

Artificial Intelligence, Computational Logic

### DEDUCTION SYSTEMS

Lecture 5 ASP Solving I \*slides adapted from Torsten Schaub [Gebser et al.(2012)]

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### Conflict-driven ASP Solving: Overview



### Outline



### Motivation of Conflict-driven ASP Solving

- Goal Approach to computing stable models of logic programs, based on concepts from
  - Constraint Processing (CP) and
  - Satisfiability Testing (SAT)
- Idea View inferences in ASP as unit propagation on nogoods
- Benefits:
  - A uniform constraint-based framework for different kinds of inferences in ASP
  - Advanced techniques from the areas of CP and SAT
  - Highly competitive implementation

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Boolean constraints

Nogoods from logic programs
Nogoods from program completion

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- Representation:  $\langle T, F \rangle$ , where
  - T is the set of all *true* atoms and
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- Definition: For  $\langle T_1, F_1 \rangle$  and  $\langle T_2, F_2 \rangle$ , define
  - $-\langle T_1, F_1 \rangle \sqsubseteq \langle T_2, F_2 \rangle$  iff  $T_1 \subseteq T_2$  and  $F_1 \subseteq F_2$
  - $\langle T_1, F_1 \rangle \sqcup \langle T_2, F_2 \rangle = \langle T_1 \cup T_2, F_1 \cup F_2 \rangle$

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PreliminariesPartial InterpretationsUnfounded Sets

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- Rules satisfying Condition 1 are not usable for further derivations
- Condition 2 is the unfounded set condition treating cyclic derivations: All rules still being usable to derive an atom in *U* require an(other) atom in *U* to be true



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- $\{a, b\}$  is an unfounded set of *P* wrt  $\langle \emptyset, \emptyset \rangle$
- $\{a, b\}$  is an unfounded set of *P* wrt any partial interpretation

### Outline



• An assignment A over  $dom(A) = atom(P) \cup body(P)$  is a sequence

 $(\sigma_1,\ldots,\sigma_n)$ 

of signed literals  $\sigma_i$  of form Tv or Fv for  $v \in dom(A)$  and  $1 \le i \le n$ 

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- · We sometimes identify an assignment with the set of its literals
- Given this, we access true and false propositions in A via

$$A^{T} = \{v \in dom(A) \mid Tv \in A\} \text{ and } A^{F} = \{v \in dom(A) \mid Fv \in A\}$$

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- For a nogood  $\delta$ , a literal  $\sigma \in \delta$ , and an assignment *A*, we say that  $\overline{\sigma}$  is unit-resulting for  $\delta$  wrt *A*, if

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 For a set Δ of nogoods and an assignment A, unit propagation is the iterated process of extending A with unit-resulting literals until no further literal is unit-resulting for any nogood in Δ

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Nogoods from logic programsNogoods from program completion

The completion of a logic program *P* can be defined as follows:

$$\{v_B \leftrightarrow a_1 \wedge \dots \wedge a_m \wedge \neg a_{m+1} \wedge \dots \wedge \neg a_n \mid B \in body(P), B = \{a_1, \dots, a_m, not \ a_{m+1}, \dots, not \ a_n\}\}$$
$$\cup \quad \{a \leftrightarrow v_{B_1} \vee \dots \vee v_{B_k} \mid a \in atom(P), body(a) = \{B_1, \dots, B_k\}\},$$
where  $body(a) = \{body(r) \mid r \in P, head(r) = a\}$ 

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•  $v_B \rightarrow a_1 \wedge \cdots \wedge a_m \wedge \neg a_{m+1} \wedge \cdots \wedge \neg a_n$ is equivalent to the conjunction of

 $\neg v_B \lor a_1, \ldots, \neg v_B \lor a_m, \neg v_B \lor \neg a_{m+1}, \ldots, \neg v_B \lor \neg a_n$ 

and induces the set of nogoods

 $\Delta(B) = \{ \{TB, Fa_1\}, \dots, \{TB, Fa_m\}, \{TB, Ta_{m+1}\}, \dots, \{TB, Ta_n\} \}$ 

• The (body-oriented) equivalence

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can be decomposed into two implications:



 $\delta(B) = \{FB, Ta_1, \ldots, Ta_m, Fa_{m+1}, \ldots, Fa_n\}$ 

• Analogously, the (atom-oriented) equivalence

 $a \leftrightarrow v_{B_1} \vee \cdots \vee v_{B_k}$ 

yields the nogoods

**1** 
$$\Delta(a) = \{ \{Fa, TB_1\}, \dots, \{Fa, TB_k\} \}$$
 and

$$2 \delta(a) = \{ Ta, FB_1, \ldots, FB_k \}$$

• For an atom *a* where  $body(a) = \{B_1, \ldots, B_k\}$ , we get

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• Example Given Atom x with  $body(x) = \{\{y\}, \{not \ z\}\}$ , we obtain

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 $\{Tx, F\{y\}, F\{not z\}\}$  $\{\{Fx, T\{y\}\}, \{Fx, T\{not z\}\}\}$ 

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 $\{F\{x, not y\}, Tx, Fy\} \\ \{\{T\{x, not y\}, Fx\}, \{T\{x, not y\}, Ty\}\} \}$ 

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$$\begin{array}{c|c} \dots \leftarrow x, not \ y \\ \vdots \\ \dots \leftarrow x, not \ y \end{array} & \{F\{x, not \ y\}, Tx, Fy\} \\ \{T\{x, not \ y\}, Fx\}, \{T\{x, not \ y\}, Ty\}\} \end{array}$$

For nogood  $\delta(\{x, not y\}) = \{F\{x, not y\}, Tx, Fy\}$ , the signed literal

- $T{x, not y}$  is unit-resulting wrt assignment (Tx, Fy) and
- Ty is unit-resulting wrt assignment ( $F{x, not y}, Tx$ )

Characterization of stable models for tight logic programs, ie. free of positive recursion

Let P be a logic program and

$$\Delta_P = \{\delta(a) \mid a \in atom(P)\} \cup \{\delta \in \Delta(a) \mid a \in atom(P)\} \\ \cup \{\delta(B) \mid B \in body(P)\} \cup \{\delta \in \Delta(B) \mid B \in body(P)\}$$

Characterization of stable models for tight logic programs, ie. free of positive recursion

Let P be a logic program and

$$\Delta_P = \{\delta(a) \mid a \in atom(P)\} \cup \{\delta \in \Delta(a) \mid a \in atom(P)\} \\ \cup \{\delta(B) \mid B \in body(P)\} \cup \{\delta \in \Delta(B) \mid B \in body(P)\}$$

#### Theorem

Let *P* be a tight logic program. Then,  $X \subseteq atom(P)$  is a stable model of *P* iff  $X = A^T \cap atom(P)$  for a (unique) solution *A* for  $\Delta_P$ 

### Summary

- Partial assignments
- Unfounded sets
- Unit resulting literals
- Unit propagation
- Nogoods via program completion
- Characterization of stable models of tight programs in terms of nogoods.

#### References

Martin Gebser, Benjamin Kaufmann Roland Kaminski, and Torsten Schaub. Answer Set Solving in Practice. Synthesis Lectures on Artificial Intelligence and Machine Learning. Morgan and Claypool Publishers, 2012. doi=10.2200/S00457ED1V01Y201211AIM019.

• See also: http://potassco.sourceforge.net