

DEDUCTION SYSTEMS

Optimizations for Tableau Procedures

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Chair for Knowledge-Based Systems

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Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

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Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

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- C is satisfiable iff there is a successful tableau construction

Treatment of Knowledge Bases

we condense the TBox into one concept:

for $\mathcal{T} = \{C_i \sqsubseteq D_i \mid 1 \leq i \leq n\}$, $C_{\mathcal{T}} = \text{NNF}(\bigwedge_{1 \leq i \leq n} \neg C_i \sqcup D_i)$

we extend the rules of the \mathcal{ALC} tableau algorithm:

\mathcal{T} -rule: for an arbitrary $v \in V$ with $C_{\mathcal{T}} \notin L(v)$,
let $L(v) := L(v) \cup \{C_{\mathcal{T}}\}$.

in order to take an ABox \mathcal{A} into account, initialize G such that

- V contains a node v_a for every individual a in \mathcal{A}
- $L(v_a) = \{C \mid C(a) \in \mathcal{A}\}$
- $\langle v_a, v_b \rangle \in E$ iff $r(a, b) \in \mathcal{A}$

Extensions of the Logic

- plus inverses (\mathcal{ALCI}): inverse roles in edge labels, definition and use of r -neighbors instead of r -successors in tableau rules
- plus functional roles (\mathcal{ALCIF}): merging of nodes to account for functionality

blocking guarantees termination:

- \mathcal{ALC} subset-blocking
- plus inverses (\mathcal{ALCI}): equality blocking
- plus functional roles (\mathcal{ALCIF}): pairwise blocking

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Unfolding

- \mathcal{T} -rule is not necessary if \mathcal{T} is **unfoldable**, i.e., every axiom is:
 - **definitorial**: form $A \sqsubseteq C$ or $A \equiv C$ for A a concept name
($A \equiv C$ corresponds to $A \sqsubseteq C$ and $C \sqsubseteq A$)
 - **acyclic**: C uses A neither directly nor indirectly
 - **unique**: only one such axiom exists for every concept name A

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 - **acyclic**: C uses A neither directly nor indirectly
 - **unique**: only one such axiom exists for every concept name A
- If \mathcal{T} is unfoldable, the TBox can be (**unfolded**) into a concept

Unfolding Example

- We check satisfiability of A w.r.t. the TBox \mathcal{T}

\mathcal{T} :

$$A \sqsubseteq B \sqcap \exists r.C$$

$$B \equiv C \sqcup D$$

$$C \sqsubseteq \exists r.D$$

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$$\begin{aligned} & A \\ \rightsquigarrow & A \sqcap B \sqcap \exists r.C \\ \rightsquigarrow & A \sqcap (C \sqcup D) \sqcap \exists r.C \end{aligned}$$

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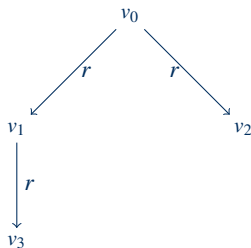
- A is satisfiable w.r.t. \mathcal{T} iff

$$A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$$

is satisfiable w.r.t. the empty TBox

Tableau Algorithm Example with Unfolding

We obtain the following contradiction-free tableau for the satisfiability of
 $U = A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$:



$$L(v_0) = \{U, A, (C \sqcap \exists r.D) \sqcup D, \\ \exists r.(C \sqcap \exists r.D), C \sqcap \exists r.D, \\ C, \exists r.D\}$$

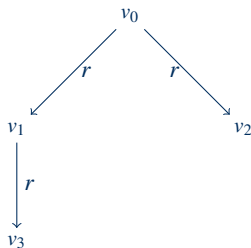
$$L(v_1) = \{C \sqcap \exists r.D, C, \exists r.D\}$$

$$L(v_2) = \{D\}$$

$$L(v_3) = \{D\}$$

Tableau Algorithm Example with Unfolding

We obtain the following contradiction-free tableau for the satisfiability of
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$$L(v_1) = \{C \sqcap \exists r.D, C, \exists r.D\}$$

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Only one disjunctive decision left!

Lazy Unfolding

- computation of NNF together with unfolding may decrease performance, e.g.:
 - satisfiability of $C \sqcap \neg C$ w.r.t. $\mathcal{T} = \{C \sqsubseteq A \sqcap B\}$
 - unfolding: $C \sqcap A \sqcap B \sqcap \neg(C \sqcap A \sqcap B)$
 - NNF + unfolding: $C \sqcap A \sqcap B \sqcap (\neg C \sqcup \neg A \sqcup \neg B)$

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 - satisfiability of $C \sqcap \neg C$ w.r.t. $\mathcal{T} = \{C \sqsubseteq A \sqcap B\}$
 - unfolding: $C \sqcap A \sqcap B \sqcap \neg(C \sqcap A \sqcap B)$
 - NNF + unfolding: $C \sqcap A \sqcap B \sqcap (\neg C \sqcup \neg A \sqcup \neg B)$
- better: apply NNF and unfolding if needed, via corresponding tableau rules:

- $A \equiv C \rightsquigarrow A \sqsubseteq C$ and $A \sqsupseteq C$

\sqsubseteq -rule: For $v \in V$ such that $A \sqsubseteq C \in \mathcal{T}$, $A \in L(v)$ and $C \notin L(v)$
let $L(v) := L(v) \cup C$.

\sqsupseteq -rule: For $v \in V$ such that $A \sqsupseteq C \in \mathcal{T}$, $\neg A \in L(v)$ and $\neg C \notin L(v)$
let $L(v) := L(v) \cup \{\neg C\}$.

\neg -rule: For $v \in V$ such that $\neg C \in L(v)$ and $\text{NNF}(\neg C) \notin L(v)$,
let $L(v) := L(v) \cup \{\text{NNF}(\neg C)\}$.

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Absorption

- What if \mathcal{T} is not unfoldable?
 - Separate \mathcal{T} into \mathcal{T}_u (unfoldable part) and \mathcal{T}_g (GCIs, not unfoldable)
 - \mathcal{T}_u is treated via \sqsubseteq - and \sqsupseteq -rules
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- absorption decreases \mathcal{T}_g and increases \mathcal{T}_u
 - 1 take an axiom from \mathcal{T}_g , e.g., $A \sqcap B \sqsubseteq C$
 - 2 transform the axiom: $A \sqsubseteq C \sqcup \neg B$
 - 3 if \mathcal{T}_u contains an axiom of the form $A \equiv D$ ($A \sqsubseteq D$ and $D \sqsupseteq A$), then $A \sqsubseteq C \sqcup \neg B$ cannot be absorbed;
 $A \sqsubseteq C \sqcup \neg B$ remains in \mathcal{T}_g
 - 4 otherwise, if \mathcal{T}_u contains an axiom of the form $A \sqsubseteq D$, then absorb $A \sqsubseteq C \sqcup \neg B$ resulting in $A \sqsubseteq D \sqcap (C \sqcup \neg B)$
 - 5 otherwise move $A \sqsubseteq C \sqcup \neg B$ to \mathcal{T}_u

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- If $A \equiv D \in \mathcal{T}_u$, try rewriting/absorption with other axioms in \mathcal{T}_u

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 - 5 otherwise move $A \sqsubseteq C \sqcup \neg B$ to \mathcal{T}_u
- If $A \equiv D \in \mathcal{T}_u$, try rewriting/absorption with other axioms in \mathcal{T}_u
- nondeterministic: $B \sqsubseteq C \sqcup \neg A$ also possible

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Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

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$$v \quad \sqcap\text{-rule} \quad L(v) \quad := \quad L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \\ \exists r. \neg A, \forall r. A\}$$

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	\vdots	\vdots
	\vdots	\vdots
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w		

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v \downarrow r \downarrow w	\sqcap -rule	$L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$
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	\vdots	\vdots
	\sqcup -rule	$L(v) := L(v) \cup \{C_n\}$
	\exists -rule	$L(w) := \{\neg A\}$
	\forall -rule	$L(w) := \{\neg A, A\}$ <i>clash</i>

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 \vdots \\
 \exists\text{-rule} \\
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 \end{array}
 \quad
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 \sqcap\text{-rule} \\
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 \quad
 \begin{array}{l}
 L(v) \\
 \vdots \\
 L(v) \\
 L(v)
 \end{array}
 \quad
 \begin{array}{l}
 := \\
 := \\
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 \end{array}
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 L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \\
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 L(v) \cup \{C_1\} \\
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 \{A\} \\
 \{\neg A, A\} \text{ clash}
 \end{array}$$

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	\vdots	\vdots		\vdots
	\sqcup-rule	$L(v)$:=	$L(v) \cup \{C_n\}$
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r	⋮	⋮
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w			

- exponentially big search space is traversed

Dependency-Directed Backtracking

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 - initially, all concepts are tagged with \emptyset
 - tableau rules combine and extend these tags
 - \sqcup -rule adds the tag $\{d\}$ to the existing tag, where d is the \sqcup -depth (number of \sqcup -rules applied by now)
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 - jump back to the last **relevant** application of a \sqcup -rule
- irrelevant part of the search space is not considered

Dependency-Directed Backtracking Example

$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$ tagged with \emptyset

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Dependency-Directed Backtracking Example

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 \downarrow
 r
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 w

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- Output **false** (unsatisfiable)

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Further Optimizations

- Simplification and Normalization
 - quick recognition of trivial contradictions
 - normalization, e.g., $A \cap (B \cap C) \equiv \cap\{A, B, C\}$, $\forall r.C \equiv \neg\exists r.\neg C$
 - simplification, e.g., $\cap\{A, \dots, \neg A, \dots\} \equiv \perp$, $\exists r.\perp \equiv \perp$, $\forall r.\top \equiv \top$

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Optimizing Classification

One of the most wide-spread tasks for automated reasoning is **classification**

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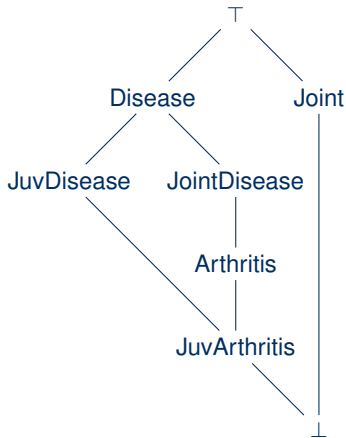
- compute all subclass relationships between atomic concepts in \mathcal{T}
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- naïve approach needs n^2 subsumption checks for n concept names
- normally cached in the **concept hierarchy** graph

Concept Hierarchy Graph



Optimizing Classification

most wide-spread technique is called [enhanced traversal](#)

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Optimizing Classification

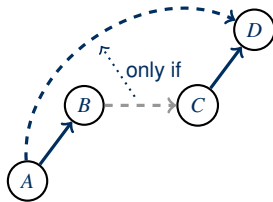
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- bottom-up phase: recognize direct subconcepts

Optimizing Classification

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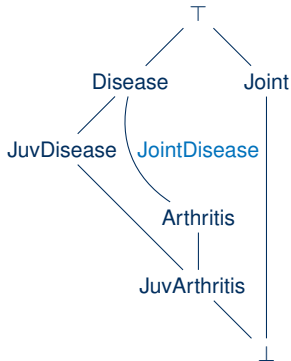
- hierarchy is created incrementally by introducing concept after concept
- top-down phase: recognize direct superconcepts
- bottom-up phase: recognize direct subconcepts
- transitivity of \sqsubseteq used to save checks



- If $A \sqsubseteq B$ and $C \sqsubseteq D$ hold,
- then $B \sqsubseteq C \rightarrow A \sqsubseteq D$
- and $A \not\sqsubseteq D \rightarrow B \not\sqsubseteq C$

Enhanced Traversal Example

already created hierarchy:



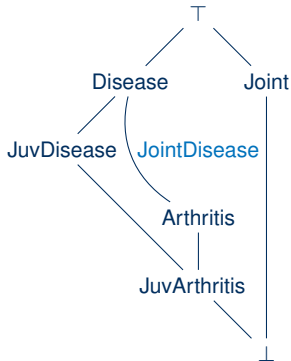
Goal: insertion of JointDisease

Top-Down Phase:

Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



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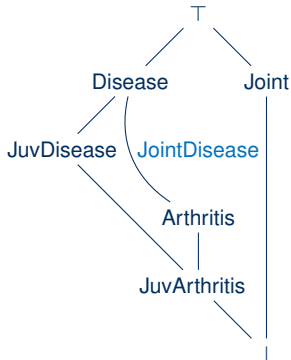
Top-Down Phase:

- $\text{JointDisease} \sqsubseteq ? \text{Disease}$

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Enhanced Traversal Example

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Goal: insertion of JointDisease

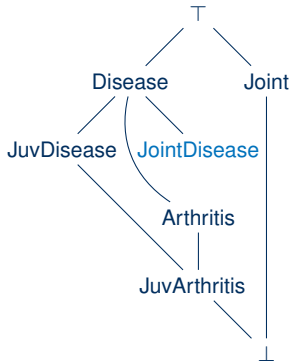
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Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



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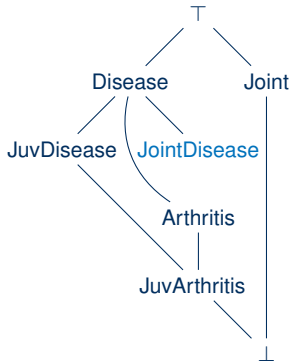
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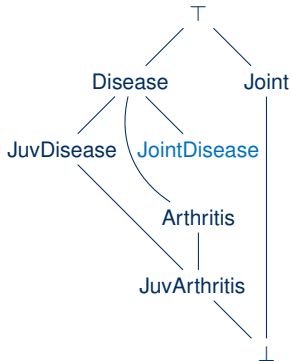
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Bottom-Up Phase:

Enhanced Traversal Example

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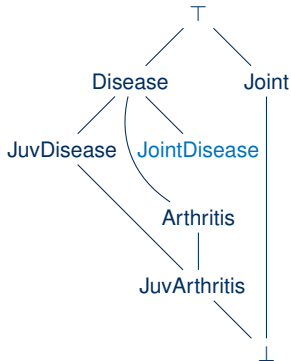
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Enhanced Traversal Example

already created hierarchy:



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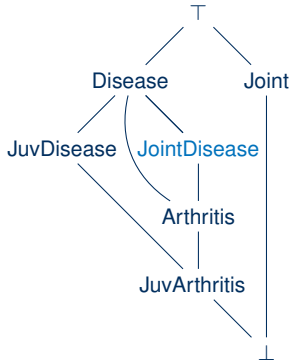
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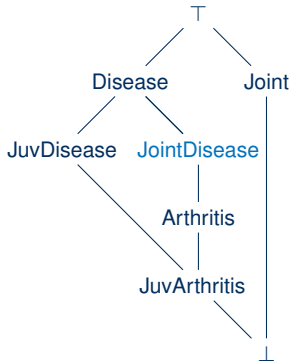
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Summary

- we have a tableau algorithm for \mathcal{ALCIF} knowledge bases
 - ABox treated like for \mathcal{ALC}
 - number restrictions are treated similar to functionality and existential quantifiers
- termination via cycle detection
 - becomes harder as the logic becomes more expressive
- naive tableau algorithm not sufficiently performant
- diverse optimizations improve average case
- specific methods for classification
 - enhanced traversal
- tableaux algorithms or variants modifications thereof are the basis of many OWL reasoners