

# DATABASE THEORY

Lecture 9: Query Optimisation

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TU Dresden, 29th May 2018

### Static Query Optimisation

Can we optimise query execution without looking at the database?

Queries are logical formulae, so some things might follow ....

#### Query equivalence:

Will the queries  $Q_1$  and  $Q_2$  return the same answers over any database?

- In symbols:  $Q_1 \equiv Q_2$
- We have seen many examples of equivalent transformations in exercises
- Several uses for optimisation:
  - $\rightarrow$  DBMS could run the "nicer" of two equivalent queries
- $\rightsquigarrow$  DBMS could use cached results of one query for the other
- $\rightsquigarrow$  Also applicable to equivalent subqueries

### Review

We have studied FO queries and the simpler conjunctive queries

Our focus was on query answering complexity:

	Combined complexity	Query complexity	Data complexity
FO queries	PSpace-comp.	PSpace-comp.	in AC <sup>0</sup>
Conjunctive queries	NP-comp.	NP-comp.	in AC <sup>0</sup>
Tree CQs	in P	in P	in AC <sup>0</sup>
Bounded Treewidth CQs	in P	in P	in AC <sup>0</sup>
Bounded Hypertree width CQs	in P	in P	in AC <sup>0</sup>

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## Static Query Optimisation (2)

#### Other things that could be useful:

- Query emptiness: Will query Q never have any results?
  - → Special equivalence with an "empty query"
  - (e.g.,  $x \neq x$  or  $R(x) \land \neg R(x)$ )
  - $\rightsquigarrow$  Empty (sub)queries could be answered immediately
- Query containment: Will the query Q<sub>1</sub> return a subset of the results of query Q<sub>2</sub>? (in symbols: Q<sub>1</sub> ⊑ Q<sub>2</sub>)
  - $\rightarrow$  Generalisation of equivalence:
    - $Q_1 \equiv Q_2$  if and only if  $Q_1 \sqsubseteq Q_2$  and  $Q_2 \sqsubseteq Q_1$
- Query minimisation: Given a query *Q*, can we find an equivalent query *Q'* that is "as simple as possible."

### First-order logic: Decidable or not?

We have seen in recent lectures:

- FO queries can be answered in PSpace (combined complexity) and AC<sup>0</sup> (data complexity)
- FO queries correspond to relational algebra, so every relational DBMS answers FO queries in practice

In foundational courses on logic, you should have learned

• Reasoning in first-order logic is undecidable

Indeed, Wikipedia says it too (so it must be true  $\ldots$ ):

 "Unlike propositional logic, first-order logic is undecidable (although semidecidable)" [Wikidedia article First-order logic]

Is the first-order logic we use different from the first-order logic used elsewhere? Is mathematics inconsistent?

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Back to Query Optimisation

#### What do these results mean for query optimisation?

#### Two similar questions:

- (1) Are the Boolean FO queries  $\varphi_1$  and  $\varphi_2$  equivalent?
- (2) Are the FO sentences  $\varphi_1$  and  $\varphi_2$  equivalent?
- $\sim$  So FO query equivalence is undecidable?

However, (1) is not equivalent to (2) but to the following:

(2') Are the FO sentences  $\varphi_1$  and  $\varphi_2$  equivalent in all finite interpretations?

 $\rightsquigarrow$  finite-model reasoning for FO logic

# Solving the Mystery

All of the above are true for first-order logic but people are studying different decision problems:

### Problem 1: Model Checking

- Given: a logical sentence  $\varphi$  and a finite model I
- Question: is I a model for  $\varphi$ , i.e., is  $\varphi$  satisfied in I?
- Corresponds to Boolean query entailment
- PSpace-complete for first-order sentences

### Problem 2: Satisfiability Checking

- Given: a logical sentence  $\varphi$
- Question: does  $\varphi$  have any model?
- (Turing-)equivalent to many reasoning problems (entailment, tautology, unsatisfiability, etc.)
- Undecidable for first-order sentences

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## Finite-Model Reasoning

#### Does it really make a difference?

#### Yes. Example formula $\varphi$ :

	$(\forall x. \exists y. R(x, y)) \land$
<i>R</i> is a function	$(\forall x, y_1, y_2.R(x, y_1) \land R(x, y_2) \rightarrow y_1 \approx y_2) \land$
and injective	$(\forall x_1, x_2, y.R(x_1, y) \land R(x_2, y) \rightarrow x_1 \approx x_2) \land$
but not surjective	$(\exists y. \forall x. \neg R(x, y))$

## Such a function R can only exist over an infinite domain.

- $\rightsquigarrow$  over finite models,  $\varphi$  is unsatisfiable
- $\rightsquigarrow \varphi$  is finitely equivalent to  $\forall x.R(x,x) \land \neg R(x,x)$
- $\rightsquigarrow$  this equivalence does not hold on arbitrary models

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## Trakhtenbrot's Theorem

Is finite-model reasoning easier than FO reasoning in general?

#### Unfortunately no:

**Theorem 9.1 (Boris Trakhtenbrot, 1950):** Finite-model reasoning of first-order logic is undecidable.

Interesting observation:

- The set of all true sentences (tautologies) of FO is recursively enumerable ("FO entailment is semi-decidable")
- but the set of all FO tautologies under finite models is not.
- ightarrow finite model reasoning is harder than FO reasoning in this case!

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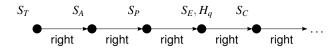
## TM Runs as Finite Models

Recall: Turing Machine is given as  $\mathcal{M} = \langle Q, q_{\text{start}}, q_{\text{acc}}, \Sigma, \Delta \rangle$ (state set Q, tape alphabet  $\Sigma$  with blank  $\Box$ , transitions  $\Delta \subseteq (Q \times \Sigma) \times (Q \times \Sigma \times \{l, r, s\})$ )

A configuration is a (finite piece of) tape + a position + a state:



Here is how we want part of our model (database) to look:



## Let's Prove Trakhtenbrot's Theorem

#### Proof idea: reduce the Halting Problem to finite satisfiability

- Input of the reduction: a deterministic Turing Machine (DTM) *M* and an input string *w*
- Output of the reduction: a first-order formula  $\varphi_{\mathcal{M},w}$
- Such that  $\mathcal{M}$  halts on w if and only if  $\varphi_{\mathcal{M},w}$  has a finite model

Ok, this would do, because Halting of DTMs is undecidable, but how should we achieve this?

- Capture the computation of the DTM in a finite model
- The model contains the whole run: the tape and state for every computation step
- A finite part of the tape is enough if the DTM halts

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# Encoding TM Runs as Relational Structures

We use several unary predicate symbols to mark tape cells:

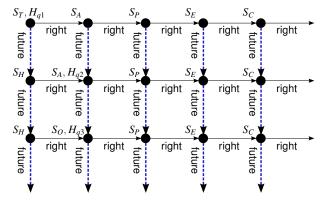
- $S_{\sigma}(\cdot)$  for each  $\sigma \in \Sigma$ : tape cell contains symbol  $\sigma$
- $H_q(\cdot)$  for each  $q \in Q$ : head is at tape cell, and TM is in state q

We use two binary predicate symbols to connect tape positions:

- right( $\cdot, \cdot$ ): neighbouring tape cells at same step
- right<sup>+</sup>( $\cdot$ ,  $\cdot$ ): transitive super-relation of right
- $\mathsf{future}(\cdot,\cdot)\mathsf{:}$  tape cells at same position in consecutive steps

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### Intended Database





We now need to specify formulae to enforce this intended structure (or something that is close enough to it).

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### Consistent Tape Contents, Head, and State

#### A cell can only contain one symbol:

$$\varphi_{S} = \bigwedge_{\sigma, \sigma' \in \Sigma, \sigma \neq \sigma'} \forall x. (\neg S_{\sigma}(x) \lor \neg S_{\sigma'}(x))$$

The TM is never at more than one position:

$$\varphi_{H} = \bigwedge_{q \in \mathcal{Q}} \forall x, y. \left( H_{q}(x) \land \mathsf{right}^{+}(x, y) \to \bigwedge_{q' \in \mathcal{Q}} \neg H_{q'}(y) \right) \land$$
$$\bigwedge_{q \in \mathcal{Q}} \forall x, y. \left( \mathsf{right}^{+}(x, y) \land H_{q}(y) \to \bigwedge_{q' \in \mathcal{Q}} \neg H_{q'}(x) \right)$$

The TM can only be in one state:

$$\varphi_{\mathcal{Q}} = \bigwedge_{q,q' \in \mathcal{Q}, q \neq q'} \forall x. (\neg H_q(x) \lor \neg H_{q'}(x))$$

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### Defining the Initial Configuration

Require that right<sup>+</sup> is a transitive super-relation of right:

$$\begin{split} \varphi_{\mathsf{right}^+} &= \forall x, y. (\mathsf{right}(x, y) \to \mathsf{right}^+(x, y)) \land \\ &\forall x, y, z. (\mathsf{right}(x, y) \land \mathsf{right}^+(y, z) \to \mathsf{right}^+(x, z)) \end{split}$$

Define start configuration for an input word  $w = \sigma_1 \sigma_2 \dots \sigma_n$ :

 $\varphi_w = \exists x_1, \dots, x_n. H_{q_{\text{start}}}(x_1) \land \neg \exists z. \mathsf{right}(z, x_1) \land$  $S_{\sigma_1}(x_1) \land \neg \exists z. \mathsf{future}(z, x_1) \land \mathsf{right}(x_1, x_2) \land$  $S_{\sigma_2}(x_2) \land \neg \exists z. \mathsf{future}(z, x_2) \land \mathsf{right}(x_2, x_3) \land$ 

 $S_{\sigma_n}(x_n) \land \neg \exists z. \mathsf{future}(z, x_n) \land \\ \forall y. (\mathsf{right}^+(x_n, y) \to (S_{-}(y) \land \neg \exists z. \mathsf{future}(z, y)))$ 

 $\sim$  there can be any number of cells right of the input, but they must contain  $\Box.$  Markus Krötzsch, 29th May 2018 Database Theory

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### Transitions

For every non-moving transition  $\delta = \langle q, \sigma, q', \sigma', s \rangle \in \Delta$ :

$$\varphi_{\delta} = \forall x. H_q(x) \land S_{\sigma}(x) \rightarrow \exists y. \mathsf{future}(x, y) \land S_{\sigma'}(y) \land H_{q'}(y)$$

For every right-moving transition  $\delta = \langle q, \sigma, q', \sigma', r \rangle \in \Delta$ :

$$\varphi_{\delta} = \forall x. H_q(x) \land S_{\sigma}(x) \to \exists y. \mathsf{future}(x, y) \land S_{\sigma'}(y) \land \exists z. \mathsf{right}(y, z) \land H_{q'}(z)$$

For every left-moving transition  $\delta = \langle q, \sigma, q', \sigma', l \rangle \in \Delta$ :

$$\varphi_{\delta} = \forall x.H_q(x) \land S_{\sigma}(x) \land (\exists v.\operatorname{right}(v, x)) \to \exists y.\operatorname{future}(x, y) \land S_{\sigma'}(y) \land \exists z.\operatorname{right}(y, z) \land H_{q'}(z)$$

Summing all up:

$$\varphi_{\Delta} = \bigwedge_{\delta \in \Delta} \varphi_{\delta}$$

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### Preserve Tape if not Changed by Transition

#### Contents of tape cells that are not under the head are kept:

$$\varphi_{\mathsf{mem}} = \forall x, y. \bigwedge_{\sigma \in \Sigma} \left( S_{\sigma}(x) \land \left( \bigwedge_{q \in Q} \neg H_q(x) \right) \land \mathsf{future}(x, y) \to S_{\sigma}(y) \right)$$

### Building the Configuration Grid

If one cell has a future  $(\rightarrow)$  or past  $(\leftarrow)$ , respectively, all cells of the tape do:

 $\varphi_{fp1} = \forall x_2, y_1.(\exists x_1.right(x_1, y_1) \land future(x_1, x_2)) \leftrightarrow (\exists y_2.future(y_1, y_2) \land right(x_2, y_2))$  $\varphi_{fp2} = \forall x_1, y_2.(\exists y_1.right(x_1, y_1) \land future(y_1, y_2)) \leftrightarrow (\exists x_2.future(x_1, x_2) \land right(x_2, y_2))$ 

Left (l) and right (r) neighbours, and future (f) and past (p) are unique:

$$\begin{split} \varphi_r &= \forall x, y, y'.\mathsf{right}(x, y) \land \mathsf{right}(x, y') \to y \approx y' \\ \varphi_l &= \forall x, x', y.\mathsf{right}(x, y) \land \mathsf{right}(x', y) \to x \approx x' \\ \varphi_f &= \forall x, y, y'.\mathsf{future}(x, y) \land \mathsf{future}(x, y') \to y \approx y' \\ \varphi_p &= \forall x, x', y.\mathsf{future}(x, y) \land \mathsf{future}(x', y) \to x \approx x' \end{split}$$

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### Finishing the Proof of Trakhtenbrot's Theorem

#### We obtain a final FO formula

 $\varphi_{\mathcal{M},w} = \varphi_{\mathsf{right}^{+}} \land \varphi_{w} \land \varphi_{S} \land \varphi_{H} \land \varphi_{Q} \land \varphi_{\Delta} \land \varphi_{\mathsf{mem}} \land$  $\varphi_{fp1} \land \varphi_{fp2} \land \varphi_{r} \land \varphi_{l} \land \varphi_{f} \land \varphi_{p}$ 

Then  $\varphi_{\mathcal{M},w}$  is finitely satisfiable if and only if  $\mathcal{M}$  halts on w:

- If  $\mathcal{M}$  has a finite run when started on w, then  $\varphi_{\mathcal{M},w}$  has a finite model that encodes this run.
- If φ<sub>M,w</sub> has a finite model, then we can extract from this model a finite run of M on w.

Note: the proof can be made to work using only one binary relation symbol and no equality (not too hard, but less readable)

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## The Impossibility of FO Query Optimisation

Trakhtenbrot's Theorem has severe consequences for static FO query optimisation

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Theorem 9.2 (Exercise): All of the following decision problems are undecidable:

- Query equivalence
- Query emptiness
- Query containment

→ "perfect" FO query optimisation is impossible

Other important questions about FO queries are also undecidable, for example:

• Is a given FO query domain independent?

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## Is Query Optimisation Futile?

#### Not quite: things are simpler for conjunctive queries

	Example 9.3: Conjunctive query containment:		
	$Q_1$ : $\exists x, y, z. \ R(x, y) \land R(y, y) \land R(y, z)$		
	$Q_2$ : $\exists u, v, w, t. R(u, v) \land R(v, w) \land R(w, t)$		
$Q_1$ find <i>R</i> -paths of length two with a loop in the middle $Q_2$ find <i>R</i> -paths of length three			
	$\rightarrow$ in a loop one can find paths of any length $\rightarrow O_1 \sqsubset O_2$		

## Summary and Outlook

There are many well-defined static optimisation tasks that are independent of the database

→ query equivalence, containment, emptiness

Unfortunately, all of them are undecidable for FO queries

 $\rightsquigarrow$  Slogan: "all interesting questions about FO queries are undecidable"

#### **Open questions:**

- More positive results for conjunctive queries
- Measure expressivity rather than just complexity
- Look at query languages beyond first-order logic

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