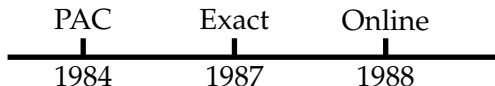


Notes on Computational Learning Theory and the problem of learning CNFs

March 5, 2018

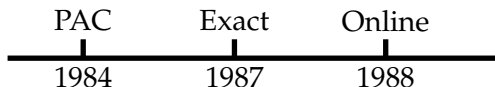
INTRODUCTION

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- ▶ Question posed in 1984: What is the complexity of learning Boolean Functions?
- ▶ Turing Award 2010: Leslie Valiant

PAC LEARNING: PROBLEM SETTING

- ▶ The learner observes a sequence of labeled examples (training).
- ▶ The learner must output a hypothesis estimating the target.
 - ▶ the hypothesis is evaluated by its performance on subsequent examples drawn according to a probability distribution.

PAC LEARNING: MOTIVATION

- ▶ Given some training data over the general data, can we guarantee something about the error?
- ▶ How large should be the training data to bound the error?
- ▶ We want to compute a hypothesis where with high probability it does not differ much from the target.



PAC LEARNING: PROBLEM SETTING

- ▶ Let X be a set of examples.
- ▶ A concept c is a subset of X .
- ▶ A concept class \mathcal{C} is a set of concepts.

PAC LEARNING: PROBLEM SETTING

- ▶ Let X be a set of examples.
- ▶ A concept c is a subset of X .
- ▶ A concept class \mathcal{C} is a set of concepts.
- ▶ Let H be a set of hypothesis concept representations (the hypothesis space) and $\mu_H : H \rightarrow \mathcal{C}_H$ a surjective function;
- ▶ Let L be a set of target concept representations and $\mu_L : L \rightarrow \mathcal{C}_L$ a surjective function;

PAC LEARNING: PROBLEM SETTING

- ▶ Training examples are generated by a fixed, unknown probability distribution \mathcal{D} over X (i.i.d).
 - ▶ $\mathcal{D} : X \rightarrow [0, 1]$ is a function with $\sum_{x \in X} \mathcal{D}(x) = 1$.
- ▶ Let $\mathcal{D} = \{(\text{red}, 0.2), (\text{blue}, 0.1), (\text{orange}, 0.3), (\text{green}, 0.2), (\text{yellow}, 0.2)\}$ be a probability distribution over X .
- ▶ The oracle labels the examples as positive or negative according to the target.
 - ▶ e.g., if the target concept representation is $\{ \text{RGB}(\text{red}), \text{RGB}(\text{blue}) \}$ then:
 - ▶  is a positive example;
 - ▶  is a negative example.

TRUE ERROR OF A HYPOTHESIS

- ▶ The *true error* (denoted $error_{\mathcal{D}}(h)$) of a hypothesis $h \in H$ w.r.t. a target concept representation $l \in L$ and a prob. distr. \mathcal{D} is the probability that h will misclassify an example drawn at random according to \mathcal{D} .

$$error_{\mathcal{D}}(h) = Pr_{x \sim \mathcal{D}}(x \in \mu_H(h) \oplus \mu_L(l))$$

TRUE ERROR OF A HYPOTHESIS

$$\text{error}_{\mathcal{D}}(h) = \Pr_{x \sim \mathcal{D}}(x \in \mu_H(h) \oplus \mu_L(l))$$

Example

- ▶ Let $\mathcal{D} = \{(\text{red}, 0.2), (\text{blue}, 0.1), (\text{orange}, 0.3), (\text{green}, 0.2), (\text{yellow}, 0.2)\}$ be a probability distribution over X .
- ▶ $h = \{\text{RGB}(\text{red}), \text{RGB}(\text{yellow})\}$
- ▶ $l = \{\text{RGB}(\text{red}), \text{RGB}(\text{blue})\}$
- ▶ Then, $\text{error}_{\mathcal{D}}(h) = 0.3$

TWO NOTIONS OF ERROR

- ▶ **Training error** of a hypothesis h w.r.t. a target concept representation l .
 - ▶ How often $x \in \mu_H(h) \oplus \mu_L(l)$ over training examples?
- ▶ **True error** of a hypothesis h w.r.t. a target concept representation l .
 - ▶ How often $x \in \mu_H(h) \oplus \mu_L(l)$ over future random examples?
- ▶ **Question:** Can we bound the true error of h given the training error of h ?

PAC LEARNING DEFINITION

A learning framework $F = (X, L, H, \mu_H, \mu_L)$ is *PAC learnable* in polynomial time if there is an algorithm A such that for any fixed but arbitrary probability distribution \mathcal{D} and any target $l \in L$:

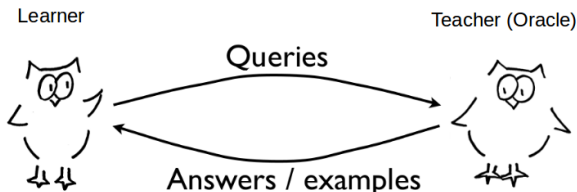
- ▶ A receives the parameters ϵ and δ as input;
- ▶ A can make calls to the oracle;
- ▶ the time used by A is bounded by a polynomial $p(|l|, |x|, \frac{1}{\epsilon}, \frac{1}{\delta})$, where $x \in X$ is the largest example returned by the oracle;
- ▶ A always halts and outputs a hypothesis $h \in H$ such that with probability at least $1 - \delta$, the probability of choosing $x \in \mu_H(h) \oplus \mu_L(l)$ is at most ϵ . That is, $Pr(Pr(x \in \mu_H(h) \oplus \mu_L(l)) \leq \epsilon) \geq 1 - \delta$.

PAC LEARNABILITY

- ▶ Question posed in 1984: What is the complexity of learning Boolean Formulas?
- ▶ The set of conjunctions of literals is PAC learnable in polynomial time from interpretations.
- ▶ 1987: Angluin proved that equivalence queries can be modified to achieve pac-learnability.
 - ▶ Exact Learning with membership and equivalence queries

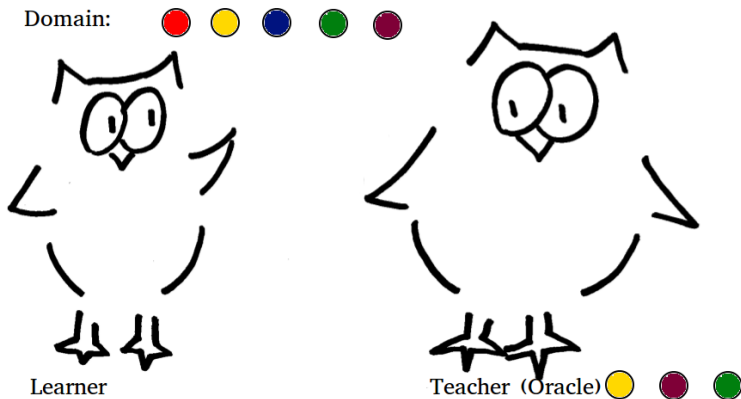
ANGLUIN'S EXACT LEARNING MODEL

- ▶ An algorithm exactly identifies a target set L_* if it always halts and outputs a hypothesis L_h such that $L_h = L_*$.
 - ▶ Membership query: $x \in L_*$? Yes/No
 - ▶ Equivalence query: $L_h = L_*$? Yes/No and $x \in L_h \oplus L_*$



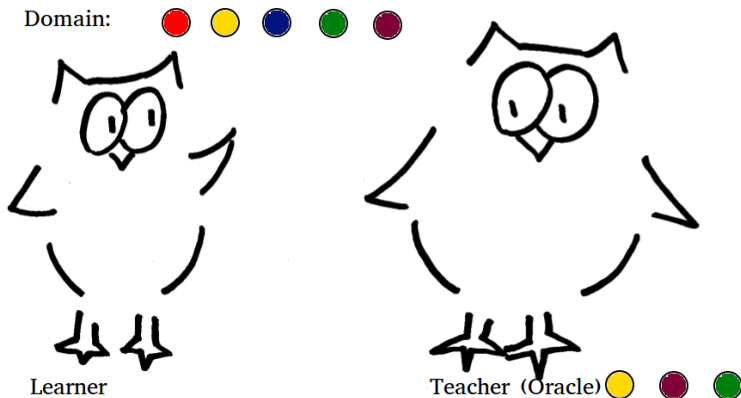
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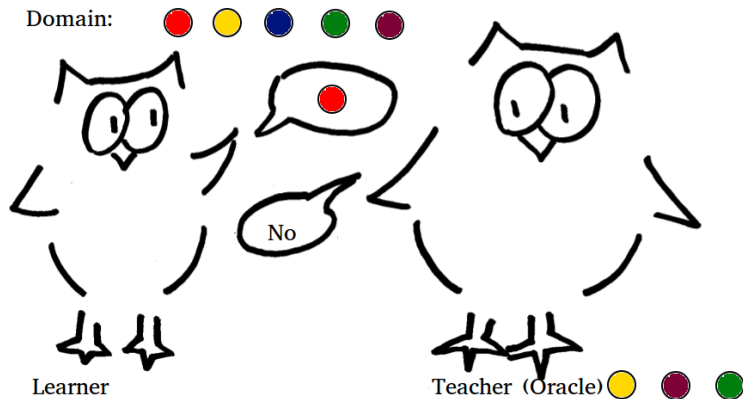
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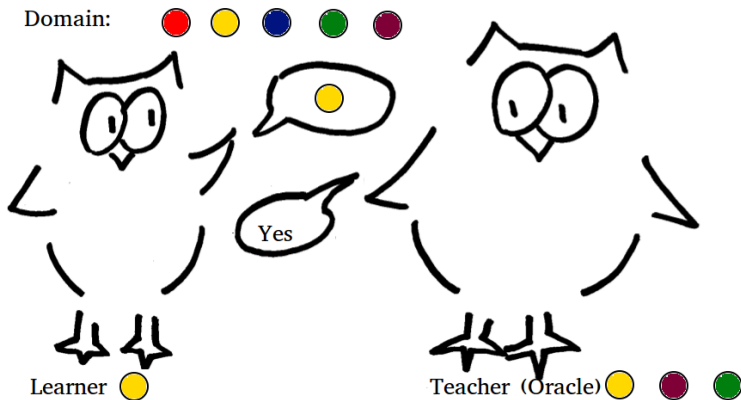
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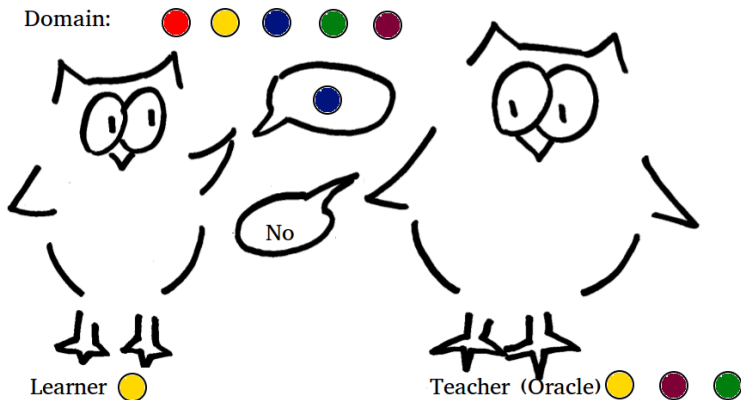
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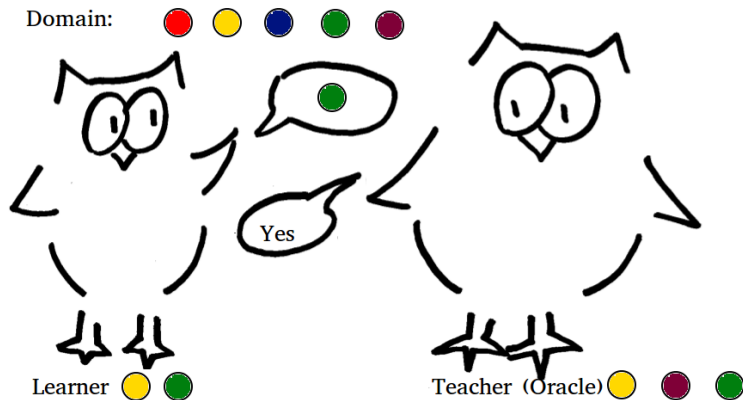
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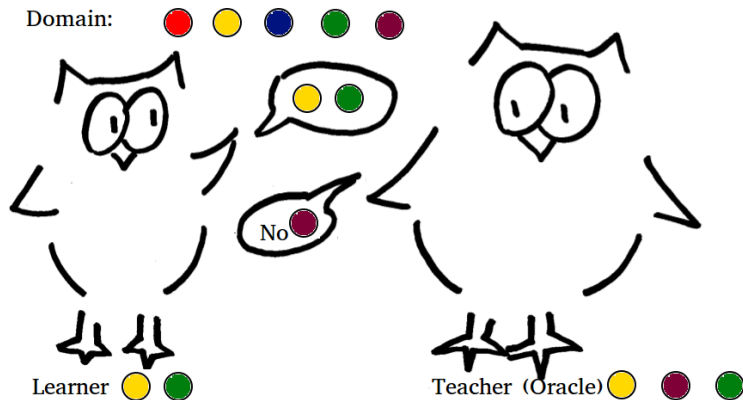
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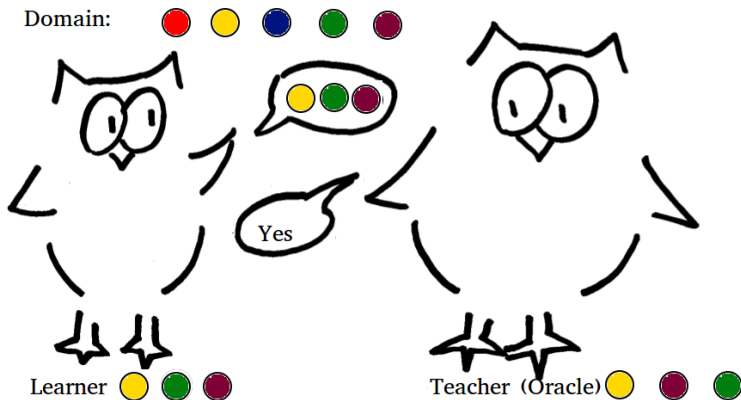
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EXACT LEARNING

- ▶ Learnability in polynomial time:
 - ▶ Polynomial in the size of the target and the largest counterexample seen so far.
- ▶ Unknown:
 - ▶ CNFs (2-Quasi-Horn)

HORN \prec MVDF \prec 2-QUASI-HORN

- ▶ An MVDF is a set of (MVD) clauses $X \rightarrow Y \vee Z$.
 - ▶ $V = X \cup Y \cup Z$ and X, Y, Z are mutually disjoint.

Example:

- ▶ Propositional Variables: $\{a, b, c, d, e, f\}$
- ▶ Target MVDF:
 - ▶ $\{ab \rightarrow cd \vee ef, \quad c \rightarrow aef \vee bc, \quad abcd \rightarrow ef\}$
 - ▶ $\{\mathbf{T} \rightarrow abcd \vee ef, \quad abcdef \rightarrow \mathbf{F}\}$
- ▶ Each mvd clause $X \rightarrow Y \vee Z$ must contain all variables.

HORN \prec MVDF \prec 2-QUASI-HORN

Let $V = \{a, b, c, d, e, f\}$

Horn can be expressed as MVDF:

- ▶ Prop. Horn: at most one positive literal
 - ▶ $\{\neg a \vee \neg b \vee c\} \equiv \{ab \rightarrow c\}$
- ▶ Translation:
 - ▶ $\{ab \rightarrow c\} \equiv \{ab \rightarrow c \vee def, \quad abdef \rightarrow c\}$
 - ▶ Any interpretation of the form $(a, b, \neg c, ?, ?, ?)$ falsifies at least one of the two MVD clauses above.

HORN \prec MVDF \prec 2-QUASI-HORN

Let $V = \{a, b, c, d, e, f\}$

MVDF is a fragment of 2-Quasi-Horn:

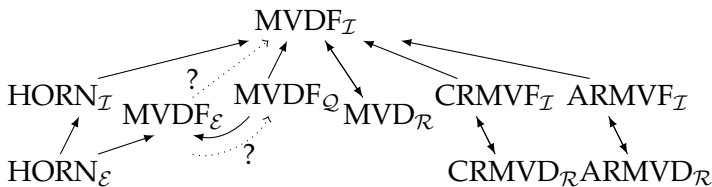
- ▶ 2-Quasi-Horn: at most two positive literals
 - ▶ $\{\neg a \vee b \vee c\} \equiv \{a \rightarrow b \vee c\}$
- ▶ Translation by distribution:
 - ▶ $\{ab \rightarrow cd \vee ef\} \equiv$
 $\{ab \rightarrow c \vee e, ab \rightarrow c \vee f, ab \rightarrow d \vee e, ab \rightarrow d \vee f\}$

OUR EXACT LEARNING PROBLEM

Horn \rightarrow MVDF \rightarrow 2-Quasi-Horn
polytime learnable ? as hard as CNF

- ▶ Horn-SAT: PTIME
- ▶ 2-Quasi-Horn-SAT: NP-Complete
- ▶ MVDF: PTIME - Exact Learning of Multivalued Dependency Formulas [Hermo and Ozaki, 2017]

OUR RESULTS



- ▶ $HORN_I$ (1992): Angluin, Frazier and Pitt
- ▶ $HORN_E$ (1993): Frazier and Pitt
- ▶ $CRMVF_I$ and $ARMVF_I$ (2011-2015): Lavin

CHALLENGES OF LEARNING MVDF

- ▶ The learning algorithm for propositional Horn refines countermodels by intersecting interpretations.
- ▶ In contrast to Horn, MVDF is not closed under intersection.
- ▶ Example: $\mathcal{T} = \{ab \rightarrow cd \vee ef\}$
 $\mathcal{I}_1 = (a, b, \neg c, \neg d, e, f)$ and $\mathcal{I}_2 = (a, b, c, d, \neg e, \neg f)$ satisfy \mathcal{T}
but $\mathcal{I}_1 \cap \mathcal{I}_2 = (a, b, \neg c, \neg d, \neg e, \neg f)$ does not satisfy \mathcal{T} .

FUTURE WORK

- ▶ PAC-learning MVDF: q -bounded distributions
- ▶ Exact Learning: $\sqsubseteq_{\Sigma}, \equiv_{\Sigma}$



Hermo, M. and Ozaki, A. (2017).

Exact learning of multivalued dependency formulas.

Theoretical Computer Science.