

# SAT Problems

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- **Propositional Logic**
- Semantics
- **Propositional SAT Problems**
- **Conjunctive Normal Form**
- Resolution
- Examples



"Logic is everywhere ..."

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# **Propositional Logic**

- Definition An alphabet of propositional logic consists of
  - ▷ a (countably) infinite set R of propositional variables
  - $\triangleright\,$  the set {¬/1, ^/2,  $\vee$ /2,  $\rightarrow$ /2,  $\leftrightarrow$ /2} of connectives and
  - the special characters "(" and ")"
- ·/n denotes the arity of ·
- Different alphabets of propositional logic differ in R and, hence, alphabets are usually specified by specifying R
- In this lecture,  $\mathcal{R}$  is usually  $\mathbb{N}^+$



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# **Propositional Formulas**

- **Definition** An atomic formula, briefly called atom, is a propositional variable
- ▶ Definition The set of propositional formulas is the smallest set L(R) of strings over an alphabet R of propositional logic with the following properties:
  - 1 If *F* is an atomic formula then  $F \in \mathcal{L}(\mathcal{R})$
  - 2 If  $F \in \mathcal{L}(\mathcal{R})$  then  $\neg F \in \mathcal{L}(\mathcal{R})$
  - 3 If  $\circ/2$  is a binary connective and  $F, G \in \mathcal{L}(\mathcal{R})$  then  $(F \circ G) \in \mathcal{L}(\mathcal{R})$
- Definition A literal is an atom or a negated atom; The complement L of a literal L is defined as follows:
  - ▶ If *L* is an atom *A* then  $\overline{L} = \neg A$
  - ▶ if *L* is a negated atom  $\neg A$  then  $\overline{L} = A$
  - A pair L,  $\overline{L}$  of literals is said to be complementary





### **Notations and Conventions**

- A (possibly indexed) denotes an atom
  - . (possibly indexed) denotes a literal
  - F, G, H (possibly indexed) denote propositional formulas
  - $\mathcal{F}, \mathcal{G}, \mathcal{H}$  denote sets of propositional formulas
- ▶ It is sometimes convenient to write -n instead of  $\neg n$ , where  $n \in \mathbb{N}^+$
- Let S be a set of literals
  - $\triangleright \overline{\mathbf{S}} = \{\overline{L} \mid L \in \mathbf{S}\}$
  - $\triangleright$  **S** is sometimes called the complement of **S**

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## **Semantics**

- The set of truth values is the set  $\{\top, \bot\}$
- We consider the following functions on  $\{\top, \bot\}$ :
  - ▷ Negation ¬\*/1
  - ▷ Conjunction ∧\*/2
  - ▷ Disjunction ∨\*/2
  - ▷ Implication  $\rightarrow^*/2$
  - $\triangleright$  Equivalence  $\leftrightarrow^*/2$

		¬*	$\wedge^*$	V*	$\rightarrow^*$	$\leftrightarrow^*$
Т	T	1	Т	Т	Т	Т
T		1		T		
	T	T		Т	Т	1
	$\bot$	T		上	Т	Т





### Interpretations

▶ Definition An interpretation / consists of the set  $\{\top, \bot\}$ and a mapping  $\cdot^{I} : \mathcal{L}(\mathcal{R}) \to \{\top, \bot\}$  with:

$$[F]' = \begin{cases} \neg^*[G]' & \text{if } F \text{ is of the form } \neg G \\ ([G_1]' \circ^* [G_2]') & \text{if } F \text{ is of the form } (G_1 \circ G_2) \end{cases}$$

- Given  $F \in \mathcal{L}(\mathcal{R})$
- ▶ Let  $\mathcal{R}_F = \{A \in \mathcal{R} \mid A \text{ occurs in } F\}$  and  $n = |\mathcal{R}_F|$
- ▶ Definition Two interpretations *I* and *J* are equal for *F*, in symbols  $I \simeq_F J$ , iff for all  $A \in \mathcal{R}_F$  we find  $A^I = A^J$
- Proposition ≃<sub>F</sub> is an equivalence relation defining 2<sup>n</sup> different equivalence classes on the set of all interpretations of L(R)
- For each of the equivalence classes defined by ≃<sub>F</sub> we can choose as representative the interpretation *I* with A<sup>I</sup> = ⊥ for all A ∈ R \ R<sub>F</sub>
- Such an interpretation I is called an interpretation for F
- The set of interpretations for F is finite; its cardinality is 2<sup>n</sup>





### Models

- ▶ Definition An interpretation *I* for *F* is called model for *F* ( $I \models F$ ) iff  $[F]^I = \top$ 
  - Definition

     F is satisfiable
     F is unsatisfiable
     F is valid
     F is valid
     F is falsifiable
     F is falsifiable
- ▶ Definition An interpretation *I* is called model for a set *G* of formulas (*I* ⊨ *G*) iff *I* is a model for all *F* ∈ *G*
- The notions of satisfiability, unsatisfiability, validity and falsifiability can be extended to sets of formulas in the obvious way





# **Representation of Interpretations**

An interpretation I for F is uniquely defined by specifying how I acts on R<sub>F</sub>

▷ *I* can be represented by a sequence  $\hat{i}$  of literals from  $\mathcal{R}_F \cup \overline{\mathcal{R}_F}$  such that  $L \in \hat{i}$  iff  $L^I = \top$ 

- Note
  - I is a mapping

î does not contain a complementary pair of literals

I is a total mapping

**For each**  $A \in \mathcal{R}_F$  either  $A \in \hat{I}$  or  $\overline{A} \in \hat{I}$  but not both

> In the sequel, we will identify *I* with  $\hat{I}$ .

▶ Definition Let *J* be a sequence of literals from *R<sub>F</sub>* ∪ *R<sub>F</sub>* such that *J* does not contain a complementary pair; *J* is a partial interpretation for *F* iff there is an *A* ∈ *R<sub>F</sub>* such that neither *A* ∈ *J* nor *A* ∈ *J* 





# **Some Additional Notations and Conventions**

- I and J (possibly indexed) denote (partial) interpretations
- We often write F<sup>1</sup> instead of [F]<sup>1</sup>
- ▶ We define the following precedence hierarchy among connectives:

 $\neg\succ\{\lor,\,\land\}\succ\rightarrow\succ\,\leftrightarrow$ 

- We sometimes omit parentheses taking into account that conjunction and disjunction are associative and commutative
- Let J be a (partial) interpretation for F and C a disjunction of literals
  - $\triangleright$  J satisfies C (J  $\models$  C) iff J contains a literal occurring as disjunct in C
  - ▷ J falsifies C ( $J \not\models C$ ) iff for each disjunct L of C we find  $\overline{L} \in J$
- Let J be a sequence of literals; It it sometimes convenient to represent J in the form I', L, I, where L is a literal occurring in J and I', I are the subsequences occurring in J before and after L, respectively





# **Propositional Satisfiability Problems**

- ▶ Definition A propositional satisfiability problem, briefly called SAT, consists of a formula  $F \in \mathcal{L}(\mathcal{R})$ , and is the problem to decide whether *F* is satisfiable
- SAT is a combinatorial decision problem
  - Decision variant yes/no answer
  - Search variant find a model if F is satisfiable
  - > All models variant find all models if F is satisfiable





SAT Problems

# **A Simple SAT Instance**

► Let 
$$F = 1$$
  
 $\land (1 \lor 2)$   
 $\land (1 \to 3)$   
 $\land (1 \land 3 \to 4]$   
 $\land (5 \lor 6)$   
 $\land (5 \to 7)$   
 $\land (\overline{5} \lor 8)$   
 $\land (\overline{7} \lor \overline{8})$ 

- (1, 2, 3, 4,  $\overline{5}$ , 6,  $\overline{7}$ ,  $\overline{8}$ ) is a model for F
- ▶ Hence, F is satisfiable
- ▶ How can we find such a model?





### Model Finding – First Ideas

▶ Reconsider F = 1  $C_1$   $\land (1 \lor 2)$   $C_2$   $\land (1 \to 3)$   $C_3$   $\land (1 \land 3 \to 4)$   $C_4$   $\land (5 \lor 6)$   $C_5$   $\land (5 \to 7)$   $C_6$   $\land (\overline{5} \lor 8)$   $C_7$  $\land (\overline{7} \lor \overline{8})$   $C_8$ 

Idea

Initialize J := ()and add literals to Jsuch that  $J \models C_i$ for all  $1 \le i \le 8$ 

- ▷ Because  $C_1$  we set J := (1) and thus  $J \models C_1$ .
- ▷ Because  $1 \in J$  we find  $J \models C_2$ .
- ▷ Because  $1 \in J$  and  $C_3$  we set J := (1, 3) and thus  $J \models C_3$
- ▷ Because 1, 3  $\in$  J and C<sub>4</sub> we set J := (1, 3, 4), and thus J  $\models$  C<sub>4</sub>
- ▷ None of  $C_5 C_8$  forces the addition of a literal; we choose J := (1, 3, 4, 5)
- ▶ Because  $5 \in J$  we find  $J \models C_5$
- ▷ Because 5  $\in$  J and C<sub>6</sub> we set J := (1.3.4, 5, 7), and thus J  $\models$  C<sub>6</sub>
- ▷ Because 5  $\in$  J and C<sub>7</sub> we set J := (1, 3, 4, 5, 7, 8) and thus J  $\models$  C<sub>7</sub>
- ▷ Because 7, 8  $\in$  J we find J  $\not\models$  C<sub>8</sub>; we have a conflict





### Model Finding – First Ideas Continued

► Reconsider 
$$F = 1$$
  
 $\land (1 \lor 2)$   
 $\land (1 \to 3)$   
 $\land (1 \land 3 \to 4)$   
 $\land (5 \lor 6)$   
 $\land (5 \to 7)$   
 $\land (\overline{5} \lor 8)$   
 $\land (\overline{7} \lor \overline{8}).$   
 $C_1$   
 $C_2$   
 $\land (1 \to 3)$   
 $C_3$   
 $\land (1 \land 3 \to 4)$   
 $C_4$   
 $\land (\overline{5} \lor 8)$   
 $C_7$   
 $\land (\overline{7} \lor \overline{8}).$   
 $C_8$ 

- ▷ Recall J := (1, 3, 4, 5, 7, 8) has led to a conflict
- ▶ We backtrack and set  $J := (1, 3, 4, \overline{5})$
- ▷ Because  $\overline{5} \in J$  and  $C_5$  we set  $J := (1, 3, 4, \overline{5}, 6)$  and thus  $J \models C_5$
- ▷ Because  $\overline{5} \in J$  we find  $J \models C_6$  and  $J \models C_7$
- ▷ In order to satisfy  $C_8$  we choose  $J := (1, 3, 4, \overline{5}, 6, \overline{7})$  and thus  $J \models C_8$
- J is turned into a total interpretation by adding 2, 8; the choice was arbitrary; we could have added 2, 8 or 2, 8 or 2, 8





# **Remarks and Notational Conventions**

- Literals marked with a dot are called decision literals all others are called propagation literals
- If J is a partial interpretation then J, L is the interpretation obtained by addingL to J
  - $\triangleright$  Note *J*, *L* may be total





### **Decision Levels**

Partial interpretations will sometimes be written in the form

$$P_0, \dot{L_1}, P_1, \ldots, \dot{L_k}, P_k,$$

where  $P_i$ ,  $1 \le i \le k$ , are sequences of propagation literals

- The decision literals partition the elements of the interpretation into decision levels
- ▶ Literals occurring in L<sub>i</sub>, P<sub>i</sub> are assigned decision level i
- Likewise,

denotes a partial interpretation, where

- ▷ J is a partial interpretation
- L is decision literal and
- > P is a sequence of propagation literals

Note that  $\dot{L}$  is the decision literal with the highest level in  $J, \dot{L}, P$ 





# **Subformulas**

- ▶ Definition Let *F* be a propositional formula; The set of subformulas of *F* is the smallest set of formulas *S*(*F*) satisfying the following conditions:
  - 1.  $F \in \mathcal{S}(F)$
  - 2. If  $\neg G \in \mathcal{S}(F)$ , then  $G \in \mathcal{S}(F)$
  - 3. If  $G_1 \circ G_2 \in \mathcal{S}(F)$ , then  $G_1, G_2 \in \mathcal{S}(F)$
- ► Example

$$\begin{aligned} \mathcal{S}(\neg((p_1 \to p_2) \lor p_1)) \\ &= \{ \neg((p_1 \to p_2) \lor p_1), \ ((p_1 \to p_2) \lor p_1), \ (p_1 \to p_2), \ p_1, \ p_2 \} \end{aligned}$$



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### Semantic Equivalence

F

- ▶ Definition Two propositional formulas *F* and *G* are semantically equivalent, in symbols  $F \equiv G$ , iff for all interpretations *I* we have:  $I \models F$  iff  $I \models G$
- ▶ Theorem Some equivalence laws:

¬¬ <b>F</b>	≡	F	double negation
$ egreen (F \land G) \  egreen (F \lor G)$			de Morgan
		$(F \land G) \lor (F \land H)$ $(F \lor G) \land (F \lor H)$	distributivity
$F\leftrightarrow G$	≡	$(F \land G) \lor (\neg G \land \neg F)$	equivalence
${\it F}  ightarrow {\it G}$	≡	$ eg {m F} ee {m G}$	implication
		F, if F is valid G, if F is valid	tautology
		<i>G</i> , if <i>F</i> is unsatisfiable <i>F</i> , if <i>F</i> is unsatisfiable	unsatisfiability





# Replacement

- F[G → H] denotes the formula obtained from F by replacing an occurrence of G ∈ S(F) by H
  - Usually, the context determines which occurrence is meant
  - ▷ Sometimes the condition  $G \in S(F)$  is omitted In this case, if  $G \notin S(F)$ , then  $F \lceil G \mapsto H \rceil = F$
- ▶ Replacement Theorem If  $G \equiv H$  then  $F[G \mapsto H] \equiv F$

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# **Generalized Disjunctions and Conjunctions**

- Generalized disjunction  $[F_1, \ldots, F_n] := F_1 \lor \ldots \lor F_n$
- Generalized conjunction  $\langle F_1, \ldots, F_n \rangle := F_1 \land \ldots \land F_n$
- **•** Empty generalized disjunction [] with [] $^{I} = \bot$  for all I
- **Empty generalized conjunction**  $\langle \rangle$  with  $\langle \rangle^I = \top$  for all *I*
- ▶ Note  $n \land \overline{n}$  is unsatisfiable, whereas  $n \lor \overline{n}$  is valid, where  $n \in \mathbb{N}^+$
- ▶ Notation We consider () and [] as abbreviations for  $1 \vee \overline{1}$  and  $1 \wedge \overline{1}$ , resp.

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# **Clauses and Conjunctive Normal Forms**

#### Definition

- ▷ A clause is a generalized disjunction  $[L_1, ..., L_n]$ ,  $n \ge 0$ , where every  $L_i$ ,  $1 \le i \le n$ , is a literal
- > A clause is a Horn clause if at most one disjunct is an atom
- A clause is a unit clause if it contains precisely one literal
- ▶ A clause is a binary clause if it contains precisely two literals

### Definition

- ▷ A formula is in conjunctive normal form (clause form, CNF) iff it is of the form  $\langle C_1, \ldots, C_m \rangle$ ,  $m \ge 0$ , and every  $C_j$ ,  $1 \le j \le m$ , is a clause
- ▶ A formula *F* in CNF is a Horn formula if it contains only Horn clauses
- A formula F in CNF is said to be in *n*-CNF if each clause occurring in F has at most *n* literals





### **More Notations and Conventions**

- C (possibly indexed) denotes a clause
- C, L and F, C denote C ∨ L and F ∧ C, respectively, where C is a clause and F a CNF-formula
- Clauses and CNF-formulas are sometimes considered as sets of literals and clauses, respectively, in which case
  - ▷  $L_i$ ,  $1 \le i \le n$ , are said to be elements of  $[L_1, \ldots, L_n]$  and

▷  $C_j$ , 1 ≤ j ≤ m, are said to be elements of  $\langle C_1, \ldots, C_m \rangle$ 

Note that in sets duplicates are removed!

It should be clear from the context whether clauses and CNF-formulas are considered as sets or generalized disjunctions and conjunctions, respectively

When writing C = C', L we do not suppose that L is the "last" literal occurring in C but some literal occurring in C and C' is the disjunction or set of the "remaining" literals occurring in C

A similar convention applies to F = F', C





# **The Function lits**

▶ Let lits be the following function from the set of clauses to the set of literals

$$\mathsf{lits}(C) = \begin{cases} \emptyset & \text{if } C = []\\ \mathsf{lits}(C') \cup \{L\} & \text{if } C = C', L \end{cases}$$

▶ It is extended to a function from the set of CNF-formulas to the set of literals

$$\mathsf{lits}(F) = \begin{cases} \emptyset & \text{if } F = \langle \rangle \\ \mathsf{lits}(F') \cup \mathsf{lits}(C). & \text{if } F = F', C \end{cases}$$

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# **The Function atoms**

Let atoms be the following function from the set of literals to the set of atoms

$$\operatorname{atoms}(L) = \begin{cases} \{A\} & \text{if } L = A \\ \{A\} & \text{if } L = \neg A \end{cases}$$

It is extended to a function from the set of clauses to the set of atoms

$$\operatorname{atoms}(C) = \begin{cases} \emptyset & \text{if } C = []\\ \operatorname{atoms}(C') \cup \operatorname{atoms}(L) & \text{if } C = C', L \end{cases}$$

It is extended to a function from the set of CNF-formulas to the set of atoms

$$\operatorname{atoms}(F) = \begin{cases} \emptyset & \text{if } F = \langle \rangle \\ \operatorname{atoms}(F') \cup \operatorname{atoms}(C) & \text{if } F = F', C \end{cases}$$



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### **Transformation into Clause Form**

- ► Theorem There is an algorithm which transforms any propositional formula into a semantically equivalent formula in clause form
- Observation
  - All equivalences can be eliminated using the law

$$F \leftrightarrow G \equiv (F \wedge G) \vee (\neg F \wedge \neg G)$$

- F and G are copied which may lead to a combinatorial explosion!
- Construct a sequence of examples demonstrating this explosion
- All implications can be eliminated using the law

$$F \rightarrow G \equiv \neg F \lor G$$

 $\triangleright$  Hence, we assume that only the connectives  $\neg$ ,  $\land$  and  $\lor$  occur in formulas





# An Algorithm for the Transformation into Clause Form

Input A propositional formula F
 Output A formula, which is in conjunctive normal form and is equivalent to F
 G := <[F]> (G is a conjunction of disjunctions)
 While G is not in conjunctive normal form do:
 Select a non-clausal element H from G
 Select a non-literal element K from H
 Apply the rule among the following ones which is applicable

$$\frac{\neg \neg D}{D} \quad \frac{(D_1 \land D_2)}{D_1 \mid D_2} \quad \frac{\neg (D_1 \land D_2)}{\neg D_1, \neg D_2} \quad \frac{(D_1 \lor D_2)}{D_1, D_2} \quad \frac{\neg (D_1 \lor D_2)}{\neg D_1 \mid \neg D_2}$$

- A rule  $\frac{D}{D'}$  is applicable to K if K is of the form D If applied, then K is replaced by D'
- ► A rule D<sub>1|D2</sub> is applicable to K if K is of the form D If applied, H is replaced by two disjunctions The first one is obtained from H by replacing the occurrence of D by D<sub>1</sub> The second one is obtained from H by replacing the occurrence of D by D<sub>2</sub>



# An Example

- Let  $F = p \land (p \rightarrow q) \rightarrow q$
- F is valid
- Eliminating implications yields

$$\neg(p \land (\neg p \lor q)) \lor q$$

Applying the algorithm yields

**b** Both clauses in the final formula contain a complementary pair of literals





# **Remarks**

- An application of a rule of the form  $\frac{D}{D_1|D_2}$  may lead to copies of subformulas
  - > May this lead to a combinatorial explosion?
  - If this is the case,
    - then construct a sequence of examples showing the explosion
  - If this is not the case, then prove it





### **Definitional Transformation**

- The size of a formula may grow exponentially during normalization
- Can we do better?
  - ▷ Unfortunately, the shortest CNF of some F is exponential in the size of F
  - Luckily, we may use a weaker concept
- Definitional transformation Tseitin: On the complexity of derivation in propositional calculus. Leningrad Seminar on Mathematical Logic, 1970
  - ▶ Let *F* be a formula,  $G \in S(F)$  and  $p \notin S(F)$  a propositional variable
  - ▷ Replace F by  $F [G \mapsto p] \land (p \leftrightarrow G)$
- Some observations
  - $\triangleright \ \ F \not\equiv F \lceil G \mapsto p \rceil \land (p \leftrightarrow G)$
  - ▷ *F* is satisfiable iff  $F[G \mapsto p] \land (p \leftrightarrow G)$  is satisfiable (equi-satisfiable)
  - > The previously mentioned exponential growth can be avoided





### **Reduct of a CNF-Formula**

- ▶ Definition Let F be a CNF-formula and J a partial interpretation. The reduct of F wrt J (F|J) is obtained by applying the following transformations to F: For all L ∈ J do
  - Remove all clauses in F which contain L
  - Remove all occurrences of L
- Let F be the following formula:

 $\langle [1], [1, 2], [\overline{1}, 3], [\overline{1}, \overline{3}, 4], [5, 6], [\overline{5}, 7], [\overline{5}, 8], [\overline{7}, \overline{8}] \rangle$ 

#### Then,





# **Reduct of a Clause**

- ▶ Definition Let C be a clause and J be a (partial or total) interpretation. The reduct of C wrt J, in symbols C|J, is
  - $\triangleright \langle \rangle \text{ if } \boldsymbol{C} \cap \boldsymbol{J} \neq \emptyset$
  - ▷ the clause obtained from C by removing all occurrences of  $\overline{L}$  for all  $L \in J$





# Conflicts

- **Definition** Let *F* be a CNF-formula and *J* a (partial or total) interpretation for *F* 
  - ▷ J satisfies F (in symbols,  $J \models F$ ) iff  $F|_J$  is empty
  - ▷ J falsifies F (in symbols,  $J \not\models F$ ) iff  $F|_J$  contains the empty clause; In this case, J is sometimes called conflict for F





# **Propositional Resolution**

- In the following clauses are considered to be sets
- ▶ Definition Let C₁ be a clause containing L and C₂ be a clause containing L̄; The (propositional) resolvent of C₁ and C₂ with respect to L is the clause

 $(C_1 \setminus \{L\}) \cup (C_2 \setminus \{\overline{L}\})$ 

*C* is said to be a resolvent of  $C_1$  and  $C_2$  iff there exists a literal *L* such that *C* is the resolvent of  $C_1$  and  $C_2$  wrt *L* 





# **Linear Resolution Derivations**

- ▶ Definition Let *C*, *D* be clauses and *F* a set of formulas
  - ▷ A linear resolution derivation from *C* wrt  $\mathcal{F}$  is a sequence  $(D_i | i \ge 0)$  of clauses such that

 $\blacktriangleright$   $D_0 = C$  and

- ▶  $D_i$  is a resolvent of  $D_{i-1}$  and some  $E \in \mathcal{F}$  for all i > 0
- $\triangleright$  A linear resolution derivation from C to D wrt  $\mathcal{F}$  is
  - ▶ a finite linear resolution derivation  $(D_i | 0 \le i \le n)$  from C wrt  $\mathcal{F}$
  - such that D<sub>n</sub> = D



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# **Example: Sudoku Puzzles**

- ▶ Let  $n \in \mathbb{N}$ ; A Sudoku puzzle
  - ▷ consists of an  $n^2 \times n^2$  grid
  - $\triangleright$  made up of  $n \times n$  subgrids called blocks
  - ▷ with some integers from [1, n<sup>2</sup>] placed in some cells
  - where some of these placements are predefined

#### ▶ The problem is

- ▷ to assign  $i \in [1, n^2]$  to each cell of the grid such that
- each row, column and block contains exactly one occurrence of each integer in [1, n<sup>2</sup>]
- There are more than 6 × 10<sup>12</sup> 3-Sudoku puzzles
- Sudoku puzzles with n > 3 appear to be difficult to solve for humans





# A Simple 3-Sudoku

+	++	+
4	2 3 9	
- 8 -	5 - 6	
9	8 - 4	- 6 -
+	++	+
5 7 1		946
8		3
2 3 9		781
+	++	+
	4 - 8	7
3	9 - 7	- 1 -
	1 2 3	4
+	++	+



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# A SAT Encoding of *n*-Sudokus (1)

- (x, y, v) represents the fact that value v is in the cell x, y
- ▶ Definedness Each cell contains one element of [1, n<sup>2</sup>]

$$\bigwedge_{x=1}^{n^2}\bigwedge_{y=1}^{n^2}\bigvee_{v=1}^{n^2}(x,y,v)$$

▶ Uniqueness for Cells Each cell has at most one value

$$\bigwedge_{x=1}^{n^2}\bigwedge_{y=1}^{n^2-1}\bigwedge_{w=1}^{n^2}((x,y,v)\to\neg(x,y,w))$$

▶ Uniqueness for Rows All numbers in [1, n<sup>2</sup>] must occur in every row

$$\bigwedge^{n^2} \bigwedge^{n^2-1} \bigwedge^{n^2-1} \bigwedge^{n^2} \bigwedge^{n^2-1} ((x, y, v) \to \neg (x, w, v))$$





# A SAT Encoding of *n*-Sudokus (2)

**•** Uniqueness for Columns All numbers in  $[1, n^2]$  must occur in every column

$$\bigwedge_{y=1}^{n^2}\bigwedge_{\nu=1}^{n^2}\bigwedge_{x=1}^{n^2-1}\bigwedge_{w=x+1}^{n^2}((x,y,\nu)\to\neg(w,y,\nu))$$

▶ Uniqueness for Blocks All numbers in [1, *n*<sup>2</sup>] must occur in every block

$$\bigwedge_{i=0}^{n-1} \bigwedge_{j=0}^{n-i} \bigwedge_{x=n \cdot i+1}^{n \cdot i+n} \bigwedge_{y=n \cdot j+1}^{n \cdot j+n} \bigwedge_{v=1}^{n^2-1} \bigwedge_{w=v+1}^{n^2} ((x, y, v) \to \neg (x, y, w))$$

► Claim Let *F* be the set of formulas encoding a Sudoku puzzle Each model for *F* specifies a solution for the puzzle





# **Example: Planning**

- Situation Calculus
- A Simple Planning Language
- Planning as Satisfiability Testing
- Solving Planning Problems





# **Situation Calculus**

- Situation calculus based planning as deduction McCarthy, Hayes: Some Philosophical Problems from the Standpoint of Artificial Intelligence. In: Machine Intelligence 4, Meltzer and Michie eds., Edinburgh University Press, 463-502: 1969
  - General properties of causality, and certain obvious but until now unformalized facts about the possibility and results of actions, are given as axioms
  - ▶ It is a logical consequence of the facts of a situation and the general axioms that certain persons can achieve certain goals by taking certain actions
  - ▶ Block *a* is on block *b* after performing action move(*a*, *b*) in state *s*<sub>1</sub>

 $on(a, b, result(move(a, b), s_1))$ 

Inherently first-order







# Planning as Satisfiability Testing

- We are interested only in finite plans containing no more than a given number of actions
  - A restricted approach which is equivalent to a finite propositional system
  - Planning as satisfiability testing instead of planning as deduction Kautz, Selman: Planning as Satisfiability.
     In: Proceedings 10th European Conference on Artificial Intelligence, 359-363: 1992





# A Simple Planning Language

- We will use schemas to denote finite sets of propositional formulas
- A schema is a function-free typed predicate logic formula with equality
  - Two types: block and time
  - > Each type contains a finite set of individuals denoted by unique constants
    - **b** table, *a*, *b*, ... are constants of type block
    - The set constants of type time is a finite set of integers [1, n]
  - > The precedence order is extended to

$$\neg \ \succ \ \{\lor, \ \land\} \ \succ \rightarrow \succ \leftrightarrow \succ \{\forall, \ \exists\}$$

- ▷ X, Y, ... denote variables of type block
- ▷ *T* denotes a variable of type time ranging over [1, n 1]*T'* denotes a variable of type time ranging over [1, n]
- ▷ Arithmetic expressions like *T* + 1 are interpreted when schemas are written in full





## **Predicates**

- on(X, Y, T) denotes that block X is on top of block Y at time T
- clear(X, T) denotes that block X is clear at time T
- ▶ move(X, Y, Z, T) denotes that X is moved from the top of Y to the top of Z between T and T + 1
- $\blacktriangleright$  X = Y denotes that X and Y are the same block





# **Equality Constraints**

Equalities

 $\{a = a \mid a \text{ is a constant of type block}\}$ 

Inequalities

 $\{a \neq b \mid a \text{ and } b \text{ are two different constants of type block}\}$ 





# **Initial and Goal Conditions**

- ▶ Let [1, *n*] be the range of integers
  - ▷ *n* states *s*<sub>1</sub>,..., *s*<sub>n</sub>
  - ▷ n-1 actions  $a_1, \ldots, a_{n-1}$  with  $a_i$  leading from  $s_i$  to  $s_{i+1}, 1 \le i \le n-1$
- Initial conditions are formulas in which only 1 appears as term of type time
  - ▷ on(a, b, 1)  $\land$  on(b, table, 1)  $\land$  clear(a, 1)
- Goal conditions are formulas in which only n appears as term of type time
  - ▷ With n = 3 we may consider on(b, a, 3)

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# **Domain Constraints**

- ▶ The table is always clear  $(\forall T')$  clear(table, T')
- A block except the table cannot be clear and support a block at the same time

 $(\forall X, Y, T') (Y \neq \text{table} \rightarrow \neg(\text{clear}(Y, T') \land \text{on}(X, Y, T')))$ 

- ▶ A block cannot be on itself  $(\forall X, T') \neg on(X, X, T')$
- ▶ The table cannot be on another block  $(\forall Y, T') \neg on(table, Y, T')$
- A block can only be on one block

 $(\forall X, Y_1, Y_2, T')$  (on $(X, Y_1, T') \land$  on $(X, Y_2, T') \rightarrow Y_1 = Y_2$ )

A block except the table can support only one block

 $(\forall X_1, X_2, Y, T') (Y \neq \text{table} \land \text{on}(X_1, Y, T') \land \text{on}(X_2, Y, T') \rightarrow X_1 = X_2)$ 



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### **Action Axioms**

#### Move X from Y to Z

$$\begin{array}{l} (\forall X, Y, Z, T)(\text{on}(X, Y, T) \land \text{clear}(X, T) \land \text{clear}(Z, T) \\ \land X \neq Y \land X \neq Z \land Y \neq Z \land X \neq \text{table} \\ \land \operatorname{move}(X, Y, Z, T) \\ \to \operatorname{on}(X, Z, T+1) \land \operatorname{clear}(Y, T+1)) \end{array}$$

Actions are only executed if their preconditions hold

$$\begin{array}{l} (\forall X, Y, Z, T)(\mathsf{move}(X, Y, Z, T)) \\ \rightarrow \quad \mathsf{clear}(X, T) \land \mathsf{clear}(Z, T) \land \mathsf{on}(X, Y, T)) \\ \land X \neq Y \land X \neq Z \land Y \neq Z \land X \neq \mathsf{table} \end{array}$$



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# **More Action Axioms**

Only one actions occurs at a time

 $(\forall X_1, X_2, Y_1, Y_2, Z_1, Z_2, T) (move(X_1, Y_1, Z_1, T) \land move(X_2, Y_2, Z_2, T) \\ \rightarrow X_1 = X_2 \land Y_1 = Y_2 \land Z_1 = Z_2 )$ 

Some action occurs at every time

 $(\forall T)(\exists X, Y, Z) \operatorname{move}(X, Y, Z, T)$ 



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#### **Frame Axioms**

A clear block which is not covered as a result of a move action stays clear

$$(\forall X_1, X_2, Y, Z, T)(\operatorname{clear}(X_2, T) \land \operatorname{move}(X_1, Y, Z, T)) \land X_2 \neq Y \land X_2 \neq Z \\ \rightarrow \operatorname{clear}(X_2, T + 1))$$

A block stays on top of another one if it is not moved

 $(\forall X_1, X_2, Y_1, Y_2, Z, T) (on(X_2, Y_2, T) \land move(X_1, Y_1, Z, T) \land X_1 \neq X_2 \\ \rightarrow on(X_2, Y_2, T+1))$ 



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# Planning as Satisfiability Testing

#### ▶ Let *A* be a set of action axioms,

- $\mathcal{F}$  be a set of frame axioms,
- $\mathcal{D}$  be a set of domain axioms,
- $\mathcal{E}$  be a set of equality axioms,
- S be an initial condition,
- G be a goal condition,

then a planning problem is the question of whether

```
\mathcal{A} \cup \mathcal{F} \cup \mathcal{D} \cup \mathcal{E} \cup \{\mathbf{S}, \mathbf{G}\}
```

has a model



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# Example

- ▶ Let *a*, *b*, table be all constants of type block
- ▶ Let [1, 3] be all constants of type time
- Consider the planning problem

 $\mathcal{A} \cup \mathcal{F} \cup \mathcal{D} \cup \mathcal{E} \cup \{\mathsf{on}(a, b, 1) \land \mathsf{on}(b, \mathsf{table}, 1) \land \mathsf{clear}(a, 1), \mathsf{on}(b, a, 3)\}$ 

It has only one model (written as set instead of sequence)

```
{ on(a, b, 1), on(b, table, 1), clear(a, 1), move(a, b, table, 1),
on(a, table, 2), on(b, table, 2), clear(a, 2), clear(b, 2), move(b, table, a, 2),
on(a, table, 3), on(b, a, 3), clear(b, 3)}
\cup {clear(table, i) | 1 ≤ i ≤ 3} \cup \mathcal{E}
```

We can extract the plan

```
move(a, b, table, 1) \land move(b, table, a, 2)
```





## Remarks

Let  $\mathcal{G}$  be the specification of a planning problem

- ▶ Is *G* correct?
- What is the meaning of "correct" in this context?
- If we consider (McCarthy, Hayes 1969), then at least one needs to
  - $\triangleright$  formally define the notion of a generated plan given a model of  ${\cal G}$  and
  - show that each generated plan is also a plan wrt the planning as deduction approach
- Is G minimal?
- What are logical consequences of G?
- Reasoning is often easier in predicate logic
  - Reasoning with schemas as first-order formulas
  - But then we need to show that first-order satisfiability corresponds to propositional satisfiability





# **Solving Planning Problems**

- Let G be the specification of a planning problem
- G can be solved using the following steps
  - ▷ Write G in full
  - Transform G into CNF
  - Bijectively replace ground atoms by propositional variables
  - > Transform formulas into syntatic form required by a solver
  - Apply the solver
  - Read out the plan
- This will be demonstrated by means of our running example

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# Writing Specifications in Full

> A block except the table cannot be clear and support a block at the same time

```
(\forall X, Y, T') (Y \neq \text{table} \rightarrow \neg(\text{clear}(Y, T') \land \text{on}(X, Y, T')))
```

▶ is written in full as:

$$\{ \begin{array}{ll} (a \neq table \rightarrow \neg(clear(a, 1) \land on(a, a, 1))), \\ (a \neq table \rightarrow \neg(clear(a, 2) \land on(a, a, 2))), \\ (a \neq table \rightarrow \neg(clear(a, 3) \land on(a, a, 3))), \\ (a \neq table \rightarrow \neg(clear(a, 1) \land on(b, a, 1))), \\ (a \neq table \rightarrow \neg(clear(a, 2) \land on(b, a, 2))), \\ (a \neq table \rightarrow \neg(clear(a, 3) \land on(b, a, 3))), \\ (a \neq table \rightarrow \neg(clear(a, 1) \land on(table, a, 1))), \\ (a \neq table \rightarrow \neg(clear(a, 2) \land on(table, a, 2))), \\ (a \neq table \rightarrow \neg(clear(a, 3) \land on(table, a, 2))), \\ (a \neq table \rightarrow \neg(clear(a, 3) \land on(table, a, 3))), \\ (b \neq table \rightarrow \ldots) \\ \vdots \end{array}$$

}





# **Transformation in Conjunctive Normal Form**

A block except the table cannot be clear and support a block at the same time

```
(\forall X, Y, T') (Y \neq \text{table} \rightarrow \neg(\text{clear}(Y, T') \land \text{on}(X, Y, T')))
```

#### As CNF we obtain

$$\begin{array}{l} ( & [a = table, \neg clear(a, 1), \neg on(a, a, 1)], \\ [a = table, \neg clear(a, 2), \neg on(a, a, 2)], \\ [a = table, \neg clear(a, 3), \neg on(a, a, 3)], \\ [a = table, \neg clear(a, 1), \neg on(b, a, 1)], \\ [a = table, \neg clear(a, 2), \neg on(b, a, 2)], \\ [a = table, \neg clear(a, 3), \neg on(b, a, 3)], \\ [a = table, \neg clear(a, 3), \neg on(table, a, 1)], \\ [a = table, \neg clear(a, 2), \neg on(table, a, 2)], \\ [a = table, \neg clear(a, 3), \neg on(table, a, 2)], \\ [a = table, \neg clear(a, 3), \neg on(table, a, 3)], \\ \end{array}$$

>



## **Introduction of Propositional Variables**

A block except the table cannot be clear and support a block at the same time

 $(\forall X, Y, T') (Y \neq table \rightarrow \neg(clear(Y, T') \land on(X, Y, T')))$ 

Replacing ground atoms by natural numbers we obtain

$$\begin{matrix} [3, \neg 10, \neg 19], \\ [3, \neg 13, \neg 28], \\ [3, \neg 16, \neg 37], \\ [3, \neg 10, \neg 22], \\ [3, \neg 13, \neg 31], \\ [3, \neg 16, \neg 40], \\ [3, \neg 10, \neg 25], \\ [3, \neg 13, \neg 34], \\ [3, \neg 16, \neg 43], \\ \end{matrix}$$



### **CNF-Form Required by the Solver**

A block except the table cannot be clear and support a block at the same time

 $(\forall X, Y, T') (Y \neq table \rightarrow \neg(clear(Y, T') \land on(X, Y, T')))$ 

The solver requires formulas to be in so-called .cnf-form

```
p cnf nv nc

3 -10 -19 0

3 -13 -28 0

3 -16 -37 0

3 -10 -22 0

3 -13 -31 0

3 -16 -40 0

3 -10 -25 0

3 -13 -34 0

3 -16 -43 0

.
```

where nv and nc are the number of variables and clauses, respectively





# **Application of a Solver**

- Here we are applying the solver sat4j
  - Check out the internet for sat4j
  - In our example, nv = 99 and nc = 4299
  - It uses a different mapping from ground atoms to natural numbers
  - It uses a different representation of interpretations atoms are listed iff they are mapped to ⊤
  - It yields

(1, 5, 9, 10, 11, 14, 15, 16, 17, 18, 22, 26, 27, 30, 34, 35, 56, 77)

This translates into the model

```
( a = a, b = b, table = table,
clear(a, 1), clear(a, 2), clear(b, 2), clear(b, 3),
clear(table, 1), clear(table, 2), clear(table, 3),
on(a, b, 1), on(a, table, 2), on(a, table, 3),
on(b, a, 3), on(b, table, 1), on(b, table, 2),
move(a, b, table, 1), move(b, table, a, 2)
```





## **Reading out the Plan**

**State at** t = 2

 $(\operatorname{clear}(a, 2), \operatorname{clear}(b, 2), \operatorname{clear}(\operatorname{table}, 2), \operatorname{on}(a, \operatorname{table}, 2), \operatorname{on}(b, \operatorname{table}, 2))$ 

Action at t = 2

move(b, table, a, 2)

**>** State at t = 3

(clear(b, 3), clear(table, 3), on(a, table, 3), on(b, a, 3))





## Example: Periodic Event Scheduling Problems

- Periodic events occur in traffic control systems, train scheduling systems and many other applications
- The problem is to schedule periodic events with respect to some criteria
- The problem is  $\mathcal{NP}$ -complete
- Real world problems are often very large
  - Scheduling of trains in the railway network of Germany
  - Only subnetworks can be dealt with currently
- The previously best solvers were based on constraint programming techniques
- We looked into a SAT-based approach
  - Großmann, H., Manthey, Nachtigall, Opitz, Steinke: Solving Periodic Event Scheduling Problems with SAT. In: Advanced Research in Applied Artificial Intelligence, LNCS 7345, 166-175: 2012





### **Overview**

- Periodic Event Networks
- Periodic Event Scheduling Problems
- Direct Encoding
- Order Encoding
- Experimental Evaluation





### Intervals

- ▶ Let *I*, *u* ∈ ℤ
  - ▷  $[I, u] = \{x \in \mathbb{Z} \mid I \le x \le u\}$  is the interval from *I* to *u*

 $\triangleright$  *I* is called lower bound and *u* is called upper bound of the interval [*I*, *u*]

▶ Let 
$$[I, u]$$
 be an interval and  $t \in \mathbb{N}$ 

- ▷  $[I, u]_t = \bigcup_{x \in \mathbb{Z}} [I + x \cdot t, u + x \cdot t]$  is called interval from *I* to *u* modulo *t* ▷  $[I, u]_t \subset \mathbb{Z}$
- $\triangleright$  [2, 4]<sub>10</sub> = [2, 4]  $\cup$  [12, 14]  $\cup$  [-8, -6]  $\cup$  [22, 24]  $\cup$  [-18, -6]  $\cup$  ...
  - $\triangleright$   $[I, u]_0 = [I, u]$



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# **Periodic Event Networks and Schedules**

- Let (V, E) be a graph, t ∈ N, and a : E → 2<sup>2<sup>Z</sup></sup> a mapping which assigns to each edge a finite set of intervals modulo t
  - $\triangleright \mathcal{N} = (\mathcal{V}, \mathcal{E}, a, t)$  is called periodic event network (PEN)
  - ▷ t is called period
  - $\triangleright$  The elements of  ${\cal V}$  are called (periodic) events
  - ▷ a(e) is called set of constraints for the edge  $e \in \mathcal{E}$
- ▶ Let  $\mathcal{N} = (\mathcal{V}, \mathcal{E}, \mathbf{a}, t)$  be a PEN and  $\Pi : \mathcal{V} \to \mathbb{Z}$ 
  - $\triangleright \ \Pi \ \text{is called schedule for } \mathcal{N}$



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# Constraints

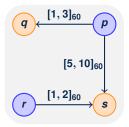
- In PENs two types of constraints are usually distinguished: time consuming constraints and symmetry constraints
- Here, only time consuming constraints are considered
- ▶ Let  $\mathcal{N} = (\mathcal{V}, \mathcal{E}, a, t)$  be a PEN,  $(i, j) \in \mathcal{E}$ ,  $[I, u]_t \in a(i, j)$ , and  $\Pi$  a schedule for  $\mathcal{N}$ 
  - ▷  $[I, u]_t$  holds for (i, j) under  $\Pi$  iff  $\Pi(j) \Pi(i) \in [I, u]_t$
- A schedule Π for a PEN N is said to be valid iff all constraints of N hold under Π

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# Example

 $\blacktriangleright$  Consider the following PEN  ${\cal N}$ 



 $\blacktriangleright$  Valid schedules for  ${\cal N}$  are

$$\begin{array}{rcl} \Pi_1 & = & \{p \mapsto 24, \ q \mapsto 27, \ r \mapsto 28, \ s \mapsto 30\} \\ \Pi_2 & = & \{p \mapsto 144, \ q \mapsto 147, \ r \mapsto 148, \ s \mapsto 150\} \end{array}$$

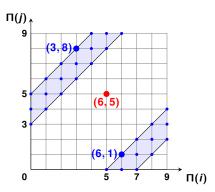


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## **Feasible Regions**

- ▶ Let  $\mathcal{N} = (\mathcal{V}, \mathcal{E}, a, t)$  be a PEN and  $(i, j) \in \mathcal{E}$ 
  - ▷ Each  $[I, u]_t \in a(i, j)$  constrains the possible values for *i* and *j* in a schedule
  - ▷ Suppose [3,5]<sub>10</sub> ∈ a(i, j), then the blue regions are feasible, whereas the other regions are infeasible wrt the constraint [3,5]<sub>10</sub>





# **Equivalent Schedules**

- ▶ Let Π<sub>1</sub> and Π<sub>2</sub> be schedules for the PEN  $\mathcal{N} = (\mathcal{V}, \mathcal{E}, a, t)$ 
  - ▷  $\Pi_1$  and  $\Pi_2$  are equivalent, in symbols  $\Pi_1 \equiv \Pi_2$ , iff for all  $i \in \mathcal{V}$  we find  $\Pi_1(i) \mod t = \Pi_2(i) \mod t$
  - $\triangleright$  **Proposition**  $\equiv$  is an equivalence relation
  - ▶ Proposition If  $\Pi_1 \equiv \Pi_2$  and  $\Pi_1$  is valid, then  $\Pi_2$  is also valid
  - ▷ Corollary If there exists a valid schedule  $\Pi_1$  for  $\mathcal{N}$ , then there exists a valid schedule  $\Pi_2 \equiv \Pi_1$ such that for all  $i \in \mathcal{V}$  we find  $\Pi_2(i) \in [0, t - 1]$
  - ▷ It suffices to search for schedules  $\Pi$  with  $\Pi(i) \in [0, t 1]$  for all  $i \in \mathcal{V}$



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# **Periodic Event Scheduling Problems**

- ► A periodic event scheduling problem (PESP) consists of a PEN *N* and is the question whether there exists a valid schedule for *N* 
  - PESP is decidable
  - PESP is NP-complete
  - > If there exists a valid schedule, then the schedule shall be computed
  - Until 2011 the best PESP-solvers were based on constraint propagation techniques (Opitz: Automatische Erzeugung und Optimierung von Taktfahrplänen in Schienenverkehrsnetzen. PhD thesis, TU Dresden: 2009)





# **Direct Encoding of Variables with Finite Domain**

- Let x be a variable with finite domain D
  - ▶ Variables are encoded with the help of propositional variables  $p_{x,k}$  such that  $p_{x,k}$  is mapped to  $\top$  iff the value of x is k
  - ▶ The direct encoding of *x* is

$$(\bigvee_{k\in D} p_{x,k}) \land (\bigwedge_{k\in D} \bigwedge_{l\in D\setminus\{k\}} \neg (p_{x,k} \land p_{x,l}))$$

▷ The direct encoding of  $x \in [2, 3]$  is

$$\begin{array}{l} (p_{x,2} \lor p_{x,3}) \land \neg (p_{x,2} \land p_{x,3}) \land \neg (p_{x,3} \land p_{x,2}) \\ \equiv (p_{x,2} \lor p_{x,3}) \land (\neg p_{x,2} \lor \neg p_{x,3}) \end{array}$$



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## **Direct Encoding of Values for Events**

- ▶ Let *N* = (*V*, *E*, *a*, *t*) be a PEN
  - ▷ Each schedule  $\Pi$  will assign a value from [0, t 1] to each  $i \in V$
  - $\triangleright$  Hence, we obtain the following direct encoding for  $\Pi(i)$

$$F_{i} = (\bigvee_{k \in [0,t-1]} p_{\Pi(i),k}) \land (\bigwedge_{k \in [0,t-1]} \bigwedge_{l \in [0,t-1] \setminus \{k\}} \neg (p_{\Pi(i),k} \land p_{\Pi(i),l}))$$

Let

$$\mathcal{F}_{\boldsymbol{E}} = \bigwedge_{i \in \mathcal{V}} F_i$$

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# **Direct Encoding of Time Consuming Constraints**

- Let  $\mathcal{N} = (\mathcal{V}, \mathcal{E}, a, t)$  be a PEN
  - $\triangleright\,$  Each constraint of  ${\cal N}$  defines an infeasible region
  - Each infeasible region can be encoded as the negation of the disjunction of all points in the region
  - $\triangleright$  Let  $\mathcal{F}_{T}$  be the conjunction of these encodings for all constraints in  $\mathcal{N}$
- ▶ The direct encoding of a PEN N is

$$\mathcal{F}_{\mathcal{N}} = \mathcal{F}_{\mathcal{E}} \wedge \mathcal{F}_{\mathcal{T}}$$

 $\triangleright \ \mathcal{F}_{\mathcal{N}}$  will be simplified and normalized before being submitted to a SAT-solver



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## **Encoding Variables with Finite Ordered Domain**

- We consider variables, whose domain is finite and ordered
  - ▷ Here, we consider as domain intervals (modulo some  $t \in \mathbb{N}$ )
  - ▶ x with domain [1,3]
- Variables are encoded with the help of propositional variables q<sub>x,j</sub> such that q<sub>x,j</sub> is mapped to ⊤ iff x ≤ j
- Let x be a variable with domain [I, u]
  - ▶ The order encoding of *x* is

$$\neg q_{x,l-1} \land q_{x,u} \land \bigwedge_{j \in [l,u]} (\neg q_{x,j-1} \lor q_{x,j})$$

▶ The order encoding of x with domain [1, 3] is

 $\langle [\neg q_{x,0}], [q_{x,3}], [\neg q_{x,0}, q_{x,1}], [\neg q_{x,1}, q_{x,2}], [\neg q_{x,2}, q_{x,3}] \rangle$ 





# Simplifying the Order Encoding

Recall

$$\langle [\neg q_{x,0}], [q_{x,3}], [\neg q_{x,0}, q_{x,1}], [\neg q_{x,1}, q_{x,2}], [\neg q_{x,2}, q_{x,3}] \rangle = F$$

and observe that  $[\neg q_{x,0}]$  and  $[q_{x,3}]$  are unit clauses

▶ Hence, any model for *F* must contain  $\neg q_{x,0}$  and  $q_{x,3}$ , and

$$\boldsymbol{F}|_{(\boldsymbol{q}_{x,3},\neg \boldsymbol{q}_{x,0})} = \langle [\neg \boldsymbol{q}_{x,1}, \boldsymbol{q}_{x,2}] \rangle.$$

Let x be a variable with domain [I, u] and  $F_x$  its order encoding, then

$$F_{\mathbf{x}}|_{(q_u,\neg q_{\mathbf{x},l-1})} = \bigwedge_{j\in [l+1,u-1]} (\neg q_{\mathbf{x},j-1} \lor q_{\mathbf{x},j}).$$

The latter is called simplified order encoding of x

▶ The simplified order encoding of *x* with domain [2, 3] or [5, 5] is ⟨⟩





## **Order Encoding of Values for Events**

• Let  $\mathcal{N} = (\mathcal{V}, \mathcal{E}, a, t)$  be a PEN

▷ Each schedule  $\Pi$  will assign a value from [0, t - 1] to each  $i \in V$ 

 $\triangleright$  Hence, we obtain the following order encoding for  $\Pi(i)$ 

$$G_{i} = \neg q_{\Pi(i),-1} \land q_{\Pi(i),t-1} \land \bigwedge_{j \in [1,t-1]} (\neg q_{\Pi(i),j-1} \lor q_{\Pi(i),j}).$$

Let

$$\mathcal{G}_{\boldsymbol{E}} = \bigwedge_{i \in \mathcal{V}} \boldsymbol{G}_i$$



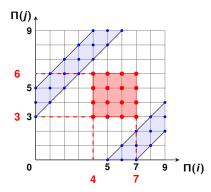
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# Order Encoding of Time Consuming Constraints – Idea

- ▶ Let  $\mathcal{N} = (\mathcal{V}, \mathcal{E}, a, t)$  be a PEN,  $(i, j) \in \mathcal{E}$ , and  $[3, 5]_{10} \in a(i, j)$ 
  - > In the following figure, the red square is infeasible, i.e.,

 $\{(\Pi(i),\Pi(j)) \mid \Pi(i) \in [4,7], \Pi(j) \in [3,6]\}$ 



Idea Encode sufficiently many squares to cover the infeasible regions





### **Order Encoding an Infeasible Square**

- ▶ Reconsider {( $\Pi(i), \Pi(j)$ ) |  $\Pi(i) \in [4, 7], \Pi(j) \in [3, 6]$ }
  - We obtain

$$\begin{array}{l} \neg(\Pi(i) \geq 4 \land \Pi(i) \leq 7 \land \Pi(j) \geq 3 \land \Pi(j) \leq 6) \\ \equiv & \neg(\neg\Pi(i) < 4 \land \Pi(i) \leq 7 \land \neg\Pi(j) < 3 \land \Pi(j) \leq 6) \\ \equiv & \neg(\neg\Pi(i) \leq 3 \land \Pi(i) \leq 7 \land \neg\Pi(j) \leq 2 \land \Pi(j) \leq 6) \\ \equiv & (\Pi(i) \leq 3 \lor \neg\Pi(i) \leq 7 \lor \Pi(j) \leq 2 \lor \neg\Pi(j) \leq 6) \\ = & [q_{\Pi(i),3}, \neg q_{\Pi(i),7}, q_{\Pi(j),2}, \neg q_{\Pi(j),6}] \end{array}$$

The final formula is the encoding of the given infeasible square

- Suppose [i, j]<sub>t</sub> was the kth constraint of a(i, j) wrt some PEN N (assuming some ordering)
  - Let G<sub>ijk</sub> denote the conjunction of encodings of infeasible squares necessary to cover the infeasible regions wrt [i, j]<sub>t</sub>





# **Order Encoding of Time Consuming Constraints**

▶ Let *N* = (*V*, *E*, *a*, *t*) be a PEN

$$\mathcal{G}_{\mathcal{T}} = \bigwedge_{i \in \mathcal{V}} \bigwedge_{j \in \mathcal{V}} \bigwedge_{k \in a(i,j)} \mathcal{G}_{ijk}$$

is the encoding of the time consuming constaints of  $\boldsymbol{\mathcal{N}}$ 

 $\blacktriangleright$  The order encoding of a PEN  ${\cal N}$  is

$$\mathcal{G}_{\mathcal{N}} = \mathcal{G}_{\mathcal{E}} \wedge \mathcal{G}_{\mathcal{T}}$$

 $\triangleright~\mathcal{G}_\mathcal{N}$  will be simplified and normalized before being submitted to a SAT-solver

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# **Experimental Evaluation**

- Cooperation with the Traffic Flow Science Group at the Faculty of Transportation and Traffic Science of TU Dresden
- Based on data from the Deutsche Bahn AG
- We compared
  - > PESPSOLVE, a state-of-the-art constaint-based PESP-solver
  - DIRECT+RISS, the state-of-the-art SAT-solver RISS using direct encoding
  - ORDERED+RISS, RISS using ordered encoding
- All solvers were given a timeout of 24h = 86400s
- The experiments were run on a Intel Core i7 with 8 GB RAM





## **Number of Variables and Clauses**

	$\mathcal{N} = (\mathcal{V}, \mathcal{E}, \mathbf{a}, \mathbf{t})$		direct encoding $\mathcal{F}_{\mathcal{N}}$		order encoding $\mathcal{G}_{\mathcal{N}}$	
instance	$ \mathcal{V} $	#a	$ var(\mathcal{F}_\mathcal{N}) $	$ \mathcal{F}_{\mathcal{N}} $	$ var(\mathcal{G}_{\mathcal{N}}) $	$ \mathcal{G}_{\mathcal{N}} $
swg <sub>2</sub>	60	1,145	7,200	2,037,732	7,140	83,740
fernsym	128	3,117	15,360	6,657,955	15,232	353,276
swg <sub>4</sub>	170	7,107	20,400	6,193,570	20,230	399,191
swg <sub>3</sub>	180	2,998	21,600	4,874,144	21,420	214,011
swg <sub>1</sub>	221	7,443	26,520	7,601,906	26,299	462,217
seg <sub>2</sub>	611	9,863	73,320	25,101,341	72,709	1,115,210
seg <sub>1</sub>	1,483	10,351	177,960	34,323,942	176,477	1,348,045

#### Notation

- ▶ #a denotes the number of constraints given by a
- $\triangleright$  var(X) denotes the number of variables occurring in X
- $\triangleright$  |X| denotes the cardinality of the set X





### **Results**

instance	PESPSOLVE/S	DIRECT+RISS/S	ORDERED+RISS/S	speedup
swg <sub>3</sub>	66	50	2	33
swg <sub>2</sub>	512	37	2	256
swg <sub>4</sub>	912	752	8	114
fernsym	2,035	294	7	290
swg <sub>1</sub>	TIMEOUT	18	7	>12,342
seg <sub>1</sub>	TIMEOUT	16	10	>8,640
seg <sub>2</sub>	TIMEOUT	TIMEOUT	11	>7,854

#### ► Conclusion The best PESP-solver is now SAT-based

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# **Further Examples**

#### Program Termination

Fuhs, Giesl, Middeldorp, Schneider-Kamp, Thiemann, Zankl 2007: SAT Solving for Termination Analysis with Polynomial Interpretations. In: *Proceedings SAT Conference*, LNCS 4501

#### Bioinformatics

Lynce, Marques-Silva 2008: Haplotype Inference with Boolean Satisfiability. In: International Journal on Artificial Intelligence Tools 17, 355-387

#### Bounded Model Checking

Clarke, Biere, Raimi, Zhu 2001: Bounded Model Checking using Satisfiability Solving. In: *Formal Methods in System Design* 19

