# DEDUCTION SYSTEMS 

## Lecture 5 ASP Solving 1 *silides adapled fiom Torsten <br> Schaub [Gebser et al.(2012)]

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Dresden, 18th June 2015


## Conflict-driven ASP Solving: Overview



## Outline

2) Preliminaries

3 Boolean constraints

4 Nogoods from logic programs

## Motivation of Conflict-driven ASP Solving

- Goal Approach to computing stable models of logic programs, based on concepts from
- Constraint Processing (CP) and
- Satisfiability Testing (SAT)
- Idea View inferences in ASP as unit propagation on nogoods
- Benefits:
- A uniform constraint-based framework for different kinds of inferences in ASP
- Advanced techniques from the areas of CP and SAT
- Highly competitive implementation


## Outline

(1) Motivation
(2) Preliminaries
3) Boolean constraints

4 Nogoods from logic programs

## Outline

- Unfounded Sets

3 Boolean constraints

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- Nogoods from program completion


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- Properties:
- $\langle T, F\rangle$ is conflicting if $T \cap F \neq \emptyset$
- $\langle T, F\rangle$ is total if $T \cup F=\mathcal{A}$ and $T \cap F=\emptyset$
- Definition: For $\left\langle T_{1}, F_{1}\right\rangle$ and $\left\langle T_{2}, F_{2}\right\rangle$, define
$-\left\langle T_{1}, F_{1}\right\rangle \sqsubseteq\left\langle T_{2}, F_{2}\right\rangle$ iff $T_{1} \subseteq T_{2}$ and $F_{1} \subseteq F_{2}$
$-\left\langle T_{1}, F_{1}\right\rangle \sqcup\left\langle T_{2}, F_{2}\right\rangle=\left\langle T_{1} \cup T_{2}, F_{1} \cup F_{2}\right\rangle$


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## (2) Preliminaries

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Let $P$ be a normal logic program, and let $\langle T, F\rangle$ be a partial interpretation

- A set $U \subseteq \operatorname{atom}(P)$ is an unfounded set of $P$ wrt $\langle T, F\rangle$ Intuitively, $\langle T, F\rangle$ is what we already know about $P$


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- Rules satisfying Condition 1 are not usable for further derivations
- Condition 2 is the unfounded set condition treating cyclic derivations: All rules still being usable to derive an atom in $U$ require an(other) atom in $U$ to be true


## Example

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P=\left\{\begin{array}{lll}
a & \leftarrow & b \\
b & \leftarrow & a
\end{array}\right\}
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- Analogously for $\{b\}$


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- $\{a, b\}$ is an unfounded set of $P$ wrt $\langle\emptyset, \emptyset\rangle$
- $\{a, b\}$ is an unfounded set of $P$ wrt any partial interpretation


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## Assignments

- An assignment $A$ over $\operatorname{dom}(A)=\operatorname{atom}(P) \cup \operatorname{body}(P)$ is a sequence

$$
\left(\sigma_{1}, \ldots, \sigma_{n}\right)
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of signed literals $\sigma_{i}$ of form $\boldsymbol{T v}$ or $\boldsymbol{F v}$ for $v \in \operatorname{dom}(A)$ and $1 \leq i \leq n$

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- We sometimes identify an assignment with the set of its literals
- Given this, we access true and false propositions in $A$ via

$$
A^{\boldsymbol{T}}=\{v \in \operatorname{dom}(A) \mid \boldsymbol{T} v \in A\} \text { and } A^{\boldsymbol{F}}=\{v \in \operatorname{dom}(A) \mid \boldsymbol{F} v \in A\}
$$

## Nogoods, solutions, and unit propagation

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(1) $\delta \backslash A=\{\sigma\}$ and
(2) $\bar{\sigma} \notin A$
- For a set $\Delta$ of nogoods and an assignment $A$, unit propagation is the iterated process of extending $A$ with unit-resulting literals until no further literal is unit-resulting for any nogood in $\Delta$


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- Nogoods from program completion


## Nogoods from logic programs via program completion

The completion of a logic program $P$ can be defined as follows:

$$
\begin{aligned}
\left\{v_{B} \leftrightarrow\right. & a_{1} \wedge \cdots \wedge a_{m} \wedge \neg a_{m+1} \wedge \cdots \wedge \neg a_{n} \mid \\
& \left.B \in \operatorname{body}(P), B=\left\{a_{1}, \ldots, a_{m}, \operatorname{not} a_{m+1}, \ldots, \operatorname{not} a_{n}\right\}\right\} \\
\cup \quad\{a \leftrightarrow & \left.v_{B_{1}} \vee \cdots \vee v_{B_{k}} \mid a \in \operatorname{atom}(P), \operatorname{body}(a)=\left\{B_{1}, \ldots, B_{k}\right\}\right\},
\end{aligned}
$$

where $\operatorname{body}(a)=\{\operatorname{body}(r) \mid r \in P, \operatorname{head}(r)=a\}$

## Nogoods from logic programs via program completion

- The (body-oriented) equivalence

$$
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can be decomposed into two implications:
(1) $v_{B} \rightarrow a_{1} \wedge \cdots \wedge a_{m} \wedge \neg a_{m+1} \wedge \cdots \wedge \neg a_{n}$
is equivalent to the conjunction of

$$
\neg v_{B} \vee a_{1}, \ldots, \neg v_{B} \vee a_{m}, \neg v_{B} \vee \neg a_{m+1}, \ldots, \neg v_{B} \vee \neg a_{n}
$$

and induces the set of nogoods

$$
\Delta(B)=\left\{\left\{\boldsymbol{T} B, \boldsymbol{F} a_{1}\right\}, \ldots,\left\{\boldsymbol{T} B, \boldsymbol{F} a_{m}\right\},\left\{\boldsymbol{T} B, \boldsymbol{T} a_{m+1}\right\}, \ldots,\left\{\boldsymbol{T} B, \boldsymbol{T} a_{n}\right\}\right\}
$$

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v_{B} \leftrightarrow a_{1} \wedge \cdots \wedge a_{m} \wedge \neg a_{m+1} \wedge \cdots \wedge \neg a_{n}
$$

can be decomposed into two implications:
(2) $a_{1} \wedge \cdots \wedge a_{m} \wedge \neg a_{m+1} \wedge \cdots \wedge \neg a_{n} \rightarrow v_{B}$
gives rise to the nogood

$$
\delta(B)=\left\{\boldsymbol{F} B, \boldsymbol{T} a_{1}, \ldots, \boldsymbol{T} a_{m}, \boldsymbol{F} a_{m+1}, \ldots, \boldsymbol{F} a_{n}\right\}
$$

## Nogoods from logic programs via program completion

- Analogously, the (atom-oriented) equivalence

$$
a \leftrightarrow v_{B_{1}} \vee \cdots \vee v_{B_{k}}
$$

yields the nogoods
(1) $\Delta(a)=\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}$ and
(2) $\delta(a)=\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\}$

## Nogoods from logic programs atom-oriented nogoods

- For an atom $a$ where $\operatorname{body}(a)=\left\{B_{1}, \ldots, B_{k}\right\}$, we get

$$
\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\} \quad \text { and } \quad\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}
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- Example Given Atom $x$ with $\operatorname{body}(x)=\{\{y\}$, $\{$ not $z\}\}$, we obtain

| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
| $x$ | $\leftarrow$ | not $z$ |

$\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$
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- For an atom $a$ where $\operatorname{body}(a)=\left\{B_{1}, \ldots, B_{k}\right\}$, we get

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\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\} \quad \text { and } \quad\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}
$$

- Example Given Atom $x$ with $\operatorname{body}(x)=\{\{y\}$, $\{$ not $z\}\}$, we obtain

| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
| $x$ | $\leftarrow$ | not $z$ |

$$
\begin{aligned}
& \{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{\text { not } z\}\} \\
& \{\{\boldsymbol{F} x, \boldsymbol{T}\{y\}\},\{\boldsymbol{F} x, \boldsymbol{T}\{\text { not } z\}\}\}
\end{aligned}
$$

For nogood $\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$, the signed literal

- $\boldsymbol{F} x$ is unit-resulting wrt assignment $(\boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\})$ and


## Nogoods from logic programs atom-oriented nogoods

- For an atom $a$ where $\operatorname{body}(a)=\left\{B_{1}, \ldots, B_{k}\right\}$, we get

$$
\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\} \quad \text { and } \quad\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}
$$

- Example Given Atom $x$ with $\operatorname{body}(x)=\{\{y\}$, $\{$ not $z\}\}$, we obtain

| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
| $x$ | $\leftarrow$ | not $z$ |

$$
\begin{aligned}
& \{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{\text { not } z\}\} \\
& \{\{\boldsymbol{F} x, \boldsymbol{T}\{y\}\},\{\boldsymbol{F} x, \boldsymbol{T}\{\text { not } z\}\}\}
\end{aligned}
$$

For nogood $\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$, the signed literal

- $\boldsymbol{F} x$ is unit-resulting wrt assignment $(\boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\})$ and


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$$
\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\} \quad \text { and } \quad\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}
$$

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| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
| $x$ | $\leftarrow$ | not $z$ |

$$
\begin{aligned}
& \{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{\text { not } z\}\} \\
& \{\{\boldsymbol{F} x, \boldsymbol{T}\{y\}\},\{\boldsymbol{F} x, \boldsymbol{T}\{\text { not } z\}\}\}
\end{aligned}
$$

For nogood $\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$, the signed literal

- $\boldsymbol{F} x$ is unit-resulting wrt assignment $(\boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\})$ and


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- For an atom $a$ where $\operatorname{body}(a)=\left\{B_{1}, \ldots, B_{k}\right\}$, we get

$$
\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\} \quad \text { and } \quad\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}
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| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
| $x$ | $\leftarrow$ | not $z$ |

$$
\begin{aligned}
& \{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{\text { not } z\}\} \\
& \{\{\boldsymbol{F} x, \boldsymbol{T}\{y\}\},\{\boldsymbol{F} x, \boldsymbol{T}\{\text { not } z\}\}\}
\end{aligned}
$$

For nogood $\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$, the signed literal

- $\boldsymbol{T}\{$ not $z\}$ is unit-resulting wrt assignment ( $\boldsymbol{T} x, \boldsymbol{F}\{y\}$ )


## Nogoods from logic programs atom-oriented nogoods

- For an atom $a$ where $\operatorname{body}(a)=\left\{B_{1}, \ldots, B_{k}\right\}$, we get

$$
\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\} \quad \text { and } \quad\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}
$$

- Example Given Atom $x$ with $\operatorname{body}(x)=\{\{y\}$, $\{$ not $z\}\}$, we obtain

| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
| $x$ | $\leftarrow$ | not $z$ |

$$
\begin{aligned}
& \{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{\text { not } z\}\} \\
& \{\{\boldsymbol{F} x, \boldsymbol{T}\{y\}\},\{\boldsymbol{F} x, \boldsymbol{T}\{\text { not } z\}\}\}
\end{aligned}
$$

For nogood $\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$, the signed literal

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$$

- Example Given Atom $x$ with $\operatorname{body}(x)=\{\{y\}$, $\{$ not $z\}\}$, we obtain

| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
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$$
\begin{aligned}
& \{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{\text { not } z\}\} \\
& \{\{\boldsymbol{F} x, \boldsymbol{T}\{y\}\},\{\boldsymbol{F} x, \boldsymbol{T}\{\text { not } z\}\}\}
\end{aligned}
$$

For nogood $\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$, the signed literal

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\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\} \quad \text { and } \quad\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}
$$

- Example Given Atom $x$ with $\operatorname{body}(x)=\{\{y\}$, $\{$ not $z\}\}$, we obtain

| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
| $x$ | $\leftarrow$ | not $z$ |

$$
\begin{aligned}
& \{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{\text { not } z\}\} \\
& \{\{\boldsymbol{F} x, \boldsymbol{T}\{y\}\},\{\boldsymbol{F} x, \boldsymbol{T}\{\text { not } z\}\}\}
\end{aligned}
$$

For nogood $\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$, the signed literal

- $\boldsymbol{T}\{$ not $z\}$ is unit-resulting wrt assignment $(\boldsymbol{T} x, \boldsymbol{F}\{y\})$


## Nogoods from logic programs atom-oriented nogoods

- For an atom $a$ where $\operatorname{body}(a)=\left\{B_{1}, \ldots, B_{k}\right\}$, we get

$$
\left\{\boldsymbol{T} a, \boldsymbol{F} B_{1}, \ldots, \boldsymbol{F} B_{k}\right\} \quad \text { and } \quad\left\{\left\{\boldsymbol{F} a, \boldsymbol{T} B_{1}\right\}, \ldots,\left\{\boldsymbol{F} a, \boldsymbol{T} B_{k}\right\}\right\}
$$

- Example Given Atom $x$ with $\operatorname{body}(x)=\{\{y\}$, $\{$ not $z\}\}$, we obtain

| $x$ | $\leftarrow$ | $y$ |
| :--- | :--- | :--- |
| $x$ | $\leftarrow$ | not $z$ |

$$
\begin{aligned}
& \{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{\text { not } z\}\} \\
& \{\{\boldsymbol{F} x, \boldsymbol{T}\{y\}\},\{\boldsymbol{F} x, \boldsymbol{T}\{\text { not } z\}\}\}
\end{aligned}
$$

For nogood $\{\boldsymbol{T} x, \boldsymbol{F}\{y\}, \boldsymbol{F}\{$ not $z\}\}$, the signed literal

- $\boldsymbol{T}\{$ not $z\}$ is unit-resulting wrt assignment $(\boldsymbol{T} x, \boldsymbol{F}\{y\})$


## Nogoods from logic programs body-oriented nogoods

- For a body $B=\left\{a_{1}, \ldots, a_{m}\right.$, not $a_{m+1}, \ldots$, not $\left.a_{n}\right\}$, we get

$$
\begin{aligned}
& \left\{\boldsymbol{F} B, \boldsymbol{T} a_{1}, \ldots, \boldsymbol{T} a_{m}, \boldsymbol{F} a_{m+1}, \ldots, \boldsymbol{F} a_{n}\right\} \\
& \left\{\left\{\boldsymbol{T} B, \boldsymbol{F} a_{1}\right\}, \ldots,\left\{\boldsymbol{T} B, \boldsymbol{F} a_{m}\right\},\left\{\boldsymbol{T} B, \boldsymbol{T} a_{m+1}\right\}, \ldots,\left\{\boldsymbol{T} B, \boldsymbol{T} a_{n}\right\}\right\}
\end{aligned}
$$

## Nogoods from logic programs body-oriented nogoods

- For a body $B=\left\{a_{1}, \ldots, a_{m}\right.$, not $a_{m+1}, \ldots$, not $\left.a_{n}\right\}$, we get

$$
\begin{aligned}
& \left\{\boldsymbol{F} B, \boldsymbol{T} a_{1}, \ldots, \boldsymbol{T} a_{m}, \boldsymbol{F} a_{m+1}, \ldots, \boldsymbol{F} a_{n}\right\} \\
& \left\{\left\{\boldsymbol{T} B, \boldsymbol{F} a_{1}\right\}, \ldots,\left\{\boldsymbol{T} B, \boldsymbol{F} a_{m}\right\},\left\{\boldsymbol{T} B, \boldsymbol{T} a_{m+1}\right\}, \ldots,\left\{\boldsymbol{T} B, \boldsymbol{T} a_{n}\right\}\right\}
\end{aligned}
$$

- Example Given Body $\{x$, not $y\}$, we obtain

$$
\begin{gathered}
\ldots \leftarrow x, \operatorname{not} y \\
\vdots \\
\ldots \leftarrow x, \operatorname{not} y
\end{gathered}
$$

$$
\begin{aligned}
& \{\boldsymbol{F}\{x, \text { not } y\}, \boldsymbol{T} x, \boldsymbol{F} y\} \\
& \{\{\boldsymbol{T}\{x, \text { not } y\}, \boldsymbol{F} x\},\{\boldsymbol{T}\{x, \text { not } y\}, \boldsymbol{T} y\}\}
\end{aligned}
$$

## Nogoods from logic programs body-oriented nogoods

- For a body $B=\left\{a_{1}, \ldots, a_{m}\right.$, not $a_{m+1}, \ldots$, not $\left.a_{n}\right\}$, we get

$$
\begin{aligned}
& \left\{\boldsymbol{F} B, \boldsymbol{T} a_{1}, \ldots, \boldsymbol{T} a_{m}, \boldsymbol{F} a_{m+1}, \ldots, \boldsymbol{F} a_{n}\right\} \\
& \left\{\left\{\boldsymbol{T} B, \boldsymbol{F} a_{1}\right\}, \ldots,\left\{\boldsymbol{T} B, \boldsymbol{F} a_{m}\right\},\left\{\boldsymbol{T} B, \boldsymbol{T} a_{m+1}\right\}, \ldots,\left\{\boldsymbol{T} B, \boldsymbol{T} a_{n}\right\}\right\}
\end{aligned}
$$

- Example Given Body $\{x$, not $y\}$, we obtain


$$
\begin{aligned}
& \{\boldsymbol{F}\{x, \text { not } y\}, \boldsymbol{T} x, \boldsymbol{F} y\} \\
& \{\{\boldsymbol{T}\{x, \text { not } y\}, \boldsymbol{F} x\},\{\boldsymbol{T}\{x, \text { not } y\}, \boldsymbol{T} y\}\}
\end{aligned}
$$

For nogood $\delta(\{x$, not $y\})=\{\boldsymbol{F}\{x$, not $y\}, \boldsymbol{T} x, \boldsymbol{F} y\}$, the signed literal

- $\boldsymbol{T}\{x$, not $y\}$ is unit-resulting wrt assignment ( $\boldsymbol{T} x, \boldsymbol{F} y$ ) and
- $\boldsymbol{T} y$ is unit-resulting wrt assignment $(\boldsymbol{F}\{x$, not $y\}, \boldsymbol{T} x)$


## Characterization of stable models

for tight logic programs, ie. free of positive recursion

Let $P$ be a logic program and

$$
\begin{aligned}
\Delta_{P} & =\{\delta(a) \mid a \in \operatorname{atom}(P)\} \cup\{\delta \in \Delta(a) \mid a \in \operatorname{atom}(P)\} \\
& \cup\{\delta(B) \mid B \in \operatorname{body}(P)\} \cup\{\delta \in \Delta(B) \mid B \in \operatorname{body}(P)\}
\end{aligned}
$$

## Characterization of stable models

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Let $P$ be a logic program and

$$
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& \cup\{\delta(B) \mid B \in \operatorname{body}(P)\} \cup\{\delta \in \Delta(B) \mid B \in \operatorname{body}(P)\}
\end{aligned}
$$

## Theorem

Let $P$ be a tight logic program. Then, $X \subseteq \operatorname{atom}(P)$ is a stable model of $P$ iff $X=A^{T} \cap \operatorname{atom}(P)$ for a (unique) solution $A$ for $\Delta_{P}$

## Summary

- Partial assignments
- Unfounded sets
- Unit resulting literals
- Unit propagation
- Nogoods via program completion
- Characterization of stable models of tight programs in terms of nogoods.


## References

Torin Martin Gebser, Benjamin Kaufmann Roland Kaminski, and Torsten Schaub.
Answer Set Solving in Practice.
Synthesis Lectures on Artificial Intelligence and Machine Learning. Morgan and Claypool Publishers, 2012. doi=10.2200/S00457ED1V01Y201211AIM019.

- See also: http://potassco.sourceforge.net

