

COMPLEXITY THEORY

Lecture 3: Undecidability

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Knowledge-Based Systems

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Decidability and Computability

Review: A language is

- **recognisable** (or **semi-decidable**, or **recursively enumerable**) if it is the language of all words recognised by some Turing machine
- **decidable** (or **recursive**) if it is the language of a Turing machine that always halts, even on inputs that are not accepted
- **undecidable** if it is not decidable

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Instead of acceptance of words, we can also consider other computations:

Definition 3.1: A TM \mathcal{M} **computes** a partial function $f_{\mathcal{M}} : \Sigma^* \rightarrow \Sigma^*$ as follows. We have $f_{\mathcal{M}}(w) = v$ for a word $w \in \Sigma^*$ if \mathcal{M} halts on input w with a tape that contains only the word $v \in \Sigma^*$ (followed by blanks).

In this case, the function $f_{\mathcal{M}}$ is called **computable**.

Total, computable functions are called **recursive**.

Functions may therefore be computable or uncomputable.

Undecidability is Real

A fundamental insight of computer science and mathematics is that there are undecidable languages:

Theorem 3.2: There are undecidable languages over every alphabet Σ .

Proof: See exercise. □

Analogously, there are uncomputable functions.

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Example 3.3: Let \mathbf{L}_π be the set of all finite number sequences, that occur in the decimal representation of π . For example, **14159265** $\in \mathbf{L}_\pi$ and **41** $\in \mathbf{L}_\pi$.

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Example 3.3: Let \mathbf{L}_π be the set of all finite number sequences, that occur in the decimal representation of π . For example, $14159265 \in \mathbf{L}_\pi$ and $41 \in \mathbf{L}_\pi$.

We do not know if the language \mathbf{L}_π is decidable, but it might be (e.g., if every finite sequence of digits occurred in π , which, however, is not known to be true today).

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There are even case, where we are sure that a problem is decidable without knowing how to solve it.

Example 3.4 (after Uwe Schöning): Let $L_{\pi 7}$ be the set of all number sequences of the form 7^n that occur in the decimal representation of π .

$L_{\pi 7}$ is decidable:

- Option 1: π contains sequences of arbitrary many 7 . Then $L_{\pi 7}$ is decided by a TM that accepts all words of the form 7^n .
- Option 2: π contains sequences of 7 s only up to a certain maximal length ℓ . Then $L_{\pi 7}$ is decided by a TM that accepts all words of the form 7^n with $n \leq \ell$.

In each possible case, we have a practical algorithm – we just don't know which one is correct.

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Answer: That depends on $n \dots$

Definition 3.5: We define $S(n)$ as the largest number of steps that any DTM with n states and tape alphabet $\Gamma = \{x, \square\}$ executes on the empty tape, before it eventually halts.

Observation: S is well defined.

- The number of TMs with at most n states is finite
- Among the relevant n -state TMs there must be a largest number of steps before halting (TMs that do not halt are ignored)

Busy Beaver



Tibor Radó, BB inventor

A small variation of the step counter function leads to the Busy-Beaver Problem:

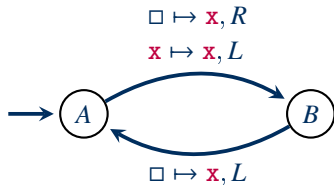
Definition 3.6: The **Busy-Beaver function** $\Sigma : \mathbb{N} \rightarrow \mathbb{N}$ is a total function, where $\Sigma(n)$ is the maximal number of x that a DTM with at most n states and tape alphabet $\Gamma = \{x, \square\}$ can write when starting on the empty tape and before it eventually halts.

Note: The exact value of $\Sigma(n)$ depends on details of the TM definition.

Most works in this area assume a two-sided infinite tape that can be extended to the left and to the right if necessary.

Example

The Busy-Beaver number $\Sigma(2)$ is 4 when using a two-way infinite tape. The following TM implements this behaviour:



We obtain: $A \square \vdash \mathbf{x} B \square \vdash A \mathbf{xx} \vdash B \square \mathbf{xxx} \vdash A \square \mathbf{xxxx} \vdash \mathbf{xBxxxx}$

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- Let k be the total number of states in \mathcal{M}_Σ , \mathcal{M}_{+1} , and $\mathcal{M}_{\times 2}$. There is a TM \mathcal{I}_k with k states that writes the word \mathbf{x}^k to the empty tape.

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- When executing \mathcal{I}_k , $\mathcal{M}_{\times 2}$, \mathcal{M}_Σ , and \mathcal{M}_{+1} after another, the result is a TM with $2k$ states that writes $\Sigma(2k) + 1$ times \mathbf{x} before halting.

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- When executing \mathcal{I}_k , $\mathcal{M}_{\times 2}$, \mathcal{M}_Σ , and \mathcal{M}_{+1} after another, the result is a TM with $2k$ states that writes $\Sigma(2k) + 1$ times \mathbf{x} before halting.
- Hence $\Sigma(2k) \geq \Sigma(2k) + 1$ – contradiction. □

Proof Notes

Note 1: The proof involves an interesting idea of using TMs as “sub-routines” in other TMs. We will use this again later on.

Note 2: If a TM can compute $f : \mathbb{N} \rightarrow \mathbb{N}$ in the usual inary encoding, it is not hard to get a TM for $\mathbf{x}^n \mapsto \mathbf{x}^{f(n)}$ by just using unary encoding instead.

Note 3: Transforming an arbitrary TM into one that uses only symbols $\{\mathbf{x}, \square\}$ on its tape is slightly more involved, but doable.

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$n:$	1	2
$\Sigma(n):$	1	4

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<hr/>			
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$n:$	1	2	3	4	5
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For $n = 10$, one has found a lower bound of the form $\Sigma(10) > 3^{3^{3^{\dots^3}}}$, where the complete expression has more than 7.6×10^{12} occurrences of the number 3.

Universality

The Universal Machine

A first important observation of Turing was that TMs are powerful enough to simulate other TMs:

Step 1: Encode Turing Machines \mathcal{M} as words $\langle \mathcal{M} \rangle$

Step 2: Construct a **universal Turing Machine** \mathcal{U} , which gets $\langle \mathcal{M} \rangle$ as input and then simulates \mathcal{M}

Step 1: encoding Turing Machines

Any reasonable encoding of a TM $\mathcal{M} = \langle Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}} \rangle$ is usable, e.g., the following (for DTMs):

- We use an alphabet $\{0, 1, \#\}$
- States are enumerated in any order (beginning with q_0), and encoded in binary:
 $Q = \{q_0, \dots, q_n\} \rightsquigarrow \langle Q \rangle = \text{bin}(0)\#\dots\#\text{bin}(n)$
- We also encode Γ and the directions $\{R, L\}$ in binary
- A transition $\delta(q_i, \sigma_n) = \langle q_j, \sigma_m, D \rangle$ is encoded as 5-tuple:
 $\text{enc}(q_i, \sigma_n) = \text{bin}(i)\#\text{bin}(n)\#\text{bin}(j)\#\text{bin}(m)\#\text{bin}(D)$
- The transition function is encoded as a list of all these tuples, separated with $\#$: $\langle \delta \rangle = (\text{enc}(q_i, \sigma_n)\#)_{q_i \in Q, \sigma_i \in \Gamma}$
- Combining everything, we set $\langle \mathcal{M} \rangle = \langle Q \rangle\#\#\langle \Sigma \rangle\#\#\langle \Gamma \rangle\#\#\langle \delta \rangle\#\#\langle q_{\text{accept}} \rangle\#\#\langle q_{\text{reject}} \rangle$

We can also encode arbitrary words to match this encoding:

- For a word $w = a_1 \dots a_\ell$ we define $\langle w \rangle = \text{bin}(a_1)\#\dots\#\text{bin}(a_\ell)$

Step 2: The Universal Turing Machine

We define the universal TM \mathcal{U} as multi-tape TM:

Tape 1: Input tape of \mathcal{U} : contains $\langle \mathcal{M} \rangle \#\#\langle w \rangle$

Tape 2: Working tape of \mathcal{U}

Tape 3: Stores the state of the simulated TM

Tape 4: Working tape of the simulated TM

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The working principle of \mathcal{U} is easily sketched:

- \mathcal{U} validates the input, copies $\langle w \rangle$ to Tape 4, moves the head on Tape 4 to the start and initialises Tape 3 with $\text{bin}(0)$ (i.e., $\langle q_0 \rangle$).
- In each step \mathcal{U} reads an (encoded) symbol from the head position on Tape 4, and searches for the simulated state (Tape 3) a matching transition in $\langle \mathcal{M} \rangle$ on Tape 1 (w.l.o.g. assume that the final states of the encoded TM have no transitions):
 - Transition found: update state on Tape 3; replace the encoded symbol on Tape 4 by the new symbol; move the head on Tape 4 accordingly
 - Transition not found: if the state on Tape 3 is q_{accept} , then go to the final accepting state; else go to the final rejecting state

The Theory of Software

Theorem 3.8: There is a **universal Turing Machine** \mathcal{U} , that, when given an input $\langle \mathcal{M} \rangle \#\#\langle w \rangle$, simulates the behaviour of a DTM \mathcal{M} on w :

- If \mathcal{M} halts on w , then \mathcal{U} halts on $\langle \mathcal{M} \rangle \#\#\langle w \rangle$ with the same result
- If \mathcal{M} does not halt on w , then \mathcal{U} does not halt on $\langle \mathcal{M} \rangle \#\#\langle w \rangle$ either

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Practical consequences:

- Universal computers are possible
- We don’t have to buy a new computer for every application
- Software exists

Undecidable Problems and Reductions

The Halting Problem

A classical undecidable problem:

Definition 3.9: The **Halting Problem** consists in the following question:

Given a TM \mathcal{M} and a word w ,
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We can formulate the Halting Problem as a word problem by encoding \mathcal{M} and w :

Definition 3.10: The **Halting Problem** is the word problem for the language

$$\mathbf{P}_{\text{Halt}} = \{\langle \mathcal{M} \rangle \#\# \langle w \rangle \mid \mathcal{M} \text{ halts on input } w\},$$

where $\langle \mathcal{M} \rangle$ und $\langle w \rangle$ are suitable encodings of \mathcal{M} and w , for which $\#\#$ can be used as separator.

Remark: Wrongly encoded inputs are rejected.

"Proof" by Intuition

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One can easily give an algorithm \mathcal{A} that verifies Goldbach's conjecture systematically by testing it for every even number starting with 4:

- Success: Test the next even number
- Failure: Terminate with output "Goldbach was wrong!"

The question "Will \mathcal{A} halt?" therefore is equivalent to the question "Is Goldbach's conjecture wrong?"

Many other important open problems could be solved in this way.

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Then one can construct a TM \mathcal{D} that does the following:

- (1) Check if the given input is a TM encoding $\langle \mathcal{M} \rangle$
- (2) Simulate \mathcal{H} on input $\langle \mathcal{M} \rangle \#\#\langle \langle \mathcal{M} \rangle \rangle$, that is, check if \mathcal{M} halts on $\langle \mathcal{M} \rangle$
- (3) If yes, enter an infinite loop;
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Will \mathcal{D} accept the input $\langle \mathcal{D} \rangle$?

\mathcal{D} halts and accepts if and only if \mathcal{D} does not halt

Contradiction. □

Proof by Reduction

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An algorithm:

- Input: natural number k (in binary)
- Iterate over all Turing machines \mathcal{M} that have k states and tape alphabet $\{\mathbf{x}, \square\}$:
 - Decide if \mathcal{M} halts on the empty input ε
(possible if the Halting problem is decidable)
 - If yes, then simulate \mathcal{M} on the empty input and, when \mathcal{M} has halted, count the number of \mathbf{x} on the tape
(possible, since there are universal TMs)
- Output: the maximal number of \mathbf{x} written.

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This algorithm would compute the Busy-Beaver funktion $\Sigma : \mathbb{N} \rightarrow \mathbb{N}$.

We have already shown that this is impossible – contradiction. □

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This idea can be generalised:

Informal Definition 3.13: A problem **P** is **Turing reducible** to a problem **Q** (in Symbols: $\mathbf{P} \leq_T \mathbf{Q}$), if **P** can be solved by a program that may call **Q** as a sub-program.

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Example 3.14: Our proof uses a reduction of the Busy-Beaver computation to the Halting problem. Note that the subroutine might be called exponentially many times here.

To make this more formal, we need oracles.

Oracles

Definition 3.15: An **Oracle Turing Machine** (OTM) is a Turing machine \mathcal{M} with a special tape, called the oracle tape, and distinguished states $q_?$, q_{yes} , and q_{no} . For a language \mathbf{O} , the **oracle machine** $\mathcal{M}^{\mathbf{O}}$ can, in addition to the normal TM operations, do the following:

Whenever $\mathcal{M}^{\mathbf{O}}$ reaches $q_?$, its next state is q_{yes} if the content of the oracle tape is in \mathbf{O} , and q_{no} otherwise.

Oracles

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Definition 3.16: A problem \mathbf{P} is **Turing reducible** to a problem \mathbf{Q} (in Symbols: $\mathbf{P} \leq_T \mathbf{Q}$), if \mathbf{P} is decided by an OTM $\mathcal{M}^{\mathbf{Q}}$ with oracle \mathbf{Q} .

Undecidability via Turing Reductions

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Here is a small application:

Theorem 3.18: The language $\mathbf{P}_{\overline{\text{Halt}}} = \{\langle \mathcal{M} \rangle \#\# \langle w \rangle \mid \mathcal{M} \text{ does not halt on } w\}$ (the “Non-Halting Problem”) is undecidable.

Proof sketch: Decide Halting by using $\mathbf{P}_{\overline{\text{Halt}}}$ as an oracle and inverting the result. Check TM encoding first (wrong encodings are rejected by Halting and Non-Halting). \square

ε -Halting

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Proof: We define an oracle machine for deciding Halting:

- Input: A Turing machine \mathcal{M} and a word w .
- Construct a TM \mathcal{M}_w that runs in two phases:
 - (1) Delete the input tape and write the word w instead
 - (2) Process the input like \mathcal{M}
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This Turing-reduces Halting to ε -halting, so the latter is also undecidable. □

Summary and Outlook

Busy Beaver is uncomputable

Halting is undecidable (for many reasons)

Oracles and Turing reductions formalise the notion of a “subroutine” and help us to transfer our insights from one problem to another

What's next?

- Some more undecidability
- Recursion and self-referentiality
- Actual complexity classes