

COMPLEXITY THEORY

Lecture 3: Undecidability

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Undecidability is Real

A fundamental insight of computer science and mathematics is that there are undecidable languages:

Theorem 3.2: There are undecidable languages over every alphabet Σ .

Proof: See exercise.

Analoguously, there are uncomputable functions.

Decidability and Computability

Review: A language is

- recognisable (or semi-decidable, or recursively enumerable) if it is the language of all words recognised by some Turing machine
- decidable (or recursive) if it is the language of a Turing machine that allways halts, even on inputs that are not accepted
- undedicable if it is not decidable

Instead of acceptance of words, we can also consider other computations:

Definition 3.1: A TM \mathcal{M} computes a partial function $f_{\mathcal{M}}: \Sigma^* \to \Sigma^*$ as follows. We have $f_{\mathcal{M}}(w) = v$ for a word $w \in \Sigma^*$ if \mathcal{M} halts on input w with a tape that contains only the word $v \in \Sigma^*$ (followed by blanks). In this case, the function $f_{\mathcal{M}}$ is called computable.

Total, computable functions are called recursive.

Functions may therefore be computable or uncomputable.

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Unknown ≠ Undecidable

How do we find concrete undecidable problems?

It is not enough to not know how to solve a problem algorithmically!

Example 3.3: Let L_{π} be the set of all finite number sequences, that occur in the decimal representation of π . For example, $14159265 \in L_{\pi}$ and $41 \in L_{\pi}$.

We do not know if the language \mathbf{L}_{π} is decidable, but it might be (e.g., if every finite sequence of digits occured in π , which, however, is not known to be true today).

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Unknown ≠ Undecidable (2)

There are even case, where we are sure that a problem is decidable without knowning how to solve it.

Example 3.4 (after Uwe Schöning): Let L_{π^7} be the set of all number sequences of the form 7^n that occur in the decimal representation of π .

 $\mathbf{L}_{\pi 7}$ is decidable:

- Option 1: π contains sequences of arbitrary many 7. Then $\mathbf{L}_{\pi 7}$ is decided by a TM that accepts all words of the form $\mathbf{7}^n$.
- Option 2: π contains sequences of 7s only up to a certain maximal length ℓ . Then \mathbf{L}_{π^7} is decided by a TM that accepts all words of the form $\mathbf{7}^n$ with $n < \ell$.

In each possible case, we have a practical algorithm – we just don't know which one is correct.

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Busy Beaver

A small variation of the step counter function leads to the Busy-Beaver Problem:



Tibor Radó, BB inventor

Definition 3.6: The Busy-Beaver function $\Sigma: \mathbb{N} \to \mathbb{N}$ is a total function, where $\Sigma(n)$ is the maximal number of \mathbf{x} that a DTM with at most n states and tape alphabet $\Gamma = \{\mathbf{x}, \square\}$ can write when starting on the empty tape an dbefore it eventually halts.

Note: The exact value of $\Sigma(n)$ depends on details of the TM definition. Most works in this area assume a two-sided infinite tape that can be extended to the left and to the right if necessary.

A First Undecidable Problem (1)

Question: If a TM halts, how long may this take in the worst case?

Answer: Arbitrarily long, since:

- (a) the input might be arbitrarily long
- (b) the TM can be arbitrarily large

Question: If a TM with *n* States and a two-element tape alphabet $\Gamma = \{\mathbf{x}, \square\}$ halts on the empty input tape, how long may this take in the worst case?

Answer: That depends on $n \dots$

Definition 3.5: We define S(n) as the largest number of steps that any DTM with n states and tape alphabet $\Gamma = \{\mathbf{x}, \Box\}$ executes on the empty tape, before it eventually halts.

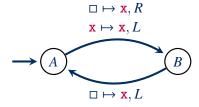
Observation: S is well defined.

- The number of TMs with at most n states is finite
- Among the relevant *n*-state TMs there must be a largest number of steps before halting (TMs that do not halt are ignored)

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Example

The Busy-Beaver number $\Sigma(2)$ is 4 when using a two-way infinite tape. The following TM implements this behaviour:



We obtain: $A \square \vdash xB \square \vdash Axx \vdash B \square xx \vdash A \square xxx \vdash xBxxx$

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Computing Busy-Beaver?

How hard could this possibly be?

Theorem 3.7: The Busy-Beaver function is not computable.

Proof sketch: Suppose for a contradiction that Σ is computable.

- Then we can define a TM \mathcal{M}_{Σ} with tape alphabet $\{\mathbf{x}, \square\}$ that computes $\mathbf{x}^n \mapsto \mathbf{x}^{\Sigma(n)}$.
- Let \mathcal{M}_{+1} be a TM that computes $\mathbf{x}^n \mapsto \mathbf{x}^{n+1}$.
- Let $\mathcal{M}_{\times 2}$ be a TM that computes $\mathbf{x}^n \mapsto \mathbf{x}^{2n}$.
- Let k be the total number of states in \mathcal{M}_{Σ} , \mathcal{M}_{+1} , and $\mathcal{M}_{\times 2}$. There is a TM I_k with k states that writes the word \mathbf{x}^k to the empty tape.
- When executing I_k , $\mathcal{M}_{\times 2}$, \mathcal{M}_{Σ} , and \mathcal{M}_{+1} after another, the result is a TM with 2k states that writes $\Sigma(2k) + 1$ times x before halting.
- Hence $\Sigma(2k) \ge \Sigma(2k) + 1$ contradiction.

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Note 1: The proof involves an interesting idea of using TMs as "sub-routines" in

Note 2: If a TM can compute $f: \mathbb{N} \to \mathbb{N}$ in the usual inary encoding, it is not hard

Note 3: Transforming an arbitrary TM into one that uses only symbols $\{x, \Box\}$ on its

to get a TM for $\mathbf{x}^n \mapsto \mathbf{x}^{f(n)}$ by just using unary encoding instead.

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Busy Beaver in Practice

"Maybe the theoretical uncomputability is not really relevant after all – in practice, we surely can find values for practically relevant sizes of TMs, no?"

Well, progress since the 1960s has been rather modest:

$$\frac{n:}{\Sigma(n):}$$
 1 2 3 4 5 6 7 8
 $\frac{n:}{\Sigma(n):}$ 1 4 6 13 ≥ 4098 ≥ 3,5 × 10¹⁸²⁶⁷ gigantic insane

For n = 10, one has found a lower bound of the form $\Sigma(10) > 3^{3^{3^{1/2}}}$, where the complete expression has more than 7.6×10^{12} occurrences of the number 3.

Proof Notes

other TMs. We will use this again later on.

tape is slightly more involved, but doable.

Universality

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The Universal Machine

A first important observation of Turing was that TMs are powerful enough to simluate other TMs:

Step 1: Encode Turing Machines \mathcal{M} as words $\langle \mathcal{M} \rangle$

Step 2: Construct a universal Turing Machine \mathcal{U} , which gets $\langle \mathcal{M} \rangle$ as input and then simulates \mathcal{M}

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Step 2: The Universal Turing Machine

We define the universal TM ${\mathcal U}$ as multi-tape TM:

Tape 1: Input tape of \mathcal{U} : contains $\langle \mathcal{M} \rangle \# \# \langle w \rangle$

Tape 2: Working tape of $\mathcal U$

Tape 3: Stores the state of the simulated TM

Tape 4: Working tape of the simulated TM

The working principle of ${\mathcal U}$ is easily sketched:

- $\mathcal U$ validates the inpurt, copies $\langle w \rangle$ to Tape 4, moves the head on Tape 4 to the start and initialises Tape 3 with bin(0) (i.e., $\langle q_0 \rangle$).
- In each step $\mathcal U$ reads an (encoded) symbol from the head position on Tape 4, and searches for the simulated state (Tape 3) a matching transition in $\langle \mathcal M \rangle$ on Tape 1 (w.l.o.g. assume that the final states of the encoded TM have no transitions):
 - Transition found: update state on Tape 3; replace the encoded symbol on Tape 4 by the new symbol; move the head on Tape 4 accordingly
 - Transition not found: if the state on Tape 3 is q_{accept} , then go to the final accepting state; else go to the final rejecting state

Step 1: encoding Turing Machines

Any reasonable encooding of a TM $\mathcal{M} = \langle Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}} \rangle$ is usable, e.g., the following (for DTMs):

- We use an alphabet {0, 1, #}
- States are enumerated in any order (beginning with q_0), and encoded in binary:

$$Q = \{q_0, \dots, q_n\} \rightsquigarrow \langle Q \rangle = \mathsf{bin}(0) \# \cdots \# \mathsf{bin}(n)$$

- We also encode Γ and the directions $\{R, L\}$ in binary
- A transition $\delta(q_i, \sigma_n) = \langle q_j, \sigma_m, D \rangle$ is encoded as 5-tuple: $\operatorname{enc}(q_i, \sigma_n) = \operatorname{bin}(i) \# \operatorname{bin}(n) \# \operatorname{bin}(j) \# \operatorname{bin}(m) \# \operatorname{bin}(D)$
- The transition function is encoded as a list of all these tuples, separated with #: $\langle \delta \rangle = (\text{enc}(q_i, \sigma_n) \#)_{a_i \in O, \sigma_i \in \Gamma}$
- Combining everything, we set $\langle \mathcal{M} \rangle = \langle \mathcal{Q} \rangle \# \langle \Sigma \rangle \# \langle \Gamma \rangle \# \langle \delta \rangle \# \langle q_{\text{accept}} \rangle \# \langle q_{\text{reject}} \rangle$

We can also encode arbitrary words to match this encoding:

• For a word $w = a_1 \cdots a_\ell$ we define $\langle w \rangle = \text{bin}(a_1) \# \cdots \# \text{bin}(a_\ell)$

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The Theory of Software

Theorem 3.8: There is a universal Turing Machine \mathcal{U} , that, when given an input $\langle \mathcal{M} \rangle$ ## $\langle w \rangle$, simulates the behaviour of a DTM \mathcal{M} on w:

- If \mathcal{M} halts on w, then \mathcal{U} halts on $\langle \mathcal{M} \rangle \# \# \langle w \rangle$ with the same result
- If \mathcal{M} does not halt on w, then \mathcal{U} does not halt on $\langle \mathcal{M} \rangle \# \# \langle w \rangle$ either

Our construction is for DTMs that recognise languages ("Turing acceptors") – DTMs that compute partila functions can be simulated in a similar fashion.

Practical consequences:

- Universal computers are possible
- We don't have to buy a new computer for every application
- Software exists

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Undecidable Problems and Reductions

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"'Proof"' by Intuition

Theorem 3.11: The Halting Problem P_{Halt} is undecidable.

"**Proof:**" The opposite would be too good to be true. Many unsolved problems could then be solved immediately.

Example 3.12: Goldbach's Conjecture (Christian Goldbach, 1742) states that every even number $n \ge 4$ is the sum of two primes. For instance, 4 = 2 + 2 and 100 = 47 + 53.

On can easily give an algorithm \mathcal{A} that verifies Goldbach's conjecture systematically by testing it for every even number starting with 4:

- Success: Test the next even number
- Failure: Terminate with output "Goldbach was wrong!"

The question "Will $\mathcal A$ halt?" therefore is equivalent of the question "Is Goldbach's conjecture wrong?"

Many other important open problems could be solved in this way.

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The Halting Problem

A classical undecidable problem:

Definition 3.9: The Halting Problem consists in the following question: Given a TM \mathcal{M} and a word w, will \mathcal{M} ever halt on input w?

We can fomulate the Halting Problem as a word problem by encoding \mathcal{M} and w:

Definition 3.10: The Halting Problem is the word problem for the language

 $\mathbf{P}_{\mathsf{Halt}} = \{ \langle \mathcal{M} \rangle \# \# \langle w \rangle \mid \mathcal{M} \text{ halts on input } w \},$

where $\langle \mathcal{M} \rangle$ und $\langle w \rangle$ are suitable encodings of \mathcal{M} and w, for which ## can be used as separator.

Remark: Wrongly encoded inputs are rejected.

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Proof by "Diagonalisation"

Theorem 3.11: The Halting Problem PHalt is undecidable.

Proof: By contradiction: Suppose there is a decider $\mathcal H$ for the Halting Problem.

Then one can construct a TM $\mathcal D$ that does the following:

- (1) Check if the given input is a TM encoding $\langle \mathcal{M} \rangle$
- (2) Simulate \mathcal{H} on input $\langle \mathcal{M} \rangle \# \langle \langle \mathcal{M} \rangle \rangle$, that is, check if \mathcal{M} halts on $\langle \mathcal{M} \rangle$
- (3) If yes, enter an infinite loop; if no, halt and accept

Will \mathcal{D} accept the input $\langle \mathcal{D} \rangle$?

 $\mathcal D$ halts and accepts if and only if $\mathcal D$ does not halt

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Contradiction.

Proof by Reduction

Theorem 3.11: The Halting Problem **P**_{Halt} is undecidable.

Proof: Suppose that the Halting Problem is decidable.

An algorithm:

- Input: natural number *k* (in binary)
- Iterate over all Turing machines \mathcal{M} that have k states and tape alphabet $\{\mathbf{x}, \square\}$:
 - Decide if $\mathcal M$ halts on the empty input ε (possible if the Halting problem is decidable)
 - If yes, then simulate M on the empty input and, when M has halted, count the number of x on the tape
 (possible, since there are universal TMs)
- Output: the maximal number of x written.

This algorithm would compute the Busy-Beaver funktion $\Sigma : \mathbb{N} \to \mathbb{N}$.

We have already shown that this is impossible – contradiction.

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Oracles

Definition 3.15: An Oracle Turing Machine (OTM) is a Turing machine \mathcal{M} with a special tape, called the oracle tape, and distinguished states $q_?$, q_{yes} , and q_{no} . For a language \mathbf{O} , the oracle machine $\mathcal{M}^{\mathbf{O}}$ can, in addition to the normal TM operations, do the following:

Whenever $\mathcal{M}^{\mathbf{0}}$ reaches $q_{?}$, its next state is q_{yes} if the content of the oracle tape is in $\mathbf{0}$, and q_{no} otherwise.

- The word problem for **O** might be very hard or even undecidable
- Nevertheless, asking the oracle always takes just one step
- For dramatic effect, we might assert that the contents of the oracle tape is consumed (emptied) during this mysterious operation. However, this does not usually make a difference to our results.

Definition 3.16: A problem **P** is Turing reducible to a problem **Q** (in Symbols: $\mathbf{P} \leq_T \mathbf{Q}$), if **P** is decided by an OTM $\mathcal{M}^{\mathbf{Q}}$ with oracle **Q**.

Turing Reductions

Our previous proof constructs an algorithm for one task (Busy Beaver) by calling subroutines for another task (the Halting Problem)

This idea can be generalised:

Informal Definition 3.13: A problem \mathbf{P} is Turing reducible to a problem \mathbf{Q} (in Symbols: $\mathbf{P} \leq_T \mathbf{Q}$), if \mathbf{P} can be solved by a program that may call \mathbf{Q} as a sub-program.

Example 3.14: Our proof uses a reduction of the Busy-Beaver computation to the Halting problem. Note that the subroutine might be called exponentially many times here.

To make this more formal, we need orcales.

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Undecidability via Turing Reductions

One can use Turing recductions to show undecidability:

Theorem 3.17: If **P** is undecidable and $P \leq_T \mathbf{Q}$, then **Q** is undecidable.

Proof: Via contrapositive: If $P \leq_T Q$ and Q is decidable, then we can implement the OTM that shows $P \leq_T Q$ as a regular TM, which shows that P is decidable. \square

Here is a small application:

Theorem 3.18: The language $\mathbf{P}_{\overline{\text{Halt}}} = \{\langle \mathcal{M} \rangle \# \# \langle w \rangle \mid \mathcal{M} \text{ does not halt on } w\}$ (the "Non-Halting Problem") is undecidable.

Proof sketch: Decide Halting by using $\mathbf{P}_{\overline{\text{Halt}}}$ as an oracle and inverting the result. Check TM encoding first (wrong encodings are rejected by Halting and Non-Halting).

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ε -Halting

Special cases of the Halting Problem are usually not simpler:

Definition 3.19: The ε -Halting Problem consists in the following question: Given a TM \mathcal{M} , will \mathcal{M} ever halt on the empty input ε ?

Theorem 3.20: The ε -Halting Problem is undecidable.

Proof: We define an oracle machine for deciding Halting:

- Input: A Turing machine \mathcal{M} and a word w.
- Construct a TM \mathcal{M}_w that runs in two phases:
 - (1) Delete the input tape and write the word w instead
 - (2) Process the input like \mathcal{M}
- Solve the ε -Halting problem for \mathcal{M}_w (oracle).
- Output: output of the ε -Halting Problem

This Turing-reduces Halting to ε -halting, so the latter is also undecidable.

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Summary and Outlook

Busy Beaver is uncomputable

Halting is undecidable (for many reasons)

Orcales and Turing reductions formalise the notion of a "subroutine" and help us to transfer our insights from one problem to another

What's next?

- Some more undecidability
- Recursion and self-referentiality
- Actual complexity classes

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