use dp(n) in the reduction? Don't we have to compute it somehow? Maybe even in polynomial time?

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Complexity Theory

slide 18 of 34

A More Common Logical Problem in PSpace

Recall standard first-order logic:

- Instead of propositional variables, we have atoms (predicates with constants and variables)
- Instead of propositional evaluations we have first-order structures (or interpretations)
- First-order quantifiers can be used on variables
- Sentences are formulae where all variables are quantified
- A sentence can be satisfied or not by a given first-order structure

FOL MODEL CHECKING

Input: A first-order sentence φ and a finite first-order

structure \mathcal{I} .

Problem: Is φ satisfied by I?

The Power of QBF

Theorem 10.4: TRUE QBF is PSpace-complete.

Proof:

- TRUE QBF ∈ PSpace:
 Give an algorithm that runs in polynomial space.
- (2) **True QBF** is PSpace-hard: Proof by reduction from the word problem for polynomially space-bounded TMs.

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First-Order Logic is PSpace-complete

Theorem 10.8: FOL Model Checking is PSpace-complete.

Proof:

- FOL MODEL CHECKING ∈ PSpace:
 Give algorithm that runs in polynomial space.
- (2) **FOL Model Checking** is PSpace-hard: Proof by reduction **True QBF** \leq_p **FOL Model Checking**.

Markus Krötzsch, 21th Nov 2017 Complexity Theory slide 20 of 34 Markus Krötzsch, 21th Nov 2017 Complexity Theory slide 21 of 34

Checking FOL Models in Polynomial Space (Sketch)

```
01 EVAL(\varphi, I) {
      switch (\varphi):
         case p(c_1, \ldots, c_n): return \langle c_1, \ldots, c_n \rangle \in p^I
03
         case \neg \psi: return NOT Eval(\psi, I)
04
05
         case \psi_1 \wedge \psi_2: return Eval(\psi_1, I) AND Eval(\psi_2, I)
         case \exists x.\psi:
06
            for c \in \Lambda^I:
07
               if \text{Eval}(\psi[x \mapsto c], I) : return TRUE
08
            // eventually, if no success:
09
            return FALSE
10
11 }
```

- We can assume φ only uses \neg , \wedge and \exists (easy to get)
- We use Δ^I to denote the (finite!) domain of I
- We allow domain elements to be used like constants in the formula

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First-Order Logic is PSpace-complete

Theorem 10.8: FOL Model Checking is PSpace-complete.

Proof:

- FOL MODEL CHECKING ∈ PSpace:
 Give algorithm that runs in polynomial space.
- (2) **FOL Model Checking** is PSpace-hard: Proof by reduction **True QBF** \leq_p **FOL Model Checking**.

Hardness of FOL Model Checking

Given: a QBF $\varphi = Q_1 X_1 \cdots Q_\ell X_\ell \psi$

FOL Model Checking Problem:

- Interpretation domain $\Delta^I := \{0, 1\}$
- Single predicate symbol true with interpretation $true^{I} = \{(1)\}$
- FOL formula φ' is obtained by replacing variables in input QBF with corresponding first-order expressions:

$$Q_1 x_1 \cdots Q_\ell x_\ell \psi[X_1 \mapsto \operatorname{true}(x_1), \dots, X_\ell \mapsto \operatorname{true}(x_\ell)]$$

Lemma 10.9: $\langle I, \varphi' \rangle \in \text{FOL Model Checking if and only if } \varphi \in \text{True QBF}.$

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FOL Model Checking: Practical Significance

Why is **FOL Model Checking** a relevant problem?

Correspondence with database query answering:

- Finite first-order interpretation = database
- First-order logic formula = database query
- Satisfying assignments (for non-sentences) = query results

Known correspondence:

As a query language, FOL has the same expressive power as (basic) SQL (relational algebra).

Corollary 10.10: Answering SQL queries over a given database is PSpacecomplete.

Markus Krötzsch, 21th Nov 2017 Complexity Theory slide 24 of 34 Markus Krötzsch, 21th Nov 2017 Complexity Theory slide 25 of 34

Games

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Example: The Formula Game

A contrived game, to illustrate the idea:

- Given: a propositional logic formula φ with consecutively numbered variables X_1, \ldots, X_ℓ .
- Two players take turns in selecting values for the next variable:
 - Player 1 sets X_1 to true or false
 - Player 2 sets X₂ to true or false
 - Player 1 sets X_3 to true or false

- ...

until all variables are set.

• Player 1 wins if the assignment makes φ true. Otherwise, Player 2 wins.

Games as Computational Problems

Many single-player games relate to NP-complete problems:

- Sudoku
- Minesweeper
- Tetris
- ...

Decision problem: Is there a solution? (For Tetris: is it possible to clear all blocks?)

What about two-player games?

- Two players take moves in turns
- The players have different goals
- The game ends if a player wins

Decision problem: Does Player 1 have a winning strategy?

In other words: can Player 1 enforce winning, whatever Player 2 does?

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Deciding the Formula Game

FORMULA GAME

Input: A formula φ .

Problem: Does Player 1 have a winning strategy on φ ?

Theorem 10.11: FORMULA GAME is PSpace-complete.

Proof sketch: Formula Game is essentially the same as True QBF.

Having a winning strategy means: there is a truth value for X_1 , such that, for all truth values of X_2 , there is a truth value of X_3 , ... such that φ becomes true.

If we have a QBF where quantifiers do not alternate, we can add dummy quantifiers and variables that do not change the semantics to get the same alternating form as for the Formula Game.

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Example: The Geography Game

A children's game:

- Two players are taking turns naming cities.
- Each city must start with the last letter of the previous.
- Repetitions are not allowed.
- The first player who cannot name a new city looses.

A mathematicians' game:

- Two players are marking nodes on a directed graph.
- Each node must be a successor of the previous one.
- · Repetitions are not allowed.
- The first player who cannot mark a new node looses.

Decision problem (GENERALISED) GEOGRAPHY:

given a graph and start node, does Player 1 have a winning strategy?

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GEOGRAPHY is PSpace-hard

Let φ with variables X_1,\ldots,X_ℓ be an instance of Formula Game.

Without loss of generality, we assume:

- ℓ is odd (Player 1 gets the first and last turn)
- φ is in CNF

We now build a graph that encodes Formula Game in terms of Geography

- The left-hand side of the graph is a chain of diamond structures that represent the choices that players have when assigning truth values
- The right-hand side of the graph encodes the structure of φ : Player 2 may choose a clause (trying to find one that is not true under the assignment); Player 1 may choose a literal (trying to find one that is true under the assignment).

(see board or [Sipser, Theorem 8.14])

GEOGRAPHY is PSpace-complete

Theorem 10.12: GENERALISED GEOGRAPHY is PSpace-complete.

Proof:

(1) **Geography** ∈ PSpace:

Give algorithm that runs in polynomial space. It is not difficult to provide a recursive algorithm similar to the one for **True QBF** or **FOL MODEL CHECKING**.

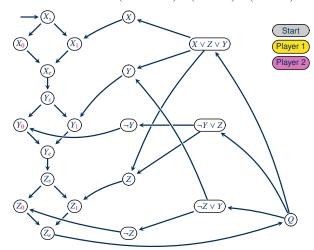
(2) **Geography** is PSpace-hard:

Proof by reduction Formula Game \leq_p Geography.

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GEOGRAPHY is PSpace-hard: Example

We consider the formula $\exists X. \forall Y. \exists Z. (X \lor Z \lor Y) \land (\neg Y \lor Z) \land (\neg Z \lor Y)$



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Summary and Outlook

TRUE QBF is PSpace-complete

FOL Model Checking and the related problem of SQL query answering are PSpace-complete

slide 34 of 34

Some games are PSpace-complete

What's next?

- Some more remarks on games
- Logarithmic space
- Complements of space classes

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