



TECHNISCHE
UNIVERSITÄT
DRESDEN

DEDUCTION SYSTEMS

Optimizations for Tableau Procedures

Sebastian Rudolph

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

- check satisfiability of C by constructing an abstraction of a model \mathcal{I} such that $C^{\mathcal{I}} \neq \emptyset$

Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

- check satisfiability of C by constructing an abstraction of a model \mathcal{I} such that $C^{\mathcal{I}} \neq \emptyset$
- concepts in negation normal form (NNF) \rightsquigarrow makes rules simpler

Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

- check satisfiability of C by constructing an abstraction of a model \mathcal{I} such that $C^{\mathcal{I}} \neq \emptyset$
- concepts in negation normal form (NNF) \rightsquigarrow makes rules simpler
- tableau (model abstraction) corresponds to a graph/tree $G = \langle V, E, L \rangle$

Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

- check satisfiability of C by constructing an abstraction of a model \mathcal{I} such that $C^{\mathcal{I}} \neq \emptyset$
- concepts in negation normal form (NNF) \rightsquigarrow makes rules simpler
- tableau (model abstraction) corresponds to a graph/tree $G = \langle V, E, L \rangle$
- initialize G with a node v such that $L(v) = \{C\}$

Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

- check satisfiability of C by constructing an abstraction of a model \mathcal{I} such that $C^{\mathcal{I}} \neq \emptyset$
- concepts in negation normal form (NNF) \rightsquigarrow makes rules simpler
- tableau (model abstraction) corresponds to a graph/tree $G = \langle V, E, L \rangle$
- initialize G with a node v such that $L(v) = \{C\}$
- extend G by applying tableau rules

Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

- check satisfiability of C by constructing an abstraction of a model \mathcal{I} such that $C^{\mathcal{I}} \neq \emptyset$
- concepts in negation normal form (NNF) \rightsquigarrow makes rules simpler
- tableau (model abstraction) corresponds to a graph/tree $G = \langle V, E, L \rangle$
- initialize G with a node v such that $L(v) = \{C\}$
- extend G by applying **tableau rules**
 - \sqcup -rule non-deterministic (we guess)
- tableau branch closed if G contains an atomic contradiction (**clash**)

Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

- check satisfiability of C by constructing an abstraction of a model \mathcal{I} such that $C^{\mathcal{I}} \neq \emptyset$
- concepts in negation normal form (NNF) \rightsquigarrow makes rules simpler
- tableau (model abstraction) corresponds to a graph/tree $G = \langle V, E, L \rangle$
- initialize G with a node v such that $L(v) = \{C\}$
- extend G by applying **tableau rules**
 - \sqcup -rule non-deterministic (we guess)
- tableau branch closed if G contains an atomic contradiction (**clash**)
- tableau construction successful, if no further rules are applicable and there is no contradiction

Tableau Algorithm for \mathcal{ALC} Concepts and TBoxes

- check satisfiability of C by constructing an abstraction of a model \mathcal{I} such that $C^{\mathcal{I}} \neq \emptyset$
- concepts in negation normal form (NNF) \rightsquigarrow makes rules simpler
- tableau (model abstraction) corresponds to a graph/tree $G = \langle V, E, L \rangle$
- initialize G with a node v such that $L(v) = \{C\}$
- extend G by applying **tableau rules**
 - \sqcup -rule non-deterministic (we guess)
- tableau branch closed if G contains an atomic contradiction (**clash**)
- tableau construction successful, if no further rules are applicable and there is no contradiction
- C is satisfiable iff there is a successful tableau construction

Treatment of Knowledge Bases

we condense the TBox into one concept:

for $\mathcal{T} = \{C_i \sqsubseteq D_i \mid 1 \leq i \leq n\}$, $C_{\mathcal{T}} = \text{NNF}(\bigwedge_{1 \leq i \leq n} \neg C_i \sqcup D_i)$

we extend the rules of the \mathcal{ALC} tableau algorithm:

\mathcal{T} -rule: for an arbitrary $v \in V$ with $C_{\mathcal{T}} \notin L(v)$,
let $L(v) := L(v) \cup \{C_{\mathcal{T}}\}$.

in order to take an ABox \mathcal{A} into account, initialize G such that

- V contains a node v_a for every individual a in \mathcal{A}
- $L(v_a) = \{C \mid C(a) \in \mathcal{A}\}$
- $\langle v_a, v_b \rangle \in E$ iff $r(a, b) \in \mathcal{A}$

Extensions of the Logic

- plus inverses (\mathcal{ALCI}): inverse roles in edge labels, definition and use of r -neighbors instead of r -successors in tableau rules
- plus functional roles (\mathcal{ALCIF}): merging of nodes to account for functionality

blocking guarantees termination:

- \mathcal{ALC} subset-blocking
- plus inverses (\mathcal{ALCI}): equality blocking
- plus functional roles (\mathcal{ALCIF}): pairwise blocking

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Optimizations

- Naïve implementation not performant enough
 - \mathcal{T} -regel adds one disjunction per axiom to the corresponding node
 - ontologies may contain > 1.000 axioms and tableaux may contain thousands of nodes

Optimizations

- Naïve implementation not performant enough
 - \mathcal{T} -regel adds one disjunction per axiom to the corresponding node
 - ontologies may contain > 1.000 axioms and tableaux may contain thousands of nodes
- realistic implementations use many optimizations
 - (Lazy) unfolding
 - Absorbtion
 - Dependency directed backtracking
 - Simplification and Normalization
 - Caching
 - Heuristics
 - ...

Optimizations

- Naïve implementation not performant enough
 - \mathcal{T} -regel adds one disjunction per axiom to the corresponding node
 - ontologies may contain > 1.000 axioms and tableaux may contain thousands of nodes
- realistic implementations use many optimizations
 - (Lazy) unfolding
 - Absorbtion
 - Dependency directed backtracking
 - Simplification and Normalization
 - Caching
 - Heuristics
 - ...

Agenda

- Recap Tableau Calculus
- Optimizations
 - **Unfolding**
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Unfolding

- \mathcal{T} -rule is not necessary if \mathcal{T} is **unfoldable**, i.e., every axiom is:
 - **definitorial**: form $A \sqsubseteq C$ or $A \equiv C$ for A a concept name
($A \equiv C$ corresponds to $A \sqsubseteq C$ and $C \sqsubseteq A$)
 - **acyclic**: C uses A neither directly nor indirectly
 - **unique**: only one such axiom exists for every concept name A

Unfolding

- \mathcal{T} -rule is not necessary if \mathcal{T} is **unfoldable**, i.e., every axiom is:
 - **definitorial**: form $A \sqsubseteq C$ or $A \equiv C$ for A a concept name
($A \equiv C$ corresponds to $A \sqsubseteq C$ and $C \sqsubseteq A$)
 - **acyclic**: C uses A neither directly nor indirectly
 - **unique**: only one such axiom exists for every concept name A
- If \mathcal{T} is unfoldable, the TBox can be (**unfolded**) into a concept

Unfolding Example

- We check satisfiability of A w.r.t. the TBox \mathcal{T}

\mathcal{T} :

$$A \sqsubseteq B \sqcap \exists r.C$$

$$B \equiv C \sqcup D$$

$$C \sqsubseteq \exists r.D$$

Unfolding Example

- We check satisfiability of A w.r.t. the TBox \mathcal{T}

A

\mathcal{T} :

$$A \sqsubseteq B \sqcap \exists r.C$$

$$B \equiv C \sqcup D$$

$$C \sqsubseteq \exists r.D$$

Unfolding Example

- We check satisfiability of A w.r.t. the TBox \mathcal{T}

$$A \\ \rightsquigarrow A \sqcap B \sqcap \exists r.C$$

$$\mathcal{T}: \\ A \sqsubseteq B \sqcap \exists r.C \\ B \equiv C \sqcup D \\ C \sqsubseteq \exists r.D$$

Unfolding Example

- We check satisfiability of A w.r.t. the TBox \mathcal{T}

$$\begin{aligned} & A \\ \rightsquigarrow & A \sqcap B \sqcap \exists r.C \\ \rightsquigarrow & A \sqcap (C \sqcup D) \sqcap \exists r.C \end{aligned}$$

$$\begin{aligned} \mathcal{T}: \\ & A \sqsubseteq B \sqcap \exists r.C \\ & B \equiv C \sqcup D \\ & C \sqsubseteq \exists r.D \end{aligned}$$

Unfolding Example

- We check satisfiability of A w.r.t. the TBox \mathcal{T}

$$\begin{aligned} & A \\ \rightsquigarrow & A \sqcap B \sqcap \exists r.C \\ \rightsquigarrow & A \sqcap (C \sqcup D) \sqcap \exists r.C \\ \rightsquigarrow & A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D) \end{aligned}$$

$$\begin{aligned} \mathcal{T}: \\ & A \sqsubseteq B \sqcap \exists r.C \\ & B \equiv C \sqcup D \\ & C \sqsubseteq \exists r.D \end{aligned}$$

Unfolding Example

- We check satisfiability of A w.r.t. the TBox \mathcal{T}

$$\begin{aligned} & A \\ \rightsquigarrow & A \sqcap B \sqcap \exists r.C \\ \rightsquigarrow & A \sqcap (C \sqcup D) \sqcap \exists r.C \\ \rightsquigarrow & A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D) \end{aligned}$$

\mathcal{T} :

$$\begin{aligned} & A \sqsubseteq B \sqcap \exists r.C \\ & B \equiv C \sqcup D \\ & C \sqsubseteq \exists r.D \end{aligned}$$

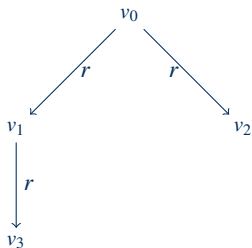
- A is satisfiable w.r.t. \mathcal{T} iff

$$A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$$

is satisfiable w.r.t. the empty TBox

Tableau Algorithm Example with Unfolding

We obtain the following contradiction-free tableau for the satisfiability of $U = A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$:



$$L(v_0) = \{U, A, (C \sqcap \exists r.D) \sqcup D, \\ \exists r.(C \sqcap \exists r.D), C \sqcap \exists r.D, \\ C, \exists r.D\}$$

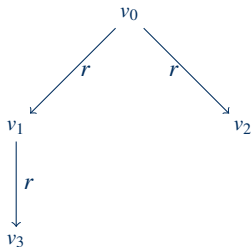
$$L(v_1) = \{C \sqcap \exists r.D, C, \exists r.D\}$$

$$L(v_2) = \{D\}$$

$$L(v_3) = \{D\}$$

Tableau Algorithm Example with Unfolding

We obtain the following contradiction-free tableau for the satisfiability of $U = A \sqcap ((C \sqcap \exists r.D) \sqcup D) \sqcap \exists r.(C \sqcap \exists r.D)$:



$$L(v_0) = \{U, A, (C \sqcap \exists r.D) \sqcup D, \\ \exists r.(C \sqcap \exists r.D), C \sqcap \exists r.D, \\ C, \exists r.D\}$$

$$L(v_1) = \{C \sqcap \exists r.D, C, \exists r.D\}$$

$$L(v_2) = \{D\}$$

$$L(v_3) = \{D\}$$

Only one disjunctive decision left!

Lazy Unfolding

- computation of NNF together with unfolding may decrease performance, e.g.:
 - satisfiability of $C \sqcap \neg C$ w.r.t. $\mathcal{T} = \{C \sqsubseteq A \sqcap B\}$
 - unfolding: $C \sqcap A \sqcap B \sqcap \neg(C \sqcap A \sqcap B)$
 - NNF + unfolding: $C \sqcap A \sqcap B \sqcap (\neg C \sqcup \neg A \sqcup \neg B)$

Lazy Unfolding

- computation of NNF together with unfolding may decrease performance, e.g.:
 - satisfiability of $C \sqcap \neg C$ w.r.t. $\mathcal{T} = \{C \sqsubseteq A \sqcap B\}$
 - unfolding: $C \sqcap A \sqcap B \sqcap \neg(C \sqcap A \sqcap B)$
 - NNF + unfolding: $C \sqcap A \sqcap B \sqcap (\neg C \sqcup \neg A \sqcup \neg B)$
 - better: apply NNF and unfolding if needed, via corresponding tableau rules:
 - $A \equiv C \rightsquigarrow A \sqsubseteq C$ and $A \supseteq C$
- \sqsubseteq -rule: For $v \in V$ such that $A \sqsubseteq C \in \mathcal{T}$, $A \in L(v)$ and $C \notin L(v)$
let $L(v) := L(v) \cup C$.
- \supseteq -rule: For $v \in V$ such that $A \supseteq C \in \mathcal{T}$, $\neg A \in L(v)$ and $\neg C \notin L(v)$
let $L(v) := L(v) \cup \{\neg C\}$.
- \neg -rule: For $v \in V$ such that $\neg C \in L(v)$ and $\text{NNF}(\neg C) \notin L(v)$,
let $L(v) := L(v) \cup \{\text{NNF}(\neg C)\}$.

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Absorption

- What if \mathcal{T} is not unfoldable?
 - Separate \mathcal{T} into \mathcal{T}_u (unfoldable part) and \mathcal{T}_g (GCIs, not unfoldable)
 - \mathcal{T}_u is treated via \sqsubseteq - and \sqsupseteq -rules
 - \mathcal{T}_g is treated via the \mathcal{T} -rule

Absorption

- What if \mathcal{T} is not unfoldable?
 - Separate \mathcal{T} into \mathcal{T}_u (unfoldable part) and \mathcal{T}_g (GCIs, not unfoldable)
 - \mathcal{T}_u is treated via \sqsubseteq - and \supseteq -rules
 - \mathcal{T}_g is treated via the \mathcal{T} -rule
- absorption decreases \mathcal{T}_g and increases \mathcal{T}_u
 - 1 take an axiom from \mathcal{T}_g , e.g., $A \sqcap B \sqsubseteq C$
 - 2 transform the axiom: $A \sqsubseteq C \sqcup \neg B$
 - 3 if \mathcal{T}_u contains an axiom of the form $A \equiv D$ ($A \sqsubseteq D$ and $D \supseteq A$), then $A \sqsubseteq C \sqcup \neg B$ cannot be absorbed; $A \sqsubseteq C \sqcup \neg B$ remains in \mathcal{T}_g
 - 4 otherwise, if \mathcal{T}_u contains an axiom of the form $A \sqsubseteq D$, then absorb $A \sqsubseteq C \sqcup \neg B$ resulting in $A \sqsubseteq D \sqcap (C \sqcup \neg B)$
 - 5 otherwise move $A \sqsubseteq C \sqcup \neg B$ to \mathcal{T}_u

Absorption

- What if \mathcal{T} is not unfoldable?
 - Separate \mathcal{T} into \mathcal{T}_u (unfoldable part) and \mathcal{T}_g (GCIs, not unfoldable)
 - \mathcal{T}_u is treated via \sqsubseteq - and \supseteq -rules
 - \mathcal{T}_g is treated via the \mathcal{T} -rule
- absorption decreases \mathcal{T}_g and increases \mathcal{T}_u
 - 1 take an axiom from \mathcal{T}_g , e.g., $A \sqcap B \sqsubseteq C$
 - 2 transform the axiom: $A \sqsubseteq C \sqcup \neg B$
 - 3 if \mathcal{T}_u contains an axiom of the form $A \equiv D$ ($A \sqsubseteq D$ and $D \supseteq A$), then $A \sqsubseteq C \sqcup \neg B$ cannot be absorbed; $A \sqsubseteq C \sqcup \neg B$ remains in \mathcal{T}_g
 - 4 otherwise, if \mathcal{T}_u contains an axiom of the form $A \sqsubseteq D$, then absorb $A \sqsubseteq C \sqcup \neg B$ resulting in $A \sqsubseteq D \sqcap (C \sqcup \neg B)$
 - 5 otherwise move $A \sqsubseteq C \sqcup \neg B$ to \mathcal{T}_u
- If $A \equiv D \in \mathcal{T}_u$, try rewriting/absorption with other axioms in \mathcal{T}_u

Absorption

- What if \mathcal{T} is not unfoldable?
 - Separate \mathcal{T} into \mathcal{T}_u (unfoldable part) and \mathcal{T}_g (GCIs, not unfoldable)
 - \mathcal{T}_u is treated via \sqsubseteq - and \supseteq -rules
 - \mathcal{T}_g is treated via the \mathcal{T} -rule
- absorption decreases \mathcal{T}_g and increases \mathcal{T}_u
 - 1 take an axiom from \mathcal{T}_g , e.g., $A \sqcap B \sqsubseteq C$
 - 2 transform the axiom: $A \sqsubseteq C \sqcup \neg B$
 - 3 if \mathcal{T}_u contains an axiom of the form $A \equiv D$ ($A \sqsubseteq D$ and $D \supseteq A$), then $A \sqsubseteq C \sqcup \neg B$ cannot be absorbed; $A \sqsubseteq C \sqcup \neg B$ remains in \mathcal{T}_g
 - 4 otherwise, if \mathcal{T}_u contains an axiom of the form $A \sqsubseteq D$, then absorb $A \sqsubseteq C \sqcup \neg B$ resulting in $A \sqsubseteq D \sqcap (C \sqcup \neg B)$
 - 5 otherwise move $A \sqsubseteq C \sqcup \neg B$ to \mathcal{T}_u
- If $A \equiv D \in \mathcal{T}_u$, try rewriting/absorption with other axioms in \mathcal{T}_u
- nondeterministic: $B \sqsubseteq C \sqcup \neg A$ also possible

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - [Dependency-Directed Backtracking](#)
 - Further Optimizations
- Classification
- Summary

Dependency-Directed Backtracking

- despite those optimizations, search space often to big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

$$v \quad \sqcap\text{-rule} \quad L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$$

Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

$$v \quad \sqcap\text{-rule} \quad L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$$

$$\quad \sqcup\text{-rule} \quad L(v) := L(v) \cup \{C_1\}$$

$$\quad \vdots \quad \quad \quad \vdots$$

$$\quad \sqcup\text{-rule} \quad L(v) := L(v) \cup \{C_n\}$$

Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

v	\sqcap -rule	$L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$
r	\sqcup -rule	$L(v) := L(v) \cup \{C_1\}$
	\vdots	\vdots
	\sqcup -rule	$L(v) := L(v) \cup \{C_n\}$
w	\exists -rule	$L(w) := \{\neg A\}$

Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

v	\sqcap -rule	$L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$
r	\sqcup -rule	$L(v) := L(v) \cup \{C_1\}$
\vdots	\vdots	\vdots
w	\sqcup -rule	$L(w) := L(v) \cup \{C_n\}$
	\exists -rule	$L(w) := \{\neg A\}$
	\forall -rule	$L(w) := \{\neg A, A\}$ <i>clash</i>

Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

$$v \quad \sqcap\text{-rule} \quad L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$$

$$\sqcup\text{-rule} \quad L(v) := L(v) \cup \{C_1\}$$

$$\vdots \quad \quad \quad \vdots \quad \quad \quad \vdots$$

~~$$\sqcup\text{-rule} \quad L(v) := L(v) \cup \{C_n\}$$

$$\exists\text{-rule} \quad L(w) := \{\neg A\}$$

$$\forall\text{-rule} \quad L(w) := \{\neg A, A\} \text{ clash}$$

$$\sqcup\text{-rule} \quad L(v) := L(v) \cup \{D_n\}$$~~

Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

v \downarrow r \downarrow w	\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n),$ $\exists r. \neg A, \forall r. A\}$
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$
	\vdots	\vdots	\vdots
	\sqcup-rule	$L(v) :=$	$L(v) \cup \{C_n\}$
	\exists-rule	$L(w) :=$	$\{\neg A\}$
	\forall-rule	$L(w) :=$	$\{\neg A, A\}$ <i>clash</i>
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{D_n\}$
	\exists -rule	$L(w) :=$	$\{\neg A\}$

Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

v \downarrow r \downarrow w	\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n),$ $\exists r. \neg A, \forall r. A\}$
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$
	\vdots	\vdots	\vdots
	\sqcup-rule	$L(v) :=$	$L(v) \cup \{C_n\}$
	\exists-rule	$L(w) :=$	$\{\neg A\}$
	\forall-rule	$L(w) :=$	$\{\neg A, A\}$ <i>clash</i>
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{D_n\}$
	\exists -rule	$L(w) :=$	$\{\neg A\}$
	\forall -rule	$L(w) :=$	$\{\neg A, A\}$ <i>clash</i>

Dependency-Directed Backtracking

- despite those optimizations, search space often too big
- let $v \in V$ with $(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$

v \downarrow r \downarrow w	\sqcap -rule	$L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$
	\sqcup -rule	$L(v) := L(v) \cup \{C_1\}$
	\vdots	\vdots
	\sqcup-rule	$L(v) := L(v) \cup \{C_n\}$
	\exists-rule	$L(w) := \{\neg A\}$
	\forall-rule	$L(w) := \{\neg A, A\}$ <i>clash</i>
	\sqcup -rule	$L(v) := L(v) \cup \{D_n\}$
	\exists -rule	$L(w) := \{\neg A\}$
	\forall -rule	$L(w) := \{\neg A, A\}$ <i>clash</i>

- exponentially big search space is traversed

Dependency-Directed Backtracking

- goal: recognize bad branching decisions quickly and do not repeat them

Dependency-Directed Backtracking

- goal: recognize bad branching decisions quickly and do not repeat them
- most frequently used: [backjumping](#)

Dependency-Directed Backtracking

- goal: recognize bad branching decisions quickly and do not repeat them
- most frequently used: **backjumping**
- backjumping works roughly as follows:
 - concepts in the node label are tagged with a set of integers (dependency set) allowing to identify the concept's "origin"
 - initially, all concepts are tagged with \emptyset
 - tableau rules combine and extend these tags
 - \sqcup -rule adds the tag $\{d\}$ to the existing tag, where d is the \sqcup -depth (number of \sqcup -rules applied by now)
 - when encountering a contradiction, the labels allow to identify the origin of the concepts causing the contradiction
 - jump back to the last **relevant** application of a \sqcup -rule

Dependency-Directed Backtracking

- goal: recognize bad branching decisions quickly and do not repeat them
- most frequently used: **backjumping**
- backjumping works roughly as follows:
 - concepts in the node label are tagged with a set of integers (dependency set) allowing to identify the concept's "origin"
 - initially, all concepts are tagged with \emptyset
 - tableau rules combine and extend these tags
 - \sqcup -rule adds the tag $\{d\}$ to the existing tag, where d is the \sqcup -depth (number of \sqcup -rules applied by now)
 - when encountering a contradiction, the labels allow to identify the origin of the concepts causing the contradiction
 - jump back to the last **relevant** application of a \sqcup -rule
- irrelevant part of the search space is not considered

Dependency-Directed Backtracking Example

$$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v) \quad \text{tagged with } \emptyset$$

Dependency-Directed Backtracking Example

$$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v) \quad \text{tagged with } \emptyset$$
$$v \quad \sqcap\text{-rule} \quad L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\} \quad \text{all with } \emptyset$$

Dependency-Directed Backtracking Example

$$\begin{array}{l}
 (C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v) \quad \text{tagged with } \emptyset \\
 v \quad \sqcap\text{-rule} \quad L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \\
 \qquad \qquad \qquad \exists r. \neg A, \forall r. A\} \quad \text{all with } \emptyset \\
 \quad \sqcup\text{-rule} \quad L(v) := L(v) \cup \{C_1\} \quad C_1 \text{ tagged with } \{1\} \\
 \quad \vdots \qquad \quad \vdots \qquad \quad \vdots \\
 \quad \sqcup\text{-rule} \quad L(v) := L(v) \cup \{C_n\} \quad C_n \text{ tagged with } \{n\}
 \end{array}$$

Dependency-Directed Backtracking Example

					$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$ tagged with \emptyset
v		\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$	all with \emptyset
		\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$	C_1 tagged with $\{1\}$
		\vdots	\vdots	\vdots	
		\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_n\}$	C_n tagged with $\{n\}$
		\exists -rule	$L(w) :=$	$\{\neg A\}$	A, r tagged with \emptyset
w	↓				

Dependency-Directed Backtracking Example

					$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$ tagged with \emptyset
v		\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$	all with \emptyset
		\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$	C_1 tagged with $\{1\}$
		\vdots	\vdots	\vdots	
		\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_n\}$	C_n tagged with $\{n\}$
		\exists -rule	$L(w) :=$	$\{\neg A\}$	A, r tagged with \emptyset
		\forall -rule	$L(w) :=$	$\{\neg A, A\}$	$\neg A$ tagged with mit \emptyset
w					

Dependency-Directed Backtracking Example

					$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$ tagged with \emptyset
v		\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$	all with \emptyset
		\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$	C_1 tagged with $\{1\}$
		\vdots	\vdots	\vdots	
		\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_n\}$	C_n tagged with $\{n\}$
		\exists -rule	$L(w) :=$	$\{\neg A\}$	A, r tagged with \emptyset
		\forall -rule	$L(w) :=$	$\{\neg A, A\}$ clash	$\neg A$ tagged with mit \emptyset
w					

Dependency-Directed Backtracking Example

		$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$		tagged with \emptyset
v \downarrow r \downarrow w	\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$	all with \emptyset
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$	C_1 tagged with $\{1\}$
	\vdots	\vdots	\vdots	
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_n\}$	C_n tagged with $\{n\}$
		\exists -rule	$L(w) := \{\neg A\}$	A, r tagged with \emptyset
		\forall -rule	$L(w) := \{\neg A, A\}$ clash	$\neg A$ tagged with mit \emptyset

- $\text{tag}(A) \cup \text{tag}(\neg A) = \emptyset$

Dependency-Directed Backtracking Example

$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$		tagged with \emptyset
v	\sqcap -rule $L(v) := L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$	all with \emptyset
\downarrow r	\sqcup -rule $L(v) := L(v) \cup \{C_1\}$	C_1 tagged with $\{1\}$
\vdots	\vdots	\vdots
\downarrow w	\sqcup -rule $L(v) := L(v) \cup \{C_n\}$	C_n tagged with $\{n\}$
	\exists -rule $L(w) := \{\neg A\}$	A, r tagged with \emptyset
	\forall -rule $L(w) := \{\neg A, A\}$	clash $\neg A$ tagged with mit \emptyset

- $\text{tag}(A) \cup \text{tag}(\neg A) = \emptyset$
- None of the \sqcup -rules has contributed to the cotradiction

Dependency-Directed Backtracking Example

		$(C_1 \sqcup D_1) \sqcap \dots \sqcap (C_n \sqcup D_n) \sqcap \exists r. \neg A \sqcap \forall r. A \in L(v)$		tagged with \emptyset
v \downarrow r \downarrow w	\sqcap -rule	$L(v) :=$	$L(v) \cup \{(C_1 \sqcup D_1), \dots, (C_n \sqcup D_n), \exists r. \neg A, \forall r. A\}$	all with \emptyset
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_1\}$	C_1 tagged with $\{1\}$
	\vdots	\vdots	\vdots	
	\sqcup -rule	$L(v) :=$	$L(v) \cup \{C_n\}$	C_n tagged with $\{n\}$
	\exists -rule	$L(w) :=$	$\{\neg A\}$	A, r tagged with \emptyset
	\forall -rule	$L(w) :=$	$\{\neg A, A\}$ clash	$\neg A$ tagged with mit \emptyset

- $\text{tag}(A) \cup \text{tag}(\neg A) = \emptyset$
- None of the \sqcup -rules has contributed to the cotradiction
- Output **false** (unsatisfiable)

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Further Optimizations

- Simplification and Normalization
 - quick recognition of trivial contradictions
 - normalization, z.B., $A \sqcap (B \sqcap C) \equiv \sqcap\{A, B, C\}$, $\forall r. C \equiv \neg \exists r. \neg C$
 - simplification, e.g., $\sqcap\{A, \dots, \neg A, \dots\} \equiv \perp$, $\exists r. \perp \equiv \perp$, $\forall r. \top \equiv \top$

Further Optimizations

- Simplification and Normalization
 - quick recognition of trivial contradictions
 - normalization, z.B., $A \sqcap (B \sqcap C) \equiv \sqcap\{A, B, C\}$, $\forall r. C \equiv \neg \exists r. \neg C$
 - simplification, e.g., $\sqcap\{A, \dots, \neg A, \dots\} \equiv \perp$, $\exists r. \perp \equiv \perp$, $\forall r. \top \equiv \top$
- caching
 - prevents the repeated construction of equal subtrees
 - $L(v)$ initialized with $\{C_1, \dots, C_n\}$ via \exists - and \forall -rules
 - check if satisfiability status is cached, otherwise
 - check satisfiability of $C_1 \sqcap \dots \sqcap C_n$, update the cache

Further Optimizations

- Simplification and Normalization
 - quick recognition of trivial contradictions
 - normalization, z.B., $A \sqcap (B \sqcap C) \equiv \sqcap\{A, B, C\}$, $\forall r. C \equiv \neg \exists r. \neg C$
 - simplification, e.g., $\sqcap\{A, \dots, \neg A, \dots\} \equiv \perp$, $\exists r. \perp \equiv \perp$, $\forall r. \top \equiv \top$
- caching
 - prevents the repeated construction of equal subtrees
 - $L(v)$ initialized with $\{C_1, \dots, C_n\}$ via \exists - and \forall -rules
 - check if satisfiability status is cached, otherwise
 - check satisfiability of $C_1 \sqcap \dots \sqcap C_n$, update the cache
- heuristics
 - try to find good orders for the “don’t care” nondeterminism
 - e.g., $\sqcap, \forall, \sqcup, \exists$

Further Optimizations

- Simplification and Normalization
 - quick recognition of trivial contradictions
 - normalization, z.B., $A \sqcap (B \sqcap C) \equiv \sqcap\{A, B, C\}$, $\forall r.C \equiv \neg\exists r.\neg C$
 - simplification, e.g., $\sqcap\{A, \dots, \neg A, \dots\} \equiv \perp$, $\exists r.\perp \equiv \perp$, $\forall r.\top \equiv \top$
- caching
 - prevents the repeated construction of equal subtrees
 - $L(v)$ initialized with $\{C_1, \dots, C_n\}$ via \exists - and \forall -rules
 - check if satisfiability status is cached, otherwise
 - check satisfiability of $C_1 \sqcap \dots \sqcap C_n$, update the cache
- heuristics
 - try to find good orders for the “don’t care” nondeterminism
 - e.g., $\sqcap, \forall, \sqcup, \exists$
- ...

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Optimizing Classification

One of the most wide-spread tasks for automated reasoning is **classification**

- compute all subclass relationships between atomic concepts in \mathcal{T}

Optimizing Classification

One of the most wide-spread tasks for automated reasoning is **classification**

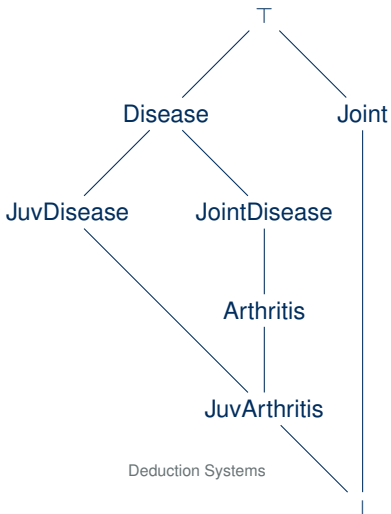
- compute all subclass relationships between atomic concepts in \mathcal{T}
- check for $\mathcal{T} \models C \sqsubseteq D$ can be reduced to checking satisfiability of \mathcal{T} together with the ABox $(C \sqcap \neg D)(a)$ (or, equivalently: $C(a), (\neg D)(a)$)
 - ↪ if \mathcal{T} is satisfiable: subsumption does not hold (as we have constructed a counter-model)
 - ↪ if \mathcal{T} is unsatisfiable: subsumption holds (no counter-model exists)

Optimizing Classification

One of the most wide-spread tasks for automated reasoning is **classification**

- compute all subclass relationships between atomic concepts in \mathcal{T}
- check for $\mathcal{T} \models C \sqsubseteq D$ can be reduced to checking satisfiability of \mathcal{T} together with the ABox $(C \sqcap \neg D)(a)$ (or, equivalently: $C(a), (\neg D)(a)$)
 - \rightsquigarrow if \mathcal{T} is satisfiable: subsumption does not hold (as we have constructed a counter-model)
 - \rightsquigarrow if \mathcal{T} is unsatisfiable: subsumption holds (no counter-model exists)
- naïve approach needs n^2 subsumption checks for n concept names
- normally cached in the **concept hierarchy** graph

Concept Hierarchy Graph



Optimizing Classification

most wide-spread technique is called [enhanced traversal](#)

Optimizing Classification

most wide-spread technique is called **enhanced traversal**

- hierarchy is created incrementally by introducing concept after concept

Optimizing Classification

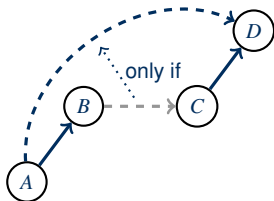
most wide-spread technique is called **enhanced traversal**

- hierarchy is created incrementally by introducing concept after concept
- top-down phase: recognize direct superconcepts
- bottom-up phase: recognize direct subconcepts

Optimizing Classification

most wide-spread technique is called **enhanced traversal**

- hierarchy is created incrementally by introducing concept after concept
- top-down phase: recognize direct superconcepts
- bottom-up phase: recognize direct subconcepts
- transitivity of \sqsubseteq used to save checks



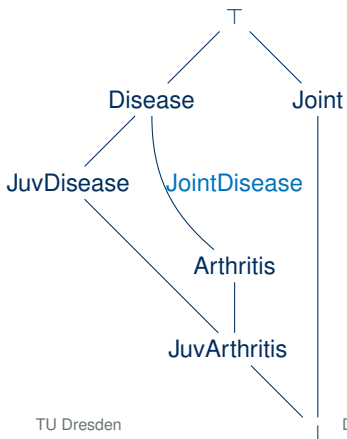
- If $A \sqsubseteq B$ and $C \sqsubseteq D$ hold,
- then $B \sqsubseteq C \rightarrow A \sqsubseteq D$
- and $A \not\sqsubseteq D \rightarrow B \not\sqsubseteq C$

Enhanced Traversal Example

already created hierarchy:

Goal: insertion of JointDisease

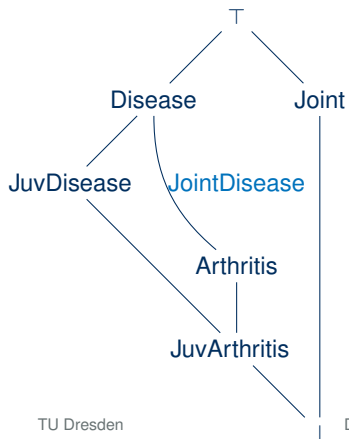
Top-Down Phase:



Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

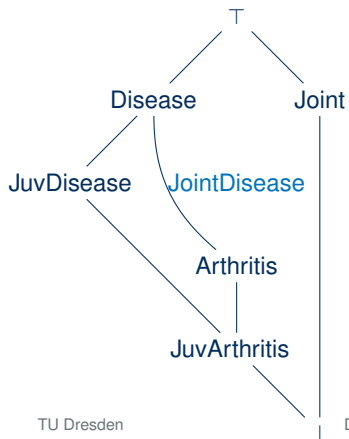
Top-Down Phase:

- $\text{JointDisease} \sqsubseteq^? \text{Disease}$

Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

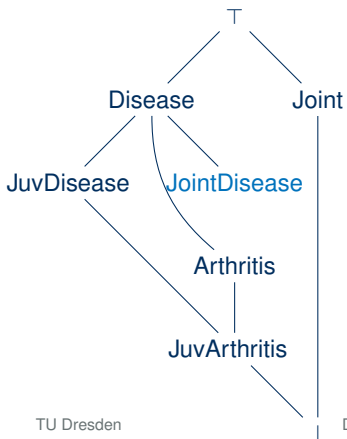
Top-Down Phase:

- $\text{JointDisease} \sqsubseteq \text{Disease}$
- $\text{JointDisease} \sqsubseteq^? \text{JuvDisease}$

Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

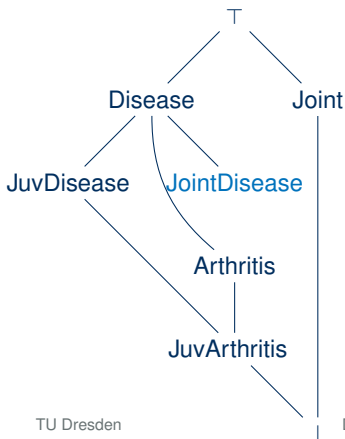
Top-Down Phase:

- $\text{JointDisease} \sqsubseteq \text{Disease}$
- $\text{JointDisease} \not\sqsubseteq \text{JuvDisease}$
- $\text{JointDisease} \sqsubseteq^? \text{Arthritis}$

Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

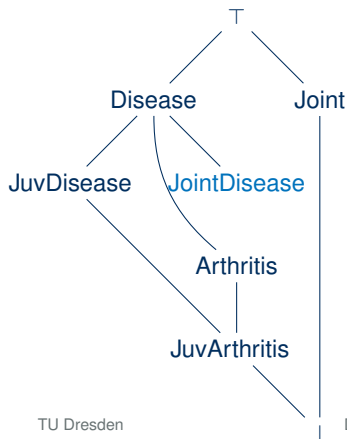
Top-Down Phase:

- $\text{JointDisease} \sqsubseteq \text{Disease}$
- $\text{JointDisease} \not\sqsubseteq \text{JuvDisease}$
- $\text{JointDisease} \not\sqsubseteq \text{Arthritis}$
- $\text{JointDisease} \sqsubseteq^? \text{Joint}$

Bottom-Up Phase:

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

Top-Down Phase:

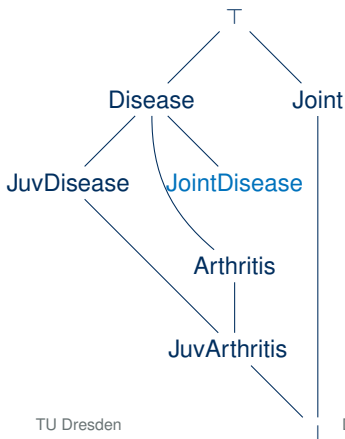
- $\text{JointDisease} \sqsubseteq \text{Disease}$
- $\text{JointDisease} \not\sqsubseteq \text{JuvDisease}$
- $\text{JointDisease} \not\sqsubseteq \text{Arthritis}$
- $\text{JointDisease} \not\sqsubseteq \text{Joint}$

Bottom-Up Phase:

- $\text{JuvArthritis} \sqsubseteq^? \text{JointDisease}$

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

Top-Down Phase:

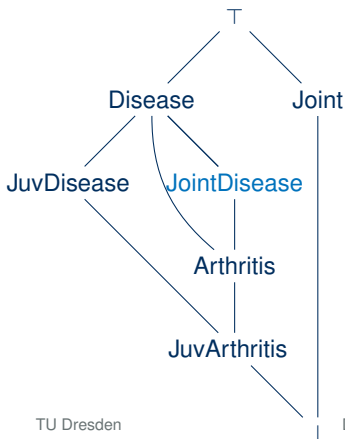
- $\text{JointDisease} \sqsubseteq \text{Disease}$
- $\text{JointDisease} \not\sqsubseteq \text{JuvDisease}$
- $\text{JointDisease} \not\sqsubseteq \text{Arthritis}$
- $\text{JointDisease} \not\sqsubseteq \text{Joint}$

Bottom-Up Phase:

- $\text{JuvArthritis} \sqsubseteq \text{JointDisease}$
- $\text{JuvDisease} \sqsubseteq^? \text{JointDisease}$

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

Top-Down Phase:

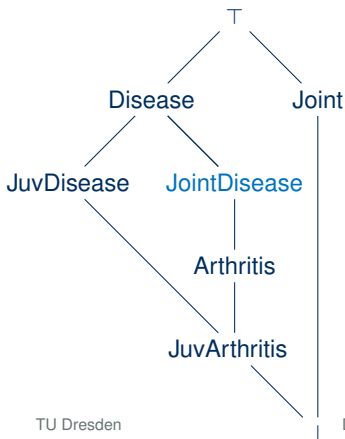
- $\text{JointDisease} \sqsubseteq \text{Disease}$
- $\text{JointDisease} \not\sqsubseteq \text{JuvDisease}$
- $\text{JointDisease} \not\sqsubseteq \text{Arthritis}$
- $\text{JointDisease} \not\sqsubseteq \text{Joint}$

Bottom-Up Phase:

- $\text{JuvArthritis} \sqsubseteq \text{JointDisease}$
- $\text{JuvDisease} \not\sqsubseteq \text{JointDisease}$
- $\text{Arthritis} \sqsubseteq^? \text{JointDisease}$

Enhanced Traversal Example

already created hierarchy:



Goal: insertion of JointDisease

Top-Down Phase:

- $\text{JointDisease} \sqsubseteq \text{Disease}$
- $\text{JointDisease} \not\sqsubseteq \text{JuvDisease}$
- $\text{JointDisease} \not\sqsubseteq \text{Arthritis}$
- $\text{JointDisease} \not\sqsubseteq \text{Joint}$

Bottom-Up Phase:

- $\text{JuvArthritis} \sqsubseteq \text{JointDisease}$
- $\text{JuvDisease} \not\sqsubseteq \text{JointDisease}$
- $\text{Arthritis} \sqsubseteq \text{JointDisease}$

Agenda

- Recap Tableau Calculus
- Optimizations
 - Unfolding
 - Absorption
 - Dependency-Directed Backtracking
 - Further Optimizations
- Classification
- Summary

Summary

- we have a tableau algorithm for \mathcal{ALCIF} knowledge bases
 - ABox treated like for \mathcal{ALC}
 - number restrictions are treated similar to functionality and existential quantifiers
- termination via cycle detection
 - becomes harder as the logic becomes more expressive
- naive tableau algorithm not sufficiently performant
- diverse optimizations improve average case
- specific methods for classification
 - enhanced traversal
- tableaux algorithms or variants modifications thereof are the basis of OWL reasoners