

# Answer Set Programming: Basics

Sebastian Rudolph

Computational Logic Group  
Technische Universität Dresden

Slides based on a lecture by Martin Gebser and Torsten Schaub.

Potassco Slide Packages are licensed under a Creative Commons Attribution 3.0  
Unported License.

# Answer Set Programming – Basics: Overview

- 1 Motivation: ASP vs. Prolog and SAT
- 2 ASP Syntax
- 3 Semantics
- 4 Examples
- 5 Variables
- 6 Reasoning modes

# Outline

- 1 Motivation: ASP vs. Prolog and SAT
- 2 ASP Syntax
- 3 Semantics
- 4 Examples
- 5 Variables
- 6 Reasoning modes

## KR's shift of paradigm

Theorem Proving based approach (eg. Prolog)

- 1 Provide a representation of the problem
- 2 A solution is given by a **derivation** of a query

Model Generation based approach (eg. SATisfiability testing)

- 1 Provide a representation of the problem
- 2 A solution is given by a **model** of the representation

## KR's shift of paradigm

### Theorem Proving based approach (eg. Prolog)

- 1 Provide a representation of the problem
- 2 A solution is given by a **derivation** of a query

### Model Generation based approach (eg. SATisfiability testing)

- 1 Provide a representation of the problem
- 2 A solution is given by a **model** of the representation

## LP-style playing with blocks

### Prolog program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- on(X,Y). above(X,Y) :- on(X,Z), above(Z,Y).
```

### Prolog queries

```
?- above(a,c). true.    ?- above(c,a). no.
```

## LP-style playing with blocks

### Prolog program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- on(X,Y). above(X,Y) :- on(X,Z), above(Z,Y).
```

### Prolog queries

```
?- above(a,c). true.    ?- above(c,a). no.
```

## LP-style playing with blocks

### Prolog program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- on(X,Y). above(X,Y) :- on(X,Z), above(Z,Y).
```

### Prolog queries

```
?- above(a,c). true.  ?- above(c,a). no.
```



## LP-style playing with blocks

### Prolog program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- on(X,Y). above(X,Y) :- on(X,Z), above(Z,Y).
```

### Prolog queries (testing entailment)

```
?- above(a,c). true. ?- above(c,a). no.
```

## LP-style playing with blocks

### Shuffled Prolog program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- above(X,Z), on(Z,Y). above(X,Y) :- on(X,Y).
```

### Prolog queries

```
?- above(a,c). Fatal Error: local stack overflow.
```

## LP-style playing with blocks

### Shuffled Prolog program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- above(X,Z), on(Z,Y). above(X,Y) :- on(X,Y).
```

### Prolog queries

```
?- above(a,c). Fatal Error: local stack overflow.
```

## LP-style playing with blocks

### Shuffled Prolog program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- above(X,Z), on(Z,Y). above(X,Y) :- on(X,Y).
```

### Prolog queries (answered via fixed execution)

```
?- above(a,c). Fatal Error: local stack overflow.
```

## KR's shift of paradigm

Theorem Proving based approach (eg. Prolog)

- 1 Provide a representation of the problem
- 2 A solution is given by a **derivation** of a query

Model Generation based approach (eg. SATisfiability testing)

- 1 Provide a representation of the problem
- 2 A solution is given by a **model** of the representation

## KR's shift of paradigm

Theorem Proving based approach (eg. Prolog)

- 1 Provide a representation of the problem
- 2 A solution is given by a **derivation** of a query

Model Generation based approach (eg. SATisfiability testing)

- 1 Provide a representation of the problem
- 2 A solution is given by a **model** of the representation

## SAT-style playing with blocks

### Formula

$$\begin{aligned}
 & on(a, b) \\
 \wedge & on(b, c) \\
 \wedge & (on(X, Y) \rightarrow above(X, Y)) \\
 \wedge & (on(X, Z) \wedge above(Z, Y) \rightarrow above(X, Y))
 \end{aligned}$$

### Herbrand model

$$\left\{ \begin{array}{l} on(a, b), \quad on(b, c), \quad on(a, c), \quad on(b, b), \\ above(a, b), \quad above(b, c), \quad above(a, c), \quad above(b, b), \quad above(c, b) \end{array} \right\}$$

## SAT-style playing with blocks

### Formula

$$\begin{aligned}
 & on(a, b) \\
 \wedge & on(b, c) \\
 \wedge & (on(X, Y) \rightarrow above(X, Y)) \\
 \wedge & (on(X, Z) \wedge above(Z, Y) \rightarrow above(X, Y))
 \end{aligned}$$

### Herbrand model

$$\left\{ \begin{array}{cccccc}
 on(a, b), & on(b, c), & on(a, c), & on(b, b), & & \\
 above(a, b), & above(b, c), & above(a, c), & above(b, b), & above(c, b) & 
 \end{array} \right\}$$



## SAT-style playing with blocks

## Formula

$$\begin{aligned}
 & on(a, b) \\
 \wedge & on(b, c) \\
 \wedge & (on(X, Y) \rightarrow above(X, Y)) \\
 \wedge & (on(X, Z) \wedge above(Z, Y) \rightarrow above(X, Y))
 \end{aligned}$$

## Herbrand model (among 426!)

$$\left\{ \begin{array}{cccccc}
 on(a, b), & on(b, c), & on(a, c), & on(b, b), & & \\
 above(a, b), & above(b, c), & above(a, c), & above(b, b), & above(c, b) & 
 \end{array} \right\}$$

## SAT-style playing with blocks

## Formula

$$\begin{aligned}
 & on(a, b) \\
 \wedge & on(b, c) \\
 \wedge & (on(X, Y) \rightarrow above(X, Y)) \\
 \wedge & (on(X, Z) \wedge above(Z, Y) \rightarrow above(X, Y))
 \end{aligned}$$

## Herbrand model (among 426!)

$$\left\{ \begin{array}{llllll}
 on(a, b), & on(b, c), & on(a, c), & on(b, b), & & \\
 above(a, b), & above(b, c), & above(a, c), & above(b, b), & above(c, b) & 
 \end{array} \right\}$$

## SAT-style playing with blocks

## Formula

$$\begin{aligned}
 & on(a, b) \\
 \wedge & on(b, c) \\
 \wedge & (on(X, Y) \rightarrow above(X, Y)) \\
 \wedge & (on(X, Z) \wedge above(Z, Y) \rightarrow above(X, Y))
 \end{aligned}$$

## Herbrand model (among 426!)

$$\left\{ \begin{array}{cccccc}
 on(a, b), & on(b, c), & on(a, c), & on(b, b), & & \\
 above(a, b), & above(b, c), & above(a, c), & above(b, b), & above(c, b) & 
 \end{array} \right\}$$

## KR's shift of paradigm

Theorem Proving based approach (eg. Prolog)

- 1 Provide a representation of the problem
- 2 A solution is given by a **derivation** of a query

Model Generation based approach (eg. SATisfiability testing)

- 1 Provide a representation of the problem
- 2 A solution is given by a **model** of the representation

## KR's shift of paradigm

Theorem Proving based approach (eg. Prolog)

- 1 Provide a representation of the problem
- 2 A solution is given by a **derivation** of a query

Model Generation based approach (eg. SATisfiability testing)

- 1 Provide a representation of the problem
- 2 A solution is given by a **model** of the representation

➡ **Answer Set Programming (ASP)**

## ASP-style playing with blocks

### Logic program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- on(X,Y). above(X,Y) :- on(X,Z), above(Z,Y).
```

### Stable Herbrand model

```
{ on(a,b), on(b,c), above(b,c), above(a,b), above(a,c) }
```

## ASP-style playing with blocks

### Logic program

`on(a,b) . on(b,c) .`

`above(X,Y) :- on(X,Y) . above(X,Y) :- on(X,Z) , above(Z,Y) .`

### Stable Herbrand model

`{ on(a,b), on(b,c), above(b,c), above(a,b), above(a,c) }`

## ASP-style playing with blocks

### Logic program

`on(a,b). on(b,c).`

`above(X,Y) :- on(X,Y). above(X,Y) :- on(X,Z), above(Z,Y).`

### Stable Herbrand model (and no others)

`{ on(a,b), on(b,c), above(b,c), above(a,b), above(a,c) }`



## ASP-style playing with blocks

### Logic program

```
on(a,b). on(b,c).
```

```
above(X,Y) :- above(Z,Y), on(X,Z). above(X,Y) :- on(X,Y).
```

### Stable Herbrand model (and no others)

```
{ on(a,b), on(b,c), above(b,c), above(a,b), above(a,c) }
```

## ASP versus LP

ASP	Prolog
Model generation	Query orientation
Bottom-up	Top-down
Modeling language	Programming language
Rule-based format	
Instantiation	Unification
Flat terms	Nested terms
(Turing +) $NP(NP)$	Turing

## ASP versus SAT

ASP	SAT
Model generation	
Bottom-up	
Constructive Logic	Classical Logic
Closed (and open) world reasoning	Open world reasoning
Modeling language	—
Complex reasoning modes	Satisfiability testing
Satisfiability	Satisfiability
Enumeration/Projection	—
Intersection/Union	—
Optimization	—
(Turing +) $NP(NP)$	$NP$

## What is ASP good for?

- Combinatorial search problems in the realm of  $P$ ,  $NP$ , and  $NP^{NP}$  (some with substantial amount of data), like
  - Automated Planning
  - Code Optimization
  - Composition of Renaissance Music
  - Database Integration
  - Decision Support for NASA shuttle controllers
  - Model Checking
  - Product Configuration
  - Robotics
  - Systems Biology
  - System Synthesis
  - (industrial) Team-building
  - and many many more

## What is ASP good for?

- Combinatorial search problems in the realm of  $P$ ,  $NP$ , and  $NP^{NP}$  (some with substantial amount of data), like
  - Automated Planning
  - Code Optimization
  - Composition of Renaissance Music
  - Database Integration
  - Decision Support for NASA shuttle controllers
  - Model Checking
  - Product Configuration
  - Robotics
  - Systems Biology
  - System Synthesis
  - (industrial) Team-building
  - and many many more

# Outline

- 1 Motivation: ASP vs. Prolog and SAT
- 2 ASP Syntax**
- 3 Semantics
- 4 Examples
- 5 Variables
- 6 Reasoning modes

## Normal logic programs

- A **logic program**,  $P$ , over a set  $\mathcal{A}$  of atoms is a finite **set** of rules
- A (normal) **rule**,  $r$ , is of the form

$$a_0 \leftarrow a_1, \dots, a_m, \sim a_{m+1}, \dots, \sim a_n$$

where  $0 \leq m \leq n$  and each  $a_i \in \mathcal{A}$  is an atom for  $0 \leq i \leq n$

### Notation

$$\text{head}(r) = a_0$$

$$\text{body}(r) = \{a_1, \dots, a_m, \sim a_{m+1}, \dots, \sim a_n\}$$

$$\text{body}(r)^+ = \{a_1, \dots, a_m\}$$

$$\text{body}(r)^- = \{a_{m+1}, \dots, a_n\}$$

$$\text{atom}(P) = \bigcup_{r \in P} (\{\text{head}(r)\} \cup \text{body}(r)^+ \cup \text{body}(r)^-)$$

$$\text{body}(P) = \{\text{body}(r) \mid r \in P\}$$

- A program  $P$  is **positive** if  $\text{body}(r)^- = \emptyset$  for all  $r \in P$

## Normal logic programs

- A **logic program**,  $P$ , over a set  $\mathcal{A}$  of atoms is a finite **set** of rules
- A (normal) **rule**,  $r$ , is of the form

$$a_0 \leftarrow a_1, \dots, a_m, \sim a_{m+1}, \dots, \sim a_n$$

where  $0 \leq m \leq n$  and each  $a_i \in \mathcal{A}$  is an atom for  $0 \leq i \leq n$

- **Notation**

$$\text{head}(r) = a_0$$

$$\text{body}(r) = \{a_1, \dots, a_m, \sim a_{m+1}, \dots, \sim a_n\}$$

$$\text{body}(r)^+ = \{a_1, \dots, a_m\}$$

$$\text{body}(r)^- = \{a_{m+1}, \dots, a_n\}$$

$$\text{atom}(P) = \bigcup_{r \in P} (\{\text{head}(r)\} \cup \text{body}(r)^+ \cup \text{body}(r)^-)$$

$$\text{body}(P) = \{\text{body}(r) \mid r \in P\}$$

- A program  $P$  is **positive** if  $\text{body}(r)^- = \emptyset$  for all  $r \in P$



## Normal logic programs

- A **logic program**,  $P$ , over a set  $\mathcal{A}$  of atoms is a finite **set** of rules
- A (normal) **rule**,  $r$ , is of the form

$$a_0 \leftarrow a_1, \dots, a_m, \sim a_{m+1}, \dots, \sim a_n$$

where  $0 \leq m \leq n$  and each  $a_i \in \mathcal{A}$  is an atom for  $0 \leq i \leq n$

- **Notation**

$$\text{head}(r) = a_0$$

$$\text{body}(r) = \{a_1, \dots, a_m, \sim a_{m+1}, \dots, \sim a_n\}$$

$$\text{body}(r)^+ = \{a_1, \dots, a_m\}$$

$$\text{body}(r)^- = \{a_{m+1}, \dots, a_n\}$$

$$\text{atom}(P) = \bigcup_{r \in P} (\{\text{head}(r)\} \cup \text{body}(r)^+ \cup \text{body}(r)^-)$$

$$\text{body}(P) = \{\text{body}(r) \mid r \in P\}$$

- A program  $P$  is **positive** if  $\text{body}(r)^- = \emptyset$  for all  $r \in P$

## Rough notational convention

We sometimes use the following notation interchangeably in order to stress the respective view:

	true, false	if	and	or	iff	default negation	classical negation
source code		<code>:-</code>	<code>,</code>	<code> </code>		<code>not</code>	<code>-</code>
logic program		<code>←</code>	<code>,</code>	<code>;</code>		<code>~</code>	<code>¬</code>
formula	$\top, \perp$	$\rightarrow$	$\wedge$	$\vee$	$\leftrightarrow$	$\sim$	$\neg$

# Outline

- 1 Motivation: ASP vs. Prolog and SAT
- 2 ASP Syntax
- 3 Semantics**
- 4 Examples
- 5 Variables
- 6 Reasoning modes

## Formal Definition

### Stable models of positive programs

- A set of atoms  $X$  is **closed under** a positive program  $P$  iff for any  $r \in P$ ,  $head(r) \in X$  whenever  $body(r)^+ \subseteq X$ 
  - $X$  corresponds to a model of  $P$  (seen as a formula)
- The **smallest** set of atoms which is closed under a positive program  $P$  is denoted by  $Cn(P)$ 
  - $Cn(P)$  corresponds to the  $\subseteq$ -smallest model of  $P$  (ditto)
- The set  $Cn(P)$  of atoms is the **stable model** of a *positive program*  $P$

## Formal Definition

### Stable models of positive programs

- A set of atoms  $X$  is **closed under** a positive program  $P$  iff for any  $r \in P$ ,  $head(r) \in X$  whenever  $body(r)^+ \subseteq X$ 
  - $X$  corresponds to a model of  $P$  (seen as a formula)
- The **smallest** set of atoms which is closed under a positive program  $P$  is denoted by  $Cn(P)$ 
  - $Cn(P)$  corresponds to the  $\subseteq$ -smallest model of  $P$  (ditto)
- The set  $Cn(P)$  of atoms is the **stable model** of a *positive program*  $P$

## Formal Definition

### Stable models of positive programs

- A set of atoms  $X$  is **closed under** a positive program  $P$  iff for any  $r \in P$ ,  $head(r) \in X$  whenever  $body(r)^+ \subseteq X$ 
  - $X$  corresponds to a model of  $P$  (seen as a formula)
- The **smallest** set of atoms which is closed under a positive program  $P$  is denoted by  $Cn(P)$ 
  - $Cn(P)$  corresponds to the  $\subseteq$ -smallest model of  $P$  (ditto)
- The set  $Cn(P)$  of atoms is the **stable model** of a *positive program*  $P$

## Formal Definition

### Stable models of positive programs

- A set of atoms  $X$  is **closed under** a positive program  $P$  iff for any  $r \in P$ ,  $head(r) \in X$  whenever  $body(r)^+ \subseteq X$ 
  - $X$  corresponds to a model of  $P$  (seen as a formula)
- The **smallest** set of atoms which is closed under a positive program  $P$  is denoted by  $Cn(P)$ 
  - $Cn(P)$  corresponds to the  $\subseteq$ -smallest model of  $P$  (ditto)
- The set  $Cn(P)$  of atoms is the **stable model** of a *positive program*  $P$

## Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$\{p, q\}$ ,  $\{q, r\}$ , and  $\{p, q, r\}$

$$\Phi \quad q \wedge (q \wedge \neg r \rightarrow p)$$

Informally, a set  $K$  of atoms is a *stable model* of a logic program  $P$  iff  $K$  is a (classical) model of  $P$  and  
 • all atoms in  $K$  are justified by some rule in  $P$ .  
 (rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))



## Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$\{p, q\}$ ,  $\{q, r\}$ , and  $\{p, q, r\}$

$$\Phi \quad \boxed{q \wedge (q \wedge \neg r \rightarrow p)}$$

Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

## Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$\{p, q\}$ ,  $\{q, r\}$ , and  $\{p, q, r\}$

$$\Phi \quad \boxed{q \wedge (q \wedge \neg r \rightarrow p)}$$

Formula  $\Phi$  has one stable model, often called answer set.

$p$	$\mapsto$	1
$q$	$\mapsto$	1
$r$	$\mapsto$	0

Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

## Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$\{p, q\}$ ,  $\{q, r\}$ , and  $\{p, q, r\}$

Formula  $\Phi$  has one stable model,  
often called answer set:

$\{p, q\}$

$$\Phi \quad \boxed{q \wedge (q \wedge \neg r \rightarrow p)}$$

$$P_{\Phi} \quad \boxed{\begin{array}{l} q \leftarrow \\ p \leftarrow q, \sim r \end{array}}$$

Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

## Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$$\{p, q\}, \{q, r\}, \text{ and } \{p, q, r\}$$

Formula  $\Phi$  has one stable model, often called **answer set**:

$$\{p, q\}$$

$$\Phi \quad \boxed{q \wedge (q \wedge \neg r \rightarrow p)}$$

$$P_\Phi \quad \boxed{\begin{array}{l} q \leftarrow \\ p \leftarrow q, \sim r \end{array}}$$

Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

## Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$$\{p, q\}, \{q, r\}, \text{ and } \{p, q, r\}$$

Formula  $\Phi$  has one stable model, often called answer set:

$$\{p, q\}$$

$$\Phi \quad \boxed{q \wedge (q \wedge \neg r \rightarrow p)}$$

$$P_\Phi \quad \boxed{\begin{array}{l} q \leftarrow \\ p \leftarrow q, \sim r \end{array}}$$

Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

## Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$$\{p, q\}, \{q, r\}, \text{ and } \{p, q, r\}$$

Formula  $\Phi$  has one stable model, often called answer set:

$$\{p, q\}$$

Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

$$\Phi \quad \boxed{q \wedge (q \wedge \neg r \rightarrow p)}$$

$$P_\Phi \quad \boxed{\begin{array}{l} q \leftarrow \\ p \leftarrow q, \sim r \end{array}}$$

## Basic idea

Consider the logical formula  $\Phi$  and its three (classical) models:

$\{p, q\}$ ,  $\{q, r\}$ , and  $\{p, q, r\}$

Formula  $\Phi$  has one stable model, often called answer set:

$\{p, q\}$

$\Phi$   $q \wedge (q \wedge \neg r \rightarrow p)$

$P_\Phi$   $q \leftarrow$   
 $p \leftarrow q, \sim r$

Informally, a set  $X$  of atoms is a **stable model** of a logic program  $P$

- if  $X$  is a (classical) model of  $P$  and
- if all atoms in  $X$  are **justified** by some rule in  $P$

(rooted in intuitionistic logics HT (Heyting, 1930) and G3 (Gödel, 1932))

## Formal Definition

### Stable model of normal programs

- The **reduct**,  $P^X$ , of a program  $P$  relative to a set  $X$  of atoms is defined by

$$P^X = \{ \text{head}(r) \leftarrow \text{body}(r)^+ \mid r \in P \text{ and } \text{body}(r)^- \cap X = \emptyset \}$$

- A set  $X$  of atoms is a **stable model** of a program  $P$ , if  $Cn(P^X) = X$
- Note  $Cn(P^X)$  is the  $\subseteq$ -smallest (classical) model of  $P^X$
- Note Every atom in  $X$  is justified by an *“applying rule from  $P$ ”*



## Formal Definition

### Stable model of normal programs

- The **reduct**,  $P^X$ , of a program  $P$  relative to a set  $X$  of atoms is defined by

$$P^X = \{ \text{head}(r) \leftarrow \text{body}(r)^+ \mid r \in P \text{ and } \text{body}(r)^- \cap X = \emptyset \}$$

- A set  $X$  of atoms is a **stable model** of a program  $P$ , if  $Cn(P^X) = X$
- Note  $Cn(P^X)$  is the  $\subseteq$ -smallest (classical) model of  $P^X$
- Note Every atom in  $X$  is justified by an *“applying rule from  $P$ ”*

## Formal Definition

### Stable model of normal programs

- The **reduct**,  $P^X$ , of a program  $P$  relative to a set  $X$  of atoms is defined by

$$P^X = \{ \text{head}(r) \leftarrow \text{body}(r)^+ \mid r \in P \text{ and } \text{body}(r)^- \cap X = \emptyset \}$$

- A set  $X$  of atoms is a **stable model** of a program  $P$ , if  $Cn(P^X) = X$
- **Note**  $Cn(P^X)$  is the  $\subseteq$ -smallest (classical) model of  $P^X$
- **Note** Every atom in  $X$  is justified by an “*applying rule from  $P$* ”

A closer look at  $P^X$ 

- In other words, given a set  $X$  of atoms from  $P$ ,

$P^X$  is obtained from  $P$  by **deleting**

- 1 each **rule** having  $\sim a$  in its body with  $a \in X$  and then
- 2 all **negative atoms** of the form  $\sim a$  in the bodies of the remaining rules

- Note Only negative body literals are evaluated wrt  $X$

A closer look at  $P^X$ 

- In other words, given a set  $X$  of atoms from  $P$ ,

$P^X$  is obtained from  $P$  by deleting

- 1 each rule having  $\sim a$  in its body with  $a \in X$  and then
  - 2 all negative atoms of the form  $\sim a$  in the bodies of the remaining rules
- Note Only **negative body literals** are evaluated wrt  $X$

# Outline

- 1 Motivation: ASP vs. Prolog and SAT
- 2 ASP Syntax
- 3 Semantics
- 4 Examples**
- 5 Variables
- 6 Reasoning modes

## A first example

$$P = \{p \leftarrow p, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$
$\{p\}$	$p \leftarrow p$	$\emptyset$
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$
$\{p, q\}$	$p \leftarrow p$	$\emptyset$

## A first example

$$P = \{p \leftarrow p, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ ✗
$\{p\}$	$p \leftarrow p$	$\emptyset$ ✗
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ ✓
$\{p, q\}$	$p \leftarrow p$	$\emptyset$ ✗

## A first example

$$P = \{p \leftarrow p, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ ✗
$\{p\}$	$p \leftarrow p$	$\emptyset$ ✗
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ ✓
$\{p, q\}$	$p \leftarrow p$	$\emptyset$ ✗



## A first example

$$P = \{p \leftarrow p, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <span style="color: red;">✗</span>
$\{p\}$	$p \leftarrow p$	$\emptyset$ <span style="color: red;">✗</span>
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <span style="color: green;">✓</span>
$\{p, q\}$	$p \leftarrow p$	$\emptyset$ <span style="color: red;">✗</span>

## A first example

$$P = \{p \leftarrow p, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <span style="color: red;">✗</span>
$\{p\}$	$p \leftarrow p$	$\emptyset$ <span style="color: red;">✗</span>
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <span style="color: green;">✓</span>
$\{p, q\}$	$p \leftarrow p$	$\emptyset$ <span style="color: red;">✗</span>

## A first example

$$P = \{p \leftarrow p, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <b>x</b>
$\{p\}$	$p \leftarrow p$	$\emptyset$ <b>x</b>
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <b>✓</b>
$\{p, q\}$	$p \leftarrow p$	$\emptyset$ <b>x</b>

## A first example

$$P = \{p \leftarrow p, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <b>x</b>
$\{p\}$	$p \leftarrow p$	$\emptyset$ <b>x</b>
$\{q\}$	$p \leftarrow p$ $q \leftarrow$	$\{q\}$ <b>✓</b>
$\{p, q\}$	$p \leftarrow p$	$\emptyset$ <b>x</b>

## A second example

$$P = \{p \leftarrow \sim q, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow$ $q \leftarrow$	$\{p, q\}$ ✗
$\{p\}$	$p \leftarrow$	$\{p\}$
$\{q\}$	$q \leftarrow$	$\{q\}$
$\{p, q\}$		$\emptyset$

## A second example

$$P = \{p \leftarrow \sim q, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow$ $q \leftarrow$	$\{p, q\}$ ✗
$\{p\}$	$p \leftarrow$	$\{p\}$ ✓
$\{q\}$	$q \leftarrow$	$\{q\}$ ✓
$\{p, q\}$		$\emptyset$

## A second example

$$P = \{p \leftarrow \sim q, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow$ $q \leftarrow$	$\{p, q\}$ ✖
$\{p\}$	$p \leftarrow$	$\{p\}$ ✔
$\{q\}$	$q \leftarrow$	$\{q\}$ ✔
$\{p, q\}$		$\emptyset$

## A second example

$$P = \{p \leftarrow \sim q, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow$ $q \leftarrow$	$\{p, q\}$ ✖
$\{p\}$	$p \leftarrow$	$\{p\}$ ✔
$\{q\}$	$q \leftarrow$	$\{q\}$ ✔
$\{p, q\}$		$\emptyset$



## A second example

$$P = \{p \leftarrow \sim q, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow$ $q \leftarrow$	$\{p, q\}$ ✗
$\{p\}$	$p \leftarrow$	$\{p\}$ ✓
$\{q\}$	$q \leftarrow$	$\{q\}$ ✓
$\{p, q\}$		$\emptyset$

## A second example

$$P = \{p \leftarrow \sim q, q \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{ \}$	$p \leftarrow$ $q \leftarrow$	$\{p, q\}$ ✗
$\{p\}$	$p \leftarrow$	$\{p\}$ ✓
$\{q\}$	$q \leftarrow$	$\{q\}$ ✓
$\{p, q\}$		$\emptyset$ ✗

## A third example

$$P = \{p \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{\}$	$p \leftarrow$	$\{p\}$ ✖
$\{p\}$		$\emptyset$

## A third example

$$P = \{p \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{\}$	$p \leftarrow$	$\{p\}$ <span style="color: red;">✗</span>
$\{p\}$		$\emptyset$

## A third example

$$P = \{p \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{\}$	$p \leftarrow$	$\{p\}$ <b>x</b>
$\{p\}$		$\emptyset$

## A third example

$$P = \{p \leftarrow \sim p\}$$

$X$	$P^X$	$Cn(P^X)$
$\{\}$	$p \leftarrow$	$\{p\}$ <b>X</b>
$\{p\}$		$\emptyset$ <b>X</b>

## Some properties

- A logic program may have zero, one, or multiple stable models!
- If  $X$  is a stable model of a logic program  $P$ , then  $X$  is a model of  $P$  (seen as a formula)
- If  $X$  and  $Y$  are stable models of a *normal* program  $P$ , then  $X \not\subseteq Y$

## Some properties

- A logic program may have zero, one, or multiple stable models!
- If  $X$  is a stable model of a logic program  $P$ , then  $X$  is a model of  $P$  (seen as a formula)
- If  $X$  and  $Y$  are stable models of a *normal* program  $P$ , then  $X \not\subseteq Y$



# Outline

- 1 Motivation: ASP vs. Prolog and SAT
- 2 ASP Syntax
- 3 Semantics
- 4 Examples
- 5 Variables**
- 6 Reasoning modes

## Programs with Variables

Let  $P$  be a logic program

- Let  $\mathcal{T}$  be a set of (variable-free) **terms**
- Let  $\mathcal{A}$  be a set of (variable-free) **atoms** constructable from  $\mathcal{T}$
- Ground Instances of  $r \in P$ : Set of variable-free rules obtained by replacing all variables in  $r$  by elements from  $\mathcal{T}$ :

$$ground(r) = \{r\theta \mid \theta : var(r) \rightarrow \mathcal{T} \text{ and } var(r\theta) = \emptyset\}$$

where  $var(r)$  stands for the set of all variables occurring in  $r$ ;  
 $\theta$  is a (ground) substitution

- **Ground Instantiation** of  $P$ :  $ground(P) = \bigcup_{r \in P} ground(r)$

## Programs with Variables

Let  $P$  be a logic program

- Let  $\mathcal{T}$  be a set of variable-free **terms** (also called **Herbrand universe**)
- Let  $\mathcal{A}$  be a set of (variable-free) **atoms** constructable from  $\mathcal{T}$  (also called **alphabet** or **Herbrand base**)
- Ground Instances of  $r \in P$ : Set of variable-free rules obtained by replacing all variables in  $r$  by elements from  $\mathcal{T}$ :

$$\mathit{ground}(r) = \{r\theta \mid \theta : \mathit{var}(r) \rightarrow \mathcal{T} \text{ and } \mathit{var}(r\theta) = \emptyset\}$$

where  $\mathit{var}(r)$  stands for the set of all variables occurring in  $r$ ;  
 $\theta$  is a (ground) substitution

- **Ground Instantiation** of  $P$ :  $\mathit{ground}(P) = \bigcup_{r \in P} \mathit{ground}(r)$

## Programs with Variables

Let  $P$  be a logic program

- Let  $\mathcal{T}$  be a set of (variable-free) terms
- Let  $\mathcal{A}$  be a set of (variable-free) atoms constructable from  $\mathcal{T}$
- **Ground Instances** of  $r \in P$ : Set of variable-free rules obtained by replacing all variables in  $r$  by elements from  $\mathcal{T}$ :

$$\mathit{ground}(r) = \{r\theta \mid \theta : \mathit{var}(r) \rightarrow \mathcal{T} \text{ and } \mathit{var}(r\theta) = \emptyset\}$$

where  $\mathit{var}(r)$  stands for the set of all variables occurring in  $r$ ;  
 $\theta$  is a (ground) substitution

- **Ground Instantiation** of  $P$ :  $\mathit{ground}(P) = \bigcup_{r \in P} \mathit{ground}(r)$

## Programs with Variables

Let  $P$  be a logic program

- Let  $\mathcal{T}$  be a set of (variable-free) terms
- Let  $\mathcal{A}$  be a set of (variable-free) atoms constructable from  $\mathcal{T}$
- Ground Instances of  $r \in P$ : Set of variable-free rules obtained by replacing all variables in  $r$  by elements from  $\mathcal{T}$ :

$$\mathit{ground}(r) = \{r\theta \mid \theta : \mathit{var}(r) \rightarrow \mathcal{T} \text{ and } \mathit{var}(r\theta) = \emptyset\}$$

where  $\mathit{var}(r)$  stands for the set of all variables occurring in  $r$ ;  
 $\theta$  is a (ground) substitution

- **Ground Instantiation** of  $P$ :  $\mathit{ground}(P) = \bigcup_{r \in P} \mathit{ground}(r)$

## An example

$$P = \{ r(a, b) \leftarrow, r(b, c) \leftarrow, t(X, Y) \leftarrow r(X, Y) \}$$

$$\mathcal{T} = \{a, b, c\}$$

$$\mathcal{A} = \left\{ \begin{array}{l} r(a, a), r(a, b), r(a, c), r(b, a), r(b, b), r(b, c), r(c, a), r(c, b), r(c, c), \\ t(a, a), t(a, b), t(a, c), t(b, a), t(b, b), t(b, c), t(c, a), t(c, b), t(c, c) \end{array} \right\}$$

$$\text{ground}(P) = \left\{ \begin{array}{l} r(a, b) \leftarrow, \\ r(b, c) \leftarrow, \\ t(a, a) \leftarrow r(a, a), t(b, a) \leftarrow r(b, a), t(c, a) \leftarrow r(c, a), \\ t(a, b) \leftarrow r(a, b), t(b, b) \leftarrow r(b, b), t(c, b) \leftarrow r(c, b), \\ t(a, c) \leftarrow r(a, c), t(b, c) \leftarrow r(b, c), t(c, c) \leftarrow r(c, c) \end{array} \right\}$$

• Intelligent Grounding aims at reducing the ground instantiation

## An example

$$P = \{ r(a, b) \leftarrow, r(b, c) \leftarrow, t(X, Y) \leftarrow r(X, Y) \}$$

$$\mathcal{T} = \{a, b, c\}$$

$$\mathcal{A} = \left\{ \begin{array}{l} r(a, a), r(a, b), r(a, c), r(b, a), r(b, b), r(b, c), r(c, a), r(c, b), r(c, c), \\ t(a, a), t(a, b), t(a, c), t(b, a), t(b, b), t(b, c), t(c, a), t(c, b), t(c, c) \end{array} \right\}$$

$$\text{ground}(P) = \left\{ \begin{array}{l} r(a, b) \leftarrow, \\ r(b, c) \leftarrow, \\ t(a, a) \leftarrow r(a, a), t(b, a) \leftarrow r(b, a), t(c, a) \leftarrow r(c, a), \\ t(a, b) \leftarrow r(a, b), t(b, b) \leftarrow r(b, b), t(c, b) \leftarrow r(c, b), \\ t(a, c) \leftarrow r(a, c), t(b, c) \leftarrow r(b, c), t(c, c) \leftarrow r(c, c) \end{array} \right\}$$

- Intelligent Grounding aims at reducing the ground instantiation

## An example

$$P = \{ r(a, b) \leftarrow, r(b, c) \leftarrow, t(X, Y) \leftarrow r(X, Y) \}$$

$$\mathcal{T} = \{a, b, c\}$$

$$\mathcal{A} = \left\{ \begin{array}{l} r(a, a), r(a, b), r(a, c), r(b, a), r(b, b), r(b, c), r(c, a), r(c, b), r(c, c), \\ t(a, a), t(a, b), t(a, c), t(b, a), t(b, b), t(b, c), t(c, a), t(c, b), t(c, c) \end{array} \right\}$$

$$\text{ground}(P) = \left\{ \begin{array}{l} r(a, b) \leftarrow, \\ r(b, c) \leftarrow, \\ t(a, a) \leftarrow r(a, a), t(b, a) \leftarrow r(b, a), t(c, a) \leftarrow r(c, a), \\ t(a, b) \leftarrow r(a, b), t(b, b) \leftarrow r(b, b), t(c, b) \leftarrow r(c, b), \\ t(a, c) \leftarrow r(a, c), t(b, c) \leftarrow r(b, c), t(c, c) \leftarrow r(c, c) \end{array} \right\}$$

- **Intelligent Grounding** aims at reducing the ground instantiation



## Stable models of programs with Variables

Let  $P$  be a normal logic program with variables

- A set  $X$  of (**ground**) atoms is a **stable model** of  $P$ ,  
if  $Cn(\text{ground}(P)^X) = X$

## Stable models of programs with Variables

Let  $P$  be a normal logic program with variables

- A set  $X$  of (**ground**) atoms is a **stable model** of  $P$ ,  
if  $Cn(\mathit{ground}(P)^X) = X$

# Outline

- 1 Motivation: ASP vs. Prolog and SAT
- 2 ASP Syntax
- 3 Semantics
- 4 Examples
- 5 Variables
- 6 Reasoning modes**

# Reasoning Modes

- Satisfiability
- Enumeration<sup>†</sup>
- Projection<sup>†</sup>
- Intersection<sup>‡</sup>
- Union<sup>‡</sup>
- Optimization
- and combinations of them

<sup>†</sup> without solution recording

<sup>‡</sup> without solution enumeration