

# DATABASE THEORY

## Lecture 8: Tree-Like Conjunctive Queries (2)

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Knowledge-Based Systems

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# Review: Treewidth

Graphs of bounded treewidth as a generalisation of (undirected) trees:

- Trees have treewidth 1
- Graphs of higher treewidth resemble trees with “thicker branches”
- It is (in theory) not hard to check if a graph has treewidth  $\leq k$  for some  $k$
- It is (in theory) not hard to answer BCQs whose primal graph has a bounded treewidth

Practically feasible only for lower treewidths

However, bounded treewidth does not generalise the notion of hypergraph acyclicity (acyclic families of hypergraphs may have unbounded treewidth)

Is there a better notion of tree-likeness for hypergraphs?

# Query Width

Idea of Chekuri and Rajamaran [1997]:

- Create tree structure similar to tree decomposition
- But consider bags of query atoms instead of bags of variables
- Two connectedness conditions:
  - (1) Bags that refer to a certain variable must be connected
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Query width: least number of atoms needed in bags of a query decomposition

**Theorem 8.1:** Given a query decomposition for a BCQ, the query answering problem can be decided in time polynomial in the query width.

# Problems with Query Width

**Theorem 8.2 (Gottlob et al. 1999):** Deciding if a query has query width at most  $k$  is NP-complete.

In particular, it is also hard to find a query decomposition

↪ Query answering complexity drops from NP to P . . .  
...but we need to solve another NP-hard problem first!

# Generalised Hypertree Width

Gottlob, Leone, and Scarcello had another idea on defining tree-like hypergraphs:

## Intuition:

- Combine key ideas of tree decomposition and query decomposition
- Start by looking at a tree decomposition
- But define the width based on query atoms:  
How many atoms do we need to cover all variables in a bag?

~> Generalised hypertree width

~> A technical condition is needed to get a simpler-to-check notion

# Hypertree Width

**Definition 8.3:** Consider a hypergraph  $G = \langle V, E \rangle$ . A **hypertree decomposition** of  $G$  is a tree structure  $T$  where each node  $n$  of  $T$  is associated with a bag of variables  $B_n \subseteq V$  and with a set of edges  $G_n \subseteq E$ , such that:

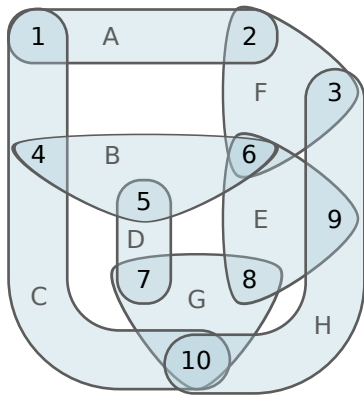
- $T$  with  $B_n$  yields a tree decomposition of the primal graph of  $G$ .
- For each node  $n$  of  $T$ :
  - (1) the vertices used in the edges  $G_n$  are a superset of  $B_n$ ,
  - (2) if a vertex  $v$  occurs in an edge of  $G_n$  and this vertex also occurs in  $B_m$  for some node  $m$  below  $n$  in  $T$ , then  $v \in B_n$ .

The **width** to  $T$  is the largest number of edges in a set  $G_n$ .

The **hypertree width** of  $G$ ,  $\text{hw}(G)$ , is the least width of its hypertree decompositions.

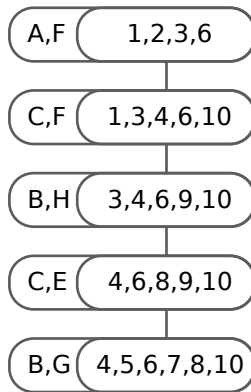
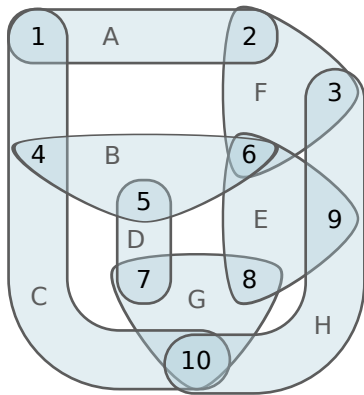
((2) is the “special condition”: without it we get the **generalised hypertree width**)

# Hypertree Width: Example

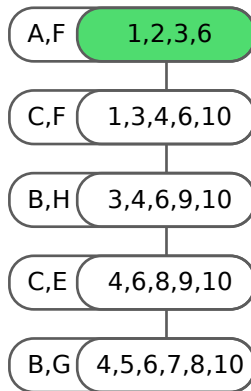
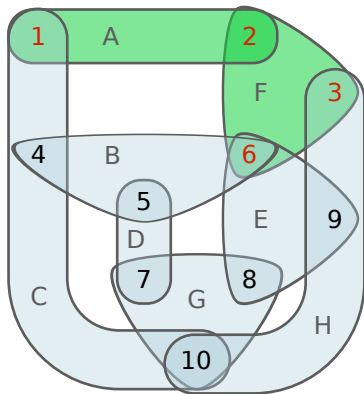




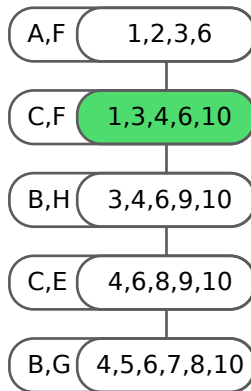
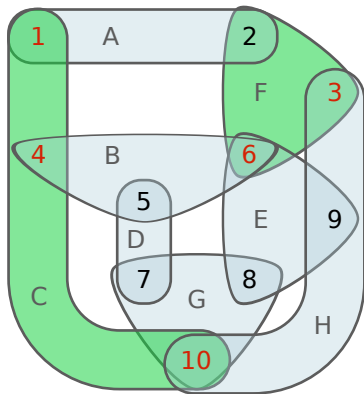
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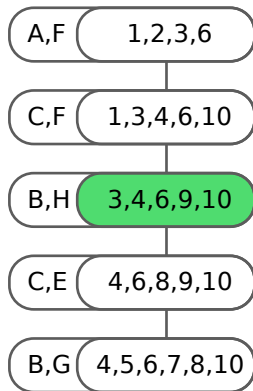
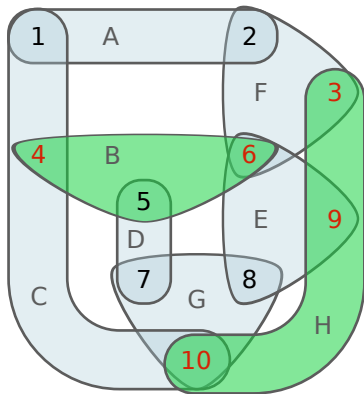
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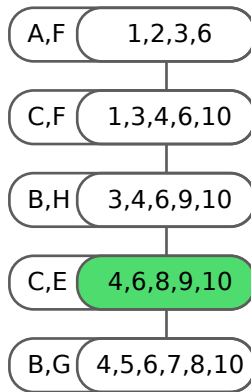
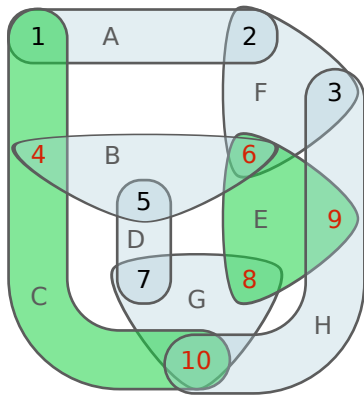
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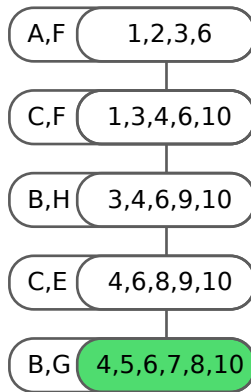
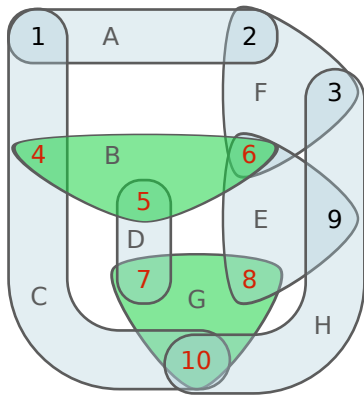
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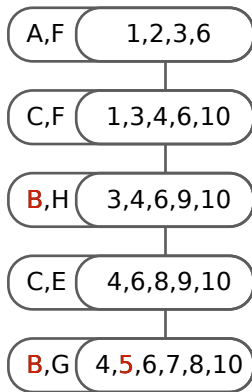
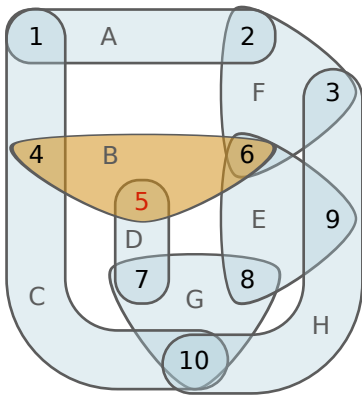
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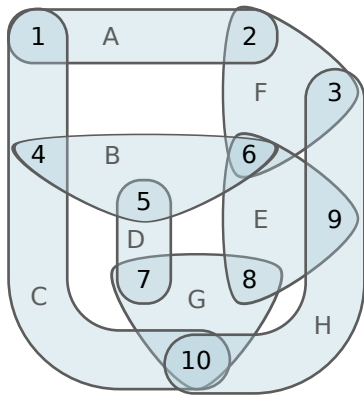


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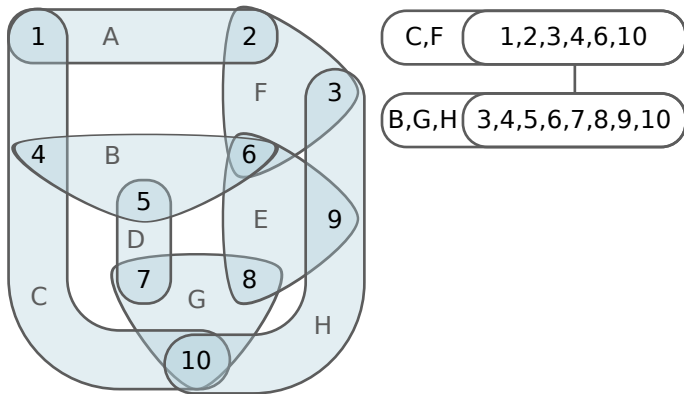
Special condition violated  $\leadsto$  no hypertree decomposition  
 $\leadsto$  But generalised hypertree decomposition of width 2

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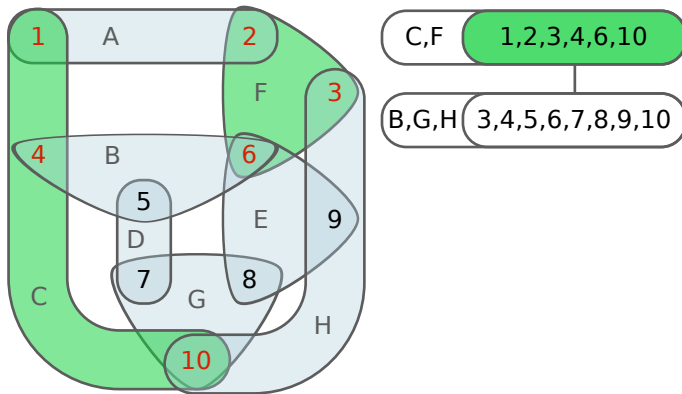




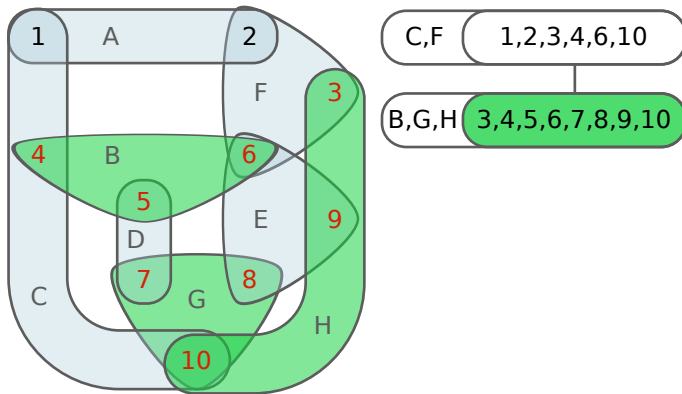
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Special condition satisfied  $\leadsto$  hypertree decomposition of width 3

# Hypertree Width: Observations

**Observation 8.4:** If  $\langle T, (B_n), (G_n) \rangle$  is a hypertree decomposition for a hypergraph  $\langle V, E \rangle$ , then the union of all sets  $G_n$  might be a proper subset of  $E$ .

**Proof:** Indeed, we only require that every bag  $B_n$  is “covered” by the edges in  $G_n$ , not that every edge in  $E$  is actually used for this purpose. □

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**Proof:** Since  $T, (B_n)$  is a tree decomposition of the primal graph, and every edge  $e \in E$  gives rise to a  $|e|$ -clique in this graph, the variables of  $e$  must occur together in one bag of the tree decomposition. □

# Complete Hypertree Decompositions

We can make sure that all atoms are in fact used in some set  $G_n$  of the decomposition:

**Theorem 8.6:** If  $\langle T, (B_n), (G_n) \rangle$  is a (generalised) hypertree decomposition for a hypergraph  $\langle V, E \rangle$ , then there is a (generalised) hypertree decomposition  $\langle T', (B'_n), (G'_n) \rangle$  of size  $O(|T| + |E|)$  such that, for all  $e \in E$ , there is a node  $n$  in  $T'$  with  $e \in G'_n$ .

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**Proof:** For every edge  $e \in E$  that does not appear in  $(G_n)$  yet:

- extend  $T$  with a new node  $m$  that is a child of an existing node  $n$  with  $e \subseteq G_n$  (this must exist as just observed)
- define  $B_m = e$  and  $G_m = \{e\}$

This establishes the claim for  $e$  and preserves all conditions in the definition of (generalised) hypertree decomposition. □

Such hypertree decompositions are called **complete**.



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- A tree structure  $T$
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This easily corresponds to a hypertree decomposition (using the same tree structure, singleton edge sets  $G_n = \{e\}$  and vertex bags  $B_n = e$  if  $n$  is associated with  $e$ )

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We modify the decomposition so that, for every edge  $e \in E$ , there is exactly one node  $n_e$  in  $T$  such that  $G_{n_e} = \{e\}$  and  $B_{n_e} = e$ :

- Choose an arbitrary total order  $<$  on the nodes of  $T$
- For each  $e \in E$ :
  - Find the  $<$ -least node  $n_e$  of  $T$  with  $G_{n_e} = \{e\}$  and  $B_{n_e} = e$   
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The modified hypertree decomposition corresponds to a join tree:

- each node is associated with a single edge
- no edge is associated with more than one node
- the vertices satisfy the connectedness condition for join trees  
(since  $T$  is a tree decomposition of the primal graph)

Hence the hypergraph has a join tree and is therefore acyclic. □



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- For each node  $n$  and atom  $r(\vec{x}) \in G_n$
- create a new relation  $r'$  and let  $\vec{y}$  be a list of all variables in  $\vec{x} \cap B_n$
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BCQ  $q'$ , hypertree decomposition  $\langle T', (B_n), (G'_n) \rangle$ , and database instance  $\mathcal{I}'$  are of size polynomial in the input.

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- so  $r(\vec{x})$  is an atom of  $q'$  as well



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The overall claim now follows by applying Yannakakis' Algorithm to answer the query. □

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generalised hypertree width  $\leq$  hypertree width  $\leq$  query width  
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**Theorem 8.9:** For a BCQ of (generalised) hypertree width  $k$ , query answering can be decided in polynomial time, and is complete for LOGCFL.

... but the degree of the polynomial time bound is greater than  $k$

# Hypertree Width via Games

There is also a game characterisation of (generalised) hypertree width.

## The Marshals-and-Robber Game

- The game is played on a hypergraph
- There are  $k$  marshals, each controlling one hyperedge, and one robber located at a vertex
- Otherwise similar to cops-and-robber game
- Special condition: Marshals must shrink the space that is left for the robber in every turn!

Hypertree width  $\leq k$  if and only if  $k$  marshals have a winning strategy

$\leadsto$  hypergraph is acyclic iff 1 marshal has a winning strategy

# Hypertree Width via Logic

There is also a logical characterisation of hypertree width.

## Loosely $k$ -Guarded Logic

- Fragment of FO with  $\exists$  and  $\wedge$
- Special form for all  $\exists$  subexpressions:

$$\exists x_1, \dots, x_n. (G_1 \wedge \dots \wedge G_k \wedge \varphi)$$

where  $G_i$  are atoms (“guards”) and every variable that is free in  $\varphi$  occurs in one such atom  $G_i$ .

A query has hypertree width  $\leq k$  if and only if it can be expressed as a loosely  $k$ -guarded formula

$\rightsquigarrow$  tree queries correspond to loosely 1-guarded formulae

(“loosely 1-guarded” logic is better known as guarded logic and widely studied)

# Summary and Outlook

Besides tree queries, there are other important classes of CQs that can be answered in polynomial time:

- Bounded treewidth queries
- Bounded hypertree width queries

General idea: decompose the query in a tree structure

Other possible characterisations via games and logic

## Open questions:

- What else is there besides query answering?  $\rightsquigarrow$  optimisation
- Measure expressivity rather than just complexity